National Science Foundation
Geosciences Directorate
Division of Ocean Sciences
Arlington, Virginia

DRAFT ENVIRONMENTAL ASSESSMENT (DEA) PURSUANT TO THE NATIONAL ENVIRONMENTAL POLICY ACT, 42 U.S.C. 4321, *et seq.*

Marine Seismic Survey on the Shatsky Rise in the Northwest Pacific Ocean June-July 2010

OCE# 0927001; OCE# 0926945; OCE# 0926611
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Project Title: Geophysical constraints on Mechanisms of Ocean Plateau Formation from Shatsky Rise, Northwest Pacific

This constitutes a draft environmental assessment (DEA) by the National Science Foundation (NSF) for a marine seismic survey proposed to be conducted in June-July 2010 on board the research vessel (R/V) *Marcus G. Langseth* in the Northwest Pacific Ocean on the Shatsky Rise. This DEA is based, in part, on an Environmental Assessment report prepared by LGL Limited environmental research associates (LGL) on behalf of NSF, entitled, "Environmental Assessment of a Marine Geophysical Survey by the R/V *Marcus G. Langseth* on the Shatsky Rise in the Northwest Pacific Ocean, June-July 2010" (Report #TA4873-1) (Attachment 1). The conclusions from the LGL report were used to inform the Division of Ocean Sciences (OCE) management of potential environmental impacts of the cruise. OCE has reviewed and concurs with the report's findings. Accordingly, the LGL report is incorporated into this DEA by reference as if fully set forth herein.

Project Objectives and Context

By deciphering the crustal structure of Shatsky Rise, a large igneous province (LIP), through a combined ocean bottom seismometers (OBS) and multichannel seismic (MCS) survey, this project would address major questions of Earth history, geodynamics, and tectonics and have a profound impact on our understanding of terrestrial magmatism and mantle convection. The sheer scale of plateau formation implies a potential role in environmental crises such as oceanic anoxia and mass extinctions, and oceanic plateaus may also be important for the growth of continental crust. The question of how plateaus are built is one with important ramifications for mantle dynamics because it bears on the state and depth of mantle convection as well as the issue of how oceanic LIPs form and their relationship to plate tectonics. This study would investigate both the origin of the plateau and the structure of it. The rise structure appears to be a huge volcano that formed at a triple junction and then was split apart by seafloor spreading. The field experiment has two foci: (1) constrain the whole crustal structure by an OBS reflection and

refraction experiment; and (2) delineate the tectonic history by extensive MCS profiling and reanalysis of bathymetry and magnetic data.

One of approximately twelve, the Shatsky Rise is a unique example of a LIP. It is the only LIP formed at a time of frequent magnetic reversal anomalies that show its relationship to coeval spreading ridges. Having formed at a ridge-ridge-ridge triple junction and intimately linked with large-scale plate boundary reorganization, the plateau offers an opportunity to evaluate competing theories of origin. The triple junction setting also provides the optimal tectonic window: minimal lithospheric contamination makes this the easiest place to probe the dynamics of mantle melting imprinted in the crustal section.

Deciphering the origins of the LIP is a critical element for understanding mantle dynamics and its relation to terrestrial magmatism. The sysnthesis of the geophysical data gathered through this project would encourage further discussions on the origins of oceanic plateaus and LIPs, stimulating further research on mantle dynamics and crustal genesis.

The project will be a collaborative effort, with scientists from multiple universities and supports graduate students.

Summary of Proposed Action and Alternatives

The procedures to be used for the survey would be similar to those used during previous seismic surveys by L-DEO and will use conventional seismic methodology. The proposed survey would take place from approximately June 17 through July 31, 2010 in the Pacific Ocean, at least 1200 km offshore from Japan, in international waters deeper than 1000 m (See Attachment 1, Figure 1). Some minor deviation from these dates may be required, depending on logistics and weather.

The seismic survey would consist of ~3160km of transect lines (including turns). The survey would involve the R/V *Marcus G. Langseth* as the source vessel which would deploy an array of 36 airguns with a total discharge volume of ~6600 in^3. The receiving system would consist of a 6 km hydrophone streamer and ~28 ocean bottom seismometers (OBSs). As the airgun array is towed along the survey lines, the hydrophone streamer would receive the returning acoustic signals and transfer the data to the on-board processing system. The shot interval will be relatively short (20 seconds) for MCS surveying with the hydrophone streamer, and relatively long (70 seconds) when recording data on the OBSs. The tow depth of the array will be 12 meters for the OBS lines and 9 meters for MCS lines. The OBSs record the returning acoustic signals internally for later analysis. The OBSs to be used would be deployed and retrieved during the cruise. In addition to the operations of the airgun array, a multibeam echosounder (MBES) and a subbottom profiler (SBP) would also be operated from the R/V *Langseth* continuously throughout the cruise. Seismic operations would be carried out for ~17 days, with the balance of the cruise occupied in transit and in deployment and retrieval of OBSs (~8 days).

One alternative to the proposed action would be to conduct the survey at an alternative time. Constraints for vessel operations and availability of equipment (including the vessel) and personnel would need to be considered for alternative cruise times. Limitations on scheduling the vessel include the additional research studies planned on the vessel for 2010 and beyond. Other research activities planned within the region also would need to be considered. Given the

fact that marine mammals and turtles are in the survey area throughout the year, altering the timing of the proposed project likely would result in few net benefits.

Another alternative to conducting the proposed activities would be the "No Action" alternative, i.e. do not issue an IHA and do not conduct the operations. If the planned research were not conducted, the "No Action" alternative would result in no disturbance to marine mammals attributable to the proposed activities, but geological data of considerable scientific value and relevance for increasing our understanding of plate tectonics, earthquake occurrence and distribution, and environmental events such as oceanic anoxia and mass extinctions would not be acquired and the project objectives as described above would not be met. The "No Action" alternative would result in a lost opportunity to obtain important scientific data and knowledge relevant to a number of research fields and to society in general. The collaboration, involving institutions, investigators, students, and technicians, would be lost along with the collection of new data, interpretation these data, and introduction of new results into the greater scientific community and applicability of this data to other similar settings. Loss of NSF support often represents a significant negative impact to the academic community.

Summary of environmental consequences

The potential effects of sounds from airguns on marine species, mammals and turtles of particular concern, are described in detail in Attachment 1 (pages 41-71 and Appendices B-E) and might include one or more of the following: tolerance, masking of natural sounds, behavioral disturbance, and at least in theory, temporary or permanent hearing impairment, or non-auditory physical or physiological effects. It is unlikely that the project would result in any cases of temporary or especially permanent hearing impairment, or any significant nonauditory physical or physiological effects. Some behavioral disturbance is expected, if animals are in the general area during seismic operations, but this would be localized, short-term, and involve limited numbers of animals.

The proposed activity would include a mitigation program to further minimize potential impacts on marine mammals that may be present during the conduct of the research to a level of insignificance. As detailed in Attachment 1 (pages 6-13; and 54) monitoring and mitigation measures would include: ramp ups, minimum of one dedicated observer maintaining a visual watch during all daytime airgun operations, two observers 30 min before and during ramp ups during the day and at night (and when possible at other times), no start ups during poor visibility or at night unless at least one airgun has been operating, passive acoustic monitoring (PAM) via towed hydro-phones during both day and night to complement visual monitoring (when practicable), and power downs (or if necessary shut downs) when marine mammals or sea turtles are detected in or about to enter designated exclusion zones. Also, a special mitigation measure of immediate shutdown would be in place in the unlikely event that North Pacific right whales were observed at any distance from the Langseth (Attachment 1, page 12). The fact that the 36-airgun array, as a result of its design, directs the majority of the energy downward, and less energy laterally, would also be an inherent mitigation measure, as is the relatively wide spacing of the airgun shots.

With the planned monitoring and mitigation measures, unavoidable impacts to each species of marine mammal and turtle that could be encountered would be expected to be limited to short-

term, localized changes in behavior and distribution near the seismic vessel. At most, effects on marine mammals may be interpreted as falling within the U.S. Marine Mammal Protection Act (MMPA) definition of "Level B Harassment" for those species managed by the National Marine Fisheries Service. No long-term or significant effects would be expected on individual marine mammals, sea turtles, seabirds, or the populations to which they belong or on their habitats.

A survey at an alternative time would result in few net benefits. Marine mammals and sea turtles are expected to be found throughout the proposed study area. Many cetaceans occur in the survey area throughout the year, but others (some baleen whales) may only migrate though the area during spring and fall; thus, altering the timing of the proposed project likely would result in few net benefits. Loggerhead, leatherback, and green turtles nest on the Ryukyu Islands, Japan, at the time of the survey, so nesting females would be nearshore or on land far from the survey area. However, migrating or foraging loggerhead, leatherback, or green turtles could be encountered in the deep waters of the survey area at any time of year.

The "no action" alternative would remove the potential of the limited direct environmental consequences as described. However, it would preclude important scientific research from going forward that has distinct potential to elucidate geological processes/concerns.

Conclusions

NSF has reviewed and concurs with the conclusions of the LGL Environmental Assessment (Attachment 1) that implementation of the proposed activity will not have a significant impact on the environment.

Environmental Assessment of a Marine Geophysical Survey by the R/V *Marcus G. Langseth* on the Shatsky Rise in the Northwest Pacific Ocean, July–September 2010

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8 February 2010

LGL Report TA4873-1

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ABSTRACT

Lamont-Doherty Earth Observatory (L-DEO), with research funding from the U.S. National Science Foundation (NSF), plans to conduct a marine seismic survey on the Shatsky Rise in the Northwest Pacific Ocean, during July–September 2010. The survey will take place in international waters in water depths >1000 m. The seismic study will use a towed array of 36 airguns with a total discharge volume of ~6600 in^3.

NSF, as the funding and action agency, has a mission to "promote the progress of science; to advance the national health, prosperity, and welfare; to secure the national defense…". The proposed seismic survey is part of a research proposal recommended for funding by an expert review panel. It will provide data necessary to decipher the crustal structure of the Shatsky Rise. The survey may also obtain information that will improve estimates of regional earthquake occurrence and distribution.

L-DEO is requesting an Incidental Harassment Authorization (IHA) from the U.S. National Marine Fisheries Service (NMFS) to authorize the incidental, i.e., not intentional, harassment of small numbers of marine mammals should this occur during the seismic survey. The information in this Environmental Assessment (EA) supports the IHA application process, provides information on marine species that are not addressed by the IHA application, and addresses the requirements of Executive Order 12114, "Environmental Effects Abroad of Major Federal Actions". Alternatives addressed in this EA consist of a corresponding program at a different time, along with issuance of an associated IHA; and the no action alternative, with no IHA and no seismic survey.

Numerous species of marine mammals inhabit the Northwest Pacific Ocean. Several of these species are listed as ***endangered*** under the U.S. Endangered Species Act (ESA), including the Western North Pacific gray, North Pacific right, sperm, humpback, sei, fin, and blue whales. The Western North Pacific gray whale is listed as ***critically endangered*** by the International Union for Conservation of Nature and Natural Resources (IUCN) 2009 Red List of Threatened species, but is unlikely to occur in the offshore study area as it prefers coastal waters. With the exception of humpback and sperm whales, the other ESA-listed whale species are also considered ***endangered*** by the IUCN (2009). Northern fur seals may also be present, and are listed as ***vulnerable*** under the ESA and by the IUCN. Other ESA-listed species that could occur in the study area include the ***endangered*** hawksbill and leatherback turtles, the ***threatened*** green, loggerhead, and olive ridley turtles, and the ***endangered*** short-tailed albatross.

Potential impacts of the seismic survey on the environment would be primarily a result of the operation of the airgun array. A multibeam echosounder and a sub-bottom profiler will also be operated. Impacts would be associated with increased underwater noise, which may result in avoidance behavior by marine mammals, sea turtles, and fish, and other forms of disturbance. An integral part of the planned survey is a monitoring and mitigation program designed to minimize impacts of the proposed activities on marine animals present during the proposed research, and to document as much as possible the nature and extent of any effects. Injurious impacts to marine mammals and sea turtles have not been proven to occur near airgun arrays, and also are not likely to be caused by the other types of sound sources to be used. However, given the high levels of sound emitted by a large array of airguns, a precautionary approach is warranted. The planned monitoring and mitigation measures would reduce the possibility of injurious effects.

Protection measures designed to mitigate the potential environmental impacts to marine mammals and turtles will include the following: ramp ups, minimum of one dedicated observer maintaining a visual watch during all daytime airgun operations, two observers 30 min before and during ramp ups

during the day and at night (and when possible at other times), no start ups during poor visibility or at night unless at least one airgun has been operating, passive acoustic monitoring (PAM) via towed hydrophones during both day and night to complement visual monitoring (when practicable), and power downs (or if necessary shut downs) when marine mammals or sea turtles are detected in or about to enter designated exclusion zones. L-DEO and its contractors are committed to apply these measures in order to minimize effects on marine mammals and sea turtles and other environmental impacts. The relatively wide shot spacing, in time and space, to be used during some of the survey, is an inherent mitigation measure relative to more typical seismic surveys with closer shotpoints.

With the planned monitoring and mitigation measures, unavoidable impacts to each species of marine mammal and turtle that could be encountered are expected to be limited to short-term, localized changes in behavior and distribution near the seismic vessel. At most, effects on marine mammals may be interpreted as falling within the U.S. Marine Mammal Protection Act (MMPA) definition of "Level B Harassment" for those species managed by NMFS. No long-term or significant effects are expected on individual marine mammals, sea turtles, seabirds, the populations to which they belong, or their habitats.

LIST OF ACRONYMS

~	approximately
CITES	Convention on International Trade in Endangered Species
CPA	Closest Point of Approach
CPUE	Catch per Unit Effort
CV	Coefficient of Variation
DoN	U.S. Department of the Navy
EA	Environmental Assessment
EEZ	Exclusive Economic Zone
ESA	(U.S.) Endangered Species Act
ETP	Eastern Tropical Pacific
ft	feet
$gCm^{-2}d^{-1}$	grams of Carbon per meter squared per day
GIS	Geographic Information System
GT	Gross Tonnes
h	hour
hp	horsepower
ICR	Japan Institute of Cetacean Research
IHA	Incidental Harassment Authorization (under U.S. MMPA)
in	inch
IUCN	International Union for the Conservation of Nature
IWC	International Whaling Commission
kHz	kilohertz
kt	knot
L-DEO	Lamont-Doherty Earth Observatory of Columbia University
Langseth	R/V *Marcus G. Langseth*
LME	Large Marine Ecosystem
m	meter
MBES	Multibeam echosounder
MCS	Multichannel seismic
mi	mile
min	minute
MMO	Marine Mammal Observer
MMPA	(U.S.) Marine Mammal Protection Act
ms	millisecond
n.mi.	nautical mile
n.d.	no date
NEPA	(U.S.) National Environmental Policy Act
NMFS	(U.S.) National Marine Fisheries Service
NOAA	(U.S.) National Oceanic and Atmospheric Administration
NRC	(U.S.) National Research Council
NSF	(U.S.) National Science Foundation
NVD	Night Vision Device
OBS	Ocean Bottom Seismometer
PAM	Passive Acoustic Monitoring
pk	peak
PL	Propagation Loss
psi	pounds per square inch
PTS	Permanent Threshold Shift
RL	Received Level

R/V	Research Vessel
rms	root-mean-square
rpm	rotations per minute
s	second
SBP	Sub-Bottom Profiler
SEL	Sound Exposure Level (a measure of acoustic energy)
SL	Source Level
SPL	sound pressure level
SWFSC	Southwest Fisheries Science Center
SOSUS	Sound Surveillance System
t	tonnes
TTS	Temporary Threshold Shift
UNEP	United Nations Environment Program
U.S.	United States of America
USFWS	U.S. Fish and Wildlife Service
USN	U.S. Navy
vs.	versus
WHOI	Woods Hole Oceanographic Institution

I. PURPOSE AND NEED

Lamont-Doherty Earth Observatory (L-DEO), a part of Columbia University, operates the oceanographic research vessel *Marcus G. Langseth* under a cooperative agreement with the U.S. National Science Foundation (NSF). L-DEO plans to conduct a seismic survey in international waters over the Shatsky Rise in the Northwest Pacific Ocean, from ~23 July to 6 September 2010.

NSF, as the funding and action agency, has a mission to "promote the progress of science; to advance the national health, prosperity, and welfare; to secure the national defense…". The proposed seismic survey is part of a research proposal recommended for funding by an expert review panel. It will provide data necessary to decipher the crustal structure of the Shatsky Rise. The survey may also obtain data that can be used to improve estimates of regional earthquake occurrence and distribution.

The purpose of this Environmental Assessment (EA) is to provide the information needed to assess the potential environmental impacts associated with the use of a 36-airgun array during the proposed study. The EA was prepared under the U.S. National Environmental Policy Act (NEPA) and Executive Order 12114, "Environmental Effects Abroad of Major Federal Actions". The EA addresses potential impacts of the proposed seismic survey on marine mammals, as well as other species of concern in and near the study area, including sea turtles, fish, and invertebrates. The EA will also provide useful information in support of the application for an Incidental Harassment Authorization (IHA) from the National Marine Fisheries Service (NMFS). The requested IHA would, if issued, allow the non-intentional "take by harassment" of small numbers of marine mammals during the proposed seismic survey by L-DEO during July–September 2010.

To be eligible for an IHA under the U.S. Marine Mammal Protection Act (MMPA), the proposed "taking" (with mitigation measures in place) must not cause serious physical injury or death of marine mammals, must have negligible impacts on the species and stocks, must "take" no more than small numbers of those species or stocks, and must not have an unmitigable adverse impact on the availability of the species or stocks for legitimate subsistence uses.

Numerous species of marine mammals inhabit the Northwest Pacific Ocean. Several of these species are listed as ***endangered*** under the U.S. Endangered Species Act (ESA), including the Western North Pacific gray, North Pacific right, sperm, humpback, sei, fin, and blue whales. The Western North Pacific gray whale is listed as ***critically endangered*** by the International Union for Conservation of Nature and Natural Resources (IUCN) 2009 Red List of Threatened species, but is unlikely to occur in the offshore study area as it prefers coastal waters. With the exception of humpback and sperm whales, the other ESA-listed whale species are also considered ***endangered*** by the IUCN (2009). Northern fur seals may also be present, and are listed as ***vulnerable*** under the ESA and by the IUCN. Other ESA-listed species that could occur in the study area include the ***endangered*** hawksbill and leatherback turtles, the ***threatened*** green, loggerhead, and olive ridley turtles, and the ***endangered*** short-tailed albatross.

Protection measures designed to mitigate the potential environmental impacts are also described in this EA as an integral part of the planned activities. With these mitigation measures in place, any impacts on marine mammals and sea turtles are expected to be limited to short-term, localized changes in behavior of small numbers of animals. No long-term or significant effects are expected on individual mammals, turtles, seabirds, or populations. The proposed project would also have little impact on fish resources, and the only effect on fish habitat would be short-term disturbance that could lead to temporary relocation of pelagic fish species or their food. Impacts of seismic sounds on some pelagic seabirds are possible, although none are expected to be significant to individual birds or their populations.

II. ALTERNATIVES INCLUDING PROPOSED ACTION

Three alternatives are evaluated: (1) the proposed seismic survey and issuance of an associated IHA, (2) a corresponding seismic survey at an alternative time, along with issuance of an associated IHA, and (3) no action alternative.

Proposed Action

The project objectives and context, activities, and mitigation measures for L-DEO's planned seismic survey are described in the following subsections.

(1) Project Objectives and Context

L-DEO plans to conduct the seismic survey over the Shatsky Rise, which is a large igneous plateau in the Northwest Pacific Ocean. The proposed survey will provide data necessary to decipher the crustal structure of the Shatsky Rise. The sheer scale of plateau formation implies a potential role in environmental crises such as oceanic anoxia and mass extinctions. Likewise, oceanic plateaus may be important for the growth of continental crust. Hence, the information provided by this survey will address major questions of Earth history, geodynamics, and tectonics, and could have a profound impact on our understanding of terrestrial magmatism and mantle convection. The survey may also obtain data that could be used to improve estimates of regional earthquake occurrence and distribution.

(2) Proposed Activities

(a) Location of the Activities

The survey will occur at 30–37°N, 154–161°E in the Shatsky Rise area, at least 1200 km offshore from Japan (Fig. 1). The seismic survey will take place in international waters deeper than 1000 m.

(b) Description of the Activities

The procedures to be used for the survey will be similar to those used during previous seismic surveys by L-DEO and will use conventional seismic methodology. The survey will involve one source vessel, the R/V *Marcus G. Langseth*. The *Langseth* will deploy an array of 36 airguns as an energy source. The receiving system will consist of a 6-km long hydrophone streamer and/or ~28 ocean bottom seismometers (OBSs). As the airgun array is towed along the survey lines, the hydrophone streamer will receive the returning acoustic signals and transfer the data to the on-board processing system. The OBSs record the returning acoustic signals internally for later analysis.

The planned seismic survey will consist of ~3160 km of transect lines (including turns) in the Shatsky Rise survey area (Fig. 1). Lines A-B and C-D are for a reflection/refraction survey with OBSs, and they will be shot twice with different shot intervals — 20 s and 70 s (Fig. 1). A multichannel seismic (MCS) survey will follow, starting at end point 1 and ending at 13 (Fig. 1).

In addition to the operations of the airgun array, a multibeam echosounder (MBES) and a sub-bottom profiler (SBP) will also be operated from the *Langseth* continuously throughout the cruise. All planned geophysical data acquisition activities will be conducted by L-DEO with on-board assistance by the scientists who have proposed the study. The Principal Investigators are Drs. Jun Korenaga (Yale University, New Haven, CT), William Sager (Texas A&M University, College Station, TX), and John Diebold (L-DEO, Palisades, NY). The vessel will be self-contained, and the crew will live aboard the vessel for the entire cruise.

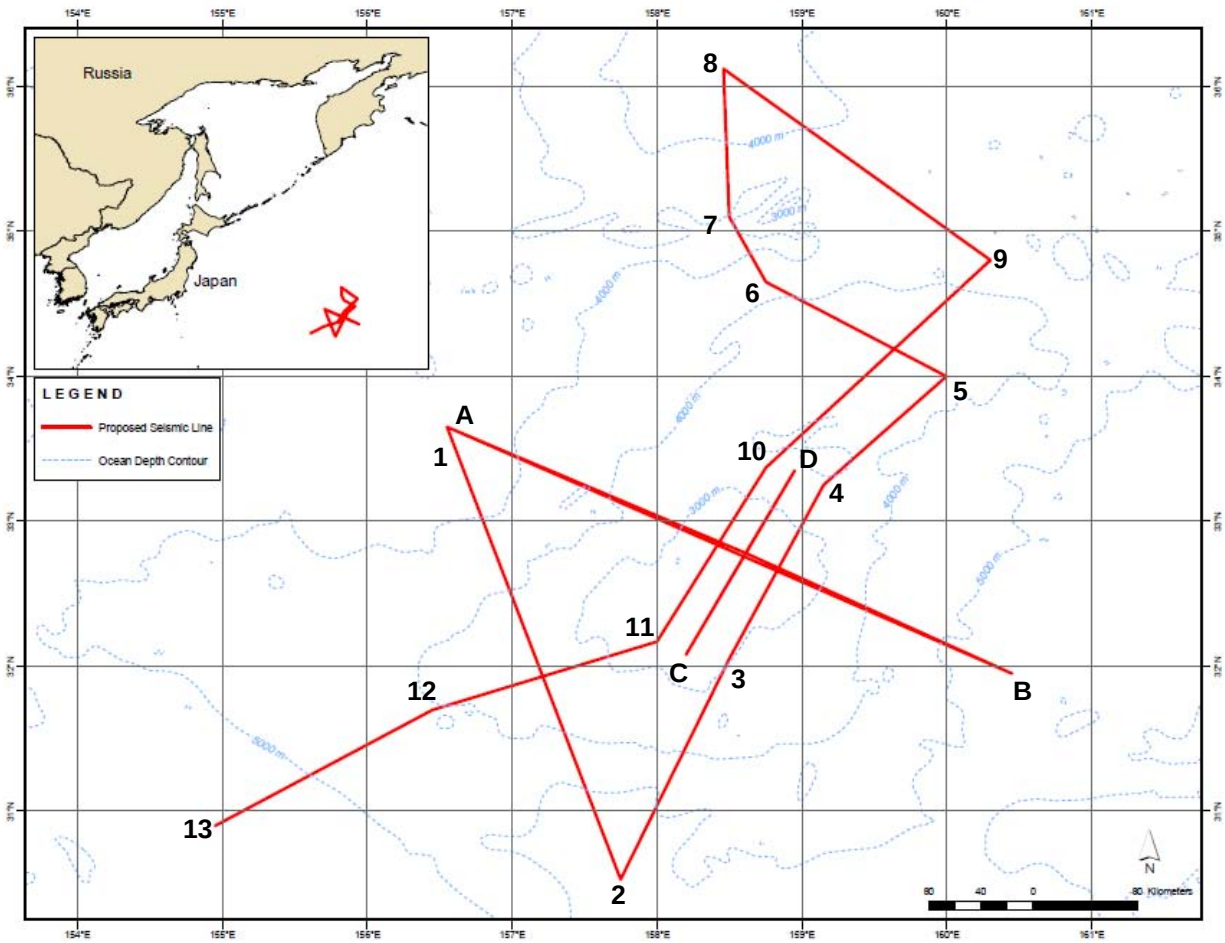

FIGURE 1. Study area and proposed seismic transect lines on the Shatsky Rise for the L-DEO survey planned for 23 July – 6 September 2010.

(c) Schedule

The *Langseth* will depart from Apra Harbor, Guam, on 23 July 2010 for a 6-day transit to the study area. After operations have been completed at Shatsky Rise, the vessel will travel to Honolulu, HI, for arrival on 6 September 2010. Seismic operations in the study area will be carried out for ~17 days, with the balance of the cruise occupied with deployment and retrieval of OBSs (8 days), and transit to and from the study area. Some minor deviation from this schedule is possible, depending on logistics and weather (i.e., the cruise may depart earlier or be extended due to poor weather; there could be extra days of seismic operations if collected data are of substandard quality).

(d) Source Vessel Specifications

The R/V *Marcus G. Langseth* will be used as the source vessel. The *Langseth* will tow the 36-airgun array, as well as the hydrophone streamer, along predetermined lines (Fig. 1). The *Langseth* will also deploy and retrieve OBSs. When the *Langseth* is towing the airgun array and the hydrophone streamer, the turning rate of the vessel is limited to five degrees per minute. Thus, the maneuverability of the vessel is limited during operations with the streamer.

The *Langseth* has a length of 71.5 m, a beam of 17.0 m, and a maximum draft of 5.9 m. The *Langseth* was designed as a seismic research vessel, with a propulsion system designed to be as quiet as

possible to avoid interference with the seismic signals. The ship is powered by two Bergen BRG-6 diesel engines, each producing 3550 hp, which drive the two propellers directly. Each propeller has four blades, and the shaft typically rotates at 750 revolutions per minute (rpm). The vessel also has an 800 hp bow-thruster, which is not used during seismic acquisition. The operation speed during seismic acquisition is typically 7.4–9.3 km/h. When not towing seismic survey gear, the *Langseth* typically cruises at 18.5 km/h and has a range of 25,000 km (the distance the vessel can travel without refueling).

The *Langseth* will also serve as the platform from which vessel-based marine mammal (and sea turtle) observers (MMOs) will watch for animals before and during airgun operations, as described in § II(3), below.

Other details of the *Langseth* include the following:

Owner:	National Science Foundation
Operator:	Lamont-Doherty Earth Observatory of Columbia University
Flag:	United States of America
Date Built:	1991 (Refitted in 2006)
Gross Tonnage:	3834
Accommodation Capacity:	55 including ~35 scientists

(e) Airgun Description

During the survey, the airgun array to be used will consist of 36 airguns, with a total volume of ~6600 in^3. The airgun array will consist of a mixture of Bolt 1500LL and Bolt 1900LLX airguns. The airguns will be configured as four identical linear arrays or "strings" (Fig. 2). Each string will have ten airguns; the first and last airguns in the strings are spaced 16 m apart. Nine airguns in each string will be fired simultaneously, whereas the tenth is kept in reserve as a spare, to be turned on in case of failure of another airgun. The four airgun strings will be distributed across an area of ~24×16 m behind the *Langseth* and will be towed ~100 m behind the vessel. The shot interval will be relatively short (20 s) for MCS surveying with the hydrophone streamer, and relatively long (70 s) when recording data on the OBSs. The firing pressure of the array is 1900 psi. During firing, a brief (~0.1 s) pulse of sound is emitted. The airguns will be silent during the intervening periods.

The tow depth of the array will be 12 m for the OBS lines (A-B and C-D) and 9 m for MCS lines. Because the actual source is a distributed sound source (36 airguns) rather than a single point source, the highest sound levels measurable at any location in the water will be less than the nominal source level. In addition, the effective source level for sound propagating in near-horizontal directions will be substantially lower than the nominal source level applicable to downward propagation because of the directional nature of the sound from the airgun array.

<u>36-Airgun Array Specifications</u>

Energy Source	Thirty-six 1900 psi Bolt airguns of 40–360 in^3, in four strings each containing nine operating airguns
Source output (downward)	0-pk is 84 bar-m (259 dB re 1 μPa·m); pk-pk is 177 bar·m (265 dB)
Air discharge volume	~6600 in^3
Dominant frequency components	2–188 Hz

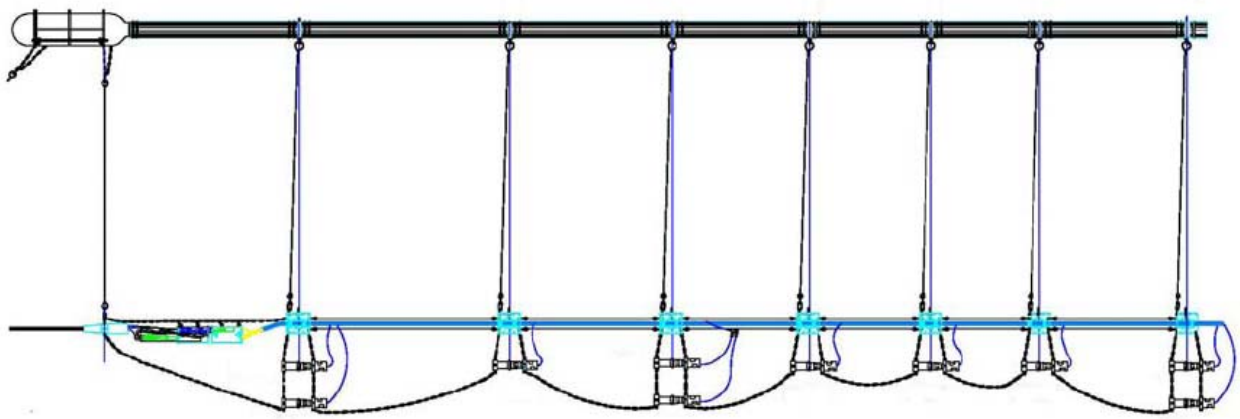

FIGURE 2. One linear airgun array or string with ten airguns, nine of which would be operating.

(f) OBS Description and Deployment

Approximately 28 OBSs will be deployed by the R/V *Langseth* before the survey. Twenty OBSs will be deployed along line A-C, and eight OBSs will be deployed along line C-D (Fig. 1). Deployment is expected to take ~3 days. All OBSs will be retrieved after seismic operations are completed, and retrieval is expected to take ~5 days.

Woods Hole Oceanographic Institution (WHOI) "D2" OBSs will be used during the cruise. This type of OBS has a height of ~1 m and a maximum diameter of 50 cm. The anchor is made of hot-rolled steel and weighs 23 kg. The anchor dimensions are 2.5 × 30.5 × 38.1 cm. Once an OBS is ready to be retrieved, an acoustic release transponder interrogates the OBS at a frequency of 9–11 kHz, and a response is received at a frequency of 9–13 kHz. The burn-wire release assembly is then activated, and the instrument is released from the anchor to float to the surface.

(g) Multibeam Echosounder and Sub-bottom Profiler

Along with the airgun operations, two additional acoustical data acquisition systems will be operated during the survey. The ocean floor will be mapped with the Kongsberg EM 122 MBES and a Knudsen 320B SBP. These sound sources will be operated from the *Langseth* continuously throughout the cruise.

The Kongsberg EM 122 MBES operates at 10.5–13 (usually 12) kHz and is hull-mounted on the *Langseth*. The transmitting beamwidth is 1 or 2° fore–aft and 150° athwartship. The maximum source level is 242 dB re 1 $\mu Pa \cdot m_{rms}$. Each "ping" consists of eight (in water >1000 m deep) or four (<1000 m) successive fan-shaped transmissions, each ensonifying a sector that extends 1° fore–aft. Continuous-wave (CW) pulses increase from 2 to 15 ms long in water depths up to 2600 m, and FM chirp pulses up to 100 ms long are used in water >2600 m. The successive transmissions span an overall cross-track angular extent of about 150°, with 2-ms gaps between the pulses for successive sectors.

The Knudsen 320B SBP is normally operated to provide information about the sedimentary features and the bottom topography that is being mapped simultaneously by the MBES. The beam is transmitted as a 27º cone, which is directed downward by a 3.5-kHz transducer in the hull of the *Langseth*. The maximum output is 1000 watts (204 dB), but in practice, the output varies with water depth. The pulse interval is 1 s, but a common mode of operation is to broadcast five pulses at 1-s intervals followed by a 5-s pause.

Langseth Sub-bottom Profiler Specifications

Maximum source output (downward)	204 dB re 1 μPa·m; 800 watts
Dominant frequency components	3.5 kHz
Bandwidth	1.0 kHz with pulse duration 4 ms
	0.5 kHz with pulse duration 2 ms
	0.25 kHz with pulse duration 1 ms
Nominal beam width	30 degrees
Pulse duration	1, 2, or 4 ms

(3) Monitoring and Mitigation Measures

Numerous species of marine mammals are known to occur in the proposed study area. However, the number of individual animals expected to be approached closely during the proposed activities will be relatively small in relation to regional population sizes. With the proposed monitoring and mitigation provisions, effects on most if not all individuals are expected to be limited to minor behavioral disturbance. Those effects are expected to have negligible impacts both on individual marine mammals and on the associated species and stocks.

To minimize the likelihood that impacts will occur to the species and stocks, airgun operations will be conducted in accordance with all applicable U.S. federal regulations and IHA requirements.

The following subsections provide more detailed information about the monitoring and mitigation measures that are an integral part of the planned activities. The procedures described here are based on protocols used during previous L-DEO seismic research cruises as approved by NMFS, and on best practices recommended in Richardson et al (1995), Pierson et al. (1998), and Weir and Dolman (2007).

(a) Visual Monitoring

MMOs will watch for marine mammals and turtles near the seismic source vessel during all daytime airgun operations and during any start ups of the airguns at night. Airgun operations will be suspended when marine mammals or turtles are observed within, or about to enter, designated exclusion zones [see subsection (d) below] where there is concern about potential effects on hearing or other physical effects. MMOs will also watch for marine mammals and turtles near the seismic vessel for at least 30 min prior to the planned start of airgun operations after an extended shut down of the airguns. When feasible, observations will also be made during daytime periods when the *Langseth* is underway without seismic operations, such as during transits.

During seismic operations, at least four visual observers will be based aboard the *Langseth*. MMOs will be appointed by L-DEO with NMFS concurrence. At least one MMO, and when practical two MMOs, will monitor marine mammals and turtles near the seismic vessel during ongoing daytime operations and nighttime start ups of the airguns. Use of two simultaneous observers will increase the effectiveness of detecting animals near the source vessel. MMO(s) will be on duty in shifts of duration no longer than 4 h. Other crew will also be instructed to assist in detecting marine mammals and turtles and implementing mitigation requirements (if practical). Before the start of the seismic survey the crew will be given additional instruction regarding how to do so.

The *Langseth* is a suitable platform for marine mammal and turtle observations. When stationed on the observation platform, the eye level will be ~21.5 m above sea level, and the observer will have a good view around the entire vessel. During daytime, the MMO(s) will scan the area around the vessel systematically with reticle binoculars (e.g., 7×50 Fujinon), Big-eye binoculars (25×150), and with the

naked eye. During darkness, night vision devices (NVDs) will be available (ITT F500 Series Generation 3 binocular-image intensifier or equivalent), when required. Laser rangefinding binoculars (Leica LRF 1200 laser rangefinder or equivalent) will be available to assist with distance estimation. Those are useful in training observers to estimate distances visually, but are generally not useful in measuring distances to animals directly; that is done primarily with the reticles in the binoculars.

When mammals or turtles are detected within or about to enter the designated exclusion zone, the airguns will immediately be powered down or shut down if necessary. The MMO(s) will continue to maintain watch to determine when the animal(s) are outside the exclusion zone. Airgun operations will not resume until the animal has left the exclusion zone.

The vessel-based monitoring will provide data to estimate the numbers of marine mammals exposed to various received sound levels, to document any apparent disturbance reactions or lack thereof, and thus to estimate the numbers of mammals potentially "taken" by harassment. It will also provide the information needed in order to power down or shut down the airguns at times when mammals or turtles are present in or near the exclusion zone. When a sighting is made, the following information about the sighting will be recorded:

1. Species, group size, age/size/sex categories (if determinable), behavior when first sighted and after initial sighting, heading (if consistent), bearing and distance from seismic vessel, sighting cue, apparent reaction to the airguns or vessel (e.g., none, avoidance, approach, paralleling, etc.), and behavioral pace.
2. Time, location, heading, speed, activity of the vessel, sea state, visibility, and sun glare.

The data listed under (2) will also be recorded at the start and end of each observation watch, and during a watch whenever there is a change in one or more of the variables.

All observations and power downs or shut downs will be recorded in a standardized format. Data will be entered into an electronic database. The accuracy of the data entry will be verified by computerized data validity checks as the data are entered and by subsequent manual checking of the database. These procedures will allow initial summaries of data to be prepared during and shortly after the field program, and will facilitate transfer of the data to statistical, graphical, and other programs for further processing and archiving.

Results from the vessel-based observations will provide

1. The basis for real-time mitigation (airgun power down or shut down).
2. Information needed to estimate the number of marine mammals potentially taken by harassment, which must be reported to NMFS.
3. Data on the occurrence, distribution, and activities of marine mammals and turtles in the area where the seismic study is conducted.
4. Information to compare the distance and distribution of marine mammals and turtles relative to the source vessel at times with and without seismic activity.
5. Data on the behavior and movement patterns of marine mammals and turtles seen at times with and without seismic activity.

(b) Passive Acoustic Monitoring

Passive acoustic monitoring (PAM) will take place to complement the visual monitoring program, when practicable. Visual monitoring typically is not effective during periods of poor visibility or at night. Even with good visibility during the daytime, observers are not able to detect marine mammals when they are below the surface or beyond visual range. Acoustical monitoring can be used in addition to visual observations to improve detection, identification, and localization of cetaceans. The acoustic monitoring will serve to alert visual observers (if on duty) when vocalizing cetaceans are detected. It is only useful when marine mammals call, but it can be effective either by day or by night, and does not depend on good visibility. It will be monitored in real time so that the visual observers can be advised when cetaceans are detected. When bearings (primary and mirror-image) to calling cetacean(s) are determined, the bearings will be relayed to the visual observer to help him/her sight the calling animal(s).

The PAM system consists of hardware (i.e., hydrophones) and software. The "wet end" of the system consists of a towed four-hydrophone array, two of which are monitored simultaineously; the active section of the array is ~30 m long. The array is attached to the vessel by a 250-m electromechanical lead-in cable and a 50-m long deck lead-in cable. However, not the entire length of lead-in cable is used; thus, the hydrophones are typically located 120 m behind the stern of the ship. The deck cable is connected from the array to a computer in the laboratory where signal conditioning and processing takes place. The digitized signal is then sent to the main laboratory, where the acoustic MMO monitors the system. The hydrophone array is typically towed at depths <20 m.

The towed hydrophones will ideally be monitored 24 h per day while at the seismic survey area during airgun operations, and during most periods when the *Langseth* is underway while the airguns are not operating. One MMO will monitor the acoustic detection system at any one time, by listening to the signals from two channels via headphones and/or speakers and watching the real-time spectrographic display for frequency ranges produced by cetaceans. MMOs monitoring the acoustical data will be on shift for 1–6 h at a time. Besides the visual MMOs, an additional MMO with primary responsibility for PAM will also be aboard. All MMOs are expected to rotate through the PAM position, although the most experienced with acoustics will be on PAM duty more frequently.

When a vocalization is detected while visual observations are in progress, the acoustic MMO will contact the visual MMO immediately, to alert him/her to the presence of cetaceans (if they have not already been seen), and to allow a power down or shut down to be initiated, if required. The information regarding the call will be entered into a database. The data to be entered include an acoustic encounter identification number, whether it was linked with a visual sighting, date, time when first and last heard and whenever any additional information was recorded, position and water depth when first detected, bearing if determinable, species or species group (e.g., unidentified dolphin, sperm whale), types and nature of sounds heard (e.g., clicks, continuous, sporadic, whistles, creaks, burst pulses, strength of signal, etc.), and any other notable information. The acoustic detection can also be recorded for further analysis.

(c) Reporting

A report will be submitted to NMFS and NSF within 90 days after the end of the cruise. The report will describe the operations that were conducted and sightings of marine mammals and turtles near the operations. The report will provide full documentation of methods, results, and interpretation pertaining to all monitoring. The 90-day report will summarize the dates and locations of seismic operations, and all marine mammal and turtle sightings (dates, times, locations, activities, associated seismic survey activities). The report will also include estimates of the number and nature of exposures that could result in "takes" of marine mammals by harassment or in other ways.

(d) Proposed Exclusion Zones

Acoustic Measurement Units.—Received sound levels have been predicted by L-DEO, in relation to distance and direction from the airguns, for the 36-airgun array and for a single 1900LL 40-in^3 airgun, which will be used during power downs. Results were recently reported for propagation measurements of pulses from the 36-airgun array in two water depths (~1600 m and 50 m) in the Gulf of Mexico in 2007–2008 (Tolstoy et al. 2009). It would be prudent to use the empirical values that resulted to determine exclusion zones for the airgun array. Measurements were not reported for a single airgun, so model results (Fig. 3) will be used. A detailed description of the modeling effort is provided in Appendix A.

The predicted sound contours for the 40-in^3 mitigation airgun are shown as sound exposure levels (SEL) in decibels (dB) re 1 $\mu Pa^2 \cdot s$. SEL is a measure of the received energy in the pulse and represents the sound pressure level (SPL) that would be measured if the pulse energy were spread evenly across a 1-s period. Because actual seismic pulses are less than 1 s in duration in most situations, this means that the SEL value for a given pulse is usually lower than the SPL calculated for the actual duration of the pulse (see Appendix B). The advantage of working with SEL is that the SEL measure accounts for the total received energy in the pulse, and biological effects of pulsed sounds are believed to depend mainly on pulse energy (Southall et al. 2007). In contrast, SPL for a given pulse depends greatly on pulse duration. A pulse with a given SEL can be long or short depending on the extent to which propagation effects have "stretched" the pulse duration. The SPL will be low if the duration is long and higher if the duration is short, even though the pulse energy (and presumably the biological effects) are the same.

Although SEL is now believed to be a better measure than SPL when dealing with biological effects of pulsed sound, SPL is the measure that has been most commonly used in studies of marine mammal reactions to airgun sounds and in NMFS guidelines concerning levels above which "taking" might occur. SPL is often referred to as rms or "root mean square" pressure, averaged over the pulse duration. As noted above, the rms received levels that are used as impact criteria for marine mammals are not directly comparable to pulse energy (SEL). At the distances where rms levels are 160–190 dB re 1 μPa, the difference between the SEL and SPL values for the same pulse measured at the same location usually average ~10–15 dB, depending on the propagation characteristics of the location (Greene 1997; McCauley et al. 1998, 2000a; Appendix B). In this EA, we assume that rms pressure levels of received seismic pulses will be 10 dB higher than the SEL values predicted by L-DEO's model. Thus, we assume that 170 dB SEL ≈ 180 dB re 1 μPa_{rms}. It should be noted that neither the SEL nor the SPL (=rms) measure is directly comparable to the peak or peak-to-peak pressure levels normally used by geophysicists to characterize source levels of airguns. Peak and peak-to-peak pressure levels for airgun pulses are always higher than the rms dB referred to in much of the biological literature (Greene 1997; McCauley et al. 1998, 2000a). For example, a measured received level of 160 dB re 1 μPa_{rms} in the far field typically would correspond to a peak measurement of ~170–172 dB re 1 μPa, and to a peak-to-peak measurement of ~176–178 dB re 1 μPa, as measured for the same pulse received at the same location (Greene 1997; McCauley et al. 1998, 2000a). (The SEL value for the same pulse would normally be 145–150 dB re 1 $\mu Pa^2 \cdot s$). The precise difference between rms and peak or peak-to-peak values for a given pulse depends on the frequency content and duration of the pulse, among other factors. However, the rms level is always lower than the peak or peak-to-peak level and (for an airgun-type source at the ranges relevant here) higher than the SEL value.

Results of the propagation measurements (Tolstoy et al. 2009) showed that radii around the airguns for various received levels varied with water depth. During the proposed study, all survey effort will take place in deep (>1000 m) water, so propagation in shallow water is not relevant here. However, the depth of the array was different in the Gulf of Mexico calibration study (6 m) than in the proposed survey (9 or

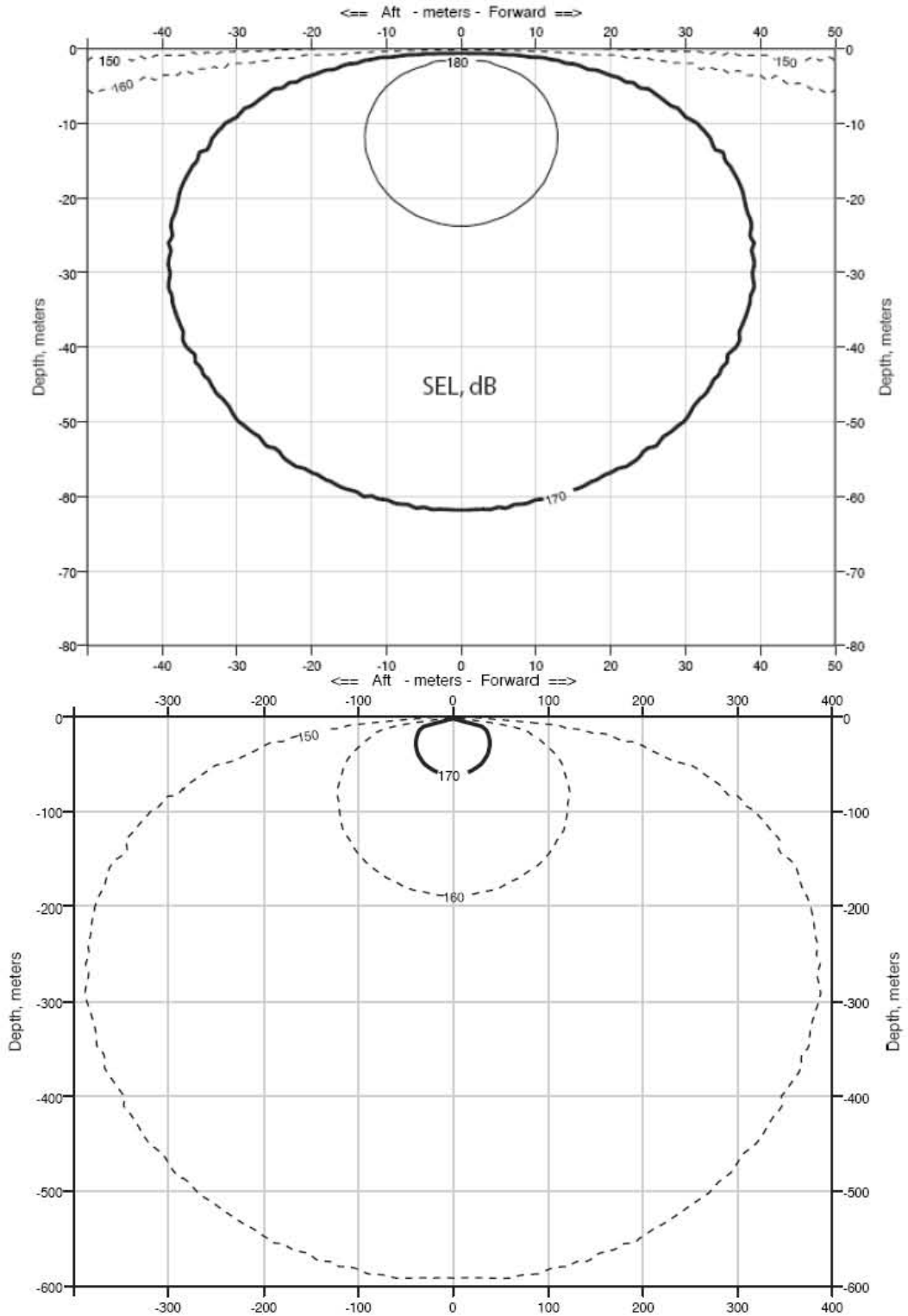

FIGURE 3. Modeled received sound levels (SELs) from a single 40-in^3 airgun operating in deep water, which is planned for use as a mitigation airgun during the Shatsky Rise survey, 23 July–6 September 2010. Received rms levels (SPLs) are expected to be ~10 dB higher.

12 m). Because propagation varies with array depth, correction factors have been applied to the distances reported by Tolstoy et al. (2009). The correction factors used were the ratios of the 160-, 170-, 180-, and 190-dB distances from the modeled results for the 6600-in^3 airgun array towed at 6 m vs. 9 m and 6 m vs. 12 m.

Using the corrected measurements (array) or model (single airgun), Table 1 shows the distances at which four rms sound levels are expected to be received from the 36-airgun array and a single airgun. The 180- and 190-dB re 1 μPa_{rms} distances are the safety criteria as specified by NMFS (2000) and are applicable to cetaceans and pinnipeds, respectively. The 180-dB distance will also be used as the exclusion zone for sea turtles, as required by NMFS in most other recent seismic projects (e.g., Smultea et al. 2004; Holst et al. 2005b; Holst and Beland 2008; Holst and Smultea 2008; Hauser et al. 2008). If marine mammals or turtles are detected within or about to enter the appropriate exclusion zone, the airguns will be powered down (or shut down if necessary) immediately.

Southall et al. (2007) made detailed recommendations for new science-based noise exposure criteria. L-DEO will be prepared to revise its procedures for estimating numbers of mammals "taken", exclusion zones, etc., as may be required by any new guidelines established by NMFS as a result of these recommendations. However, currently the procedures are based on best practices noted by Pierson et al. (1998) and Weir and Dolman (2007) as NMFS has not yet specified a new procedure for determining exclusion zones.

(e) Mitigation During Operations

Mitigation measures that will be adopted during the survey include (1) power-down procedures, (2) shut-down procedures, and (3) ramp-up procedures.

***Power-down Procedures*.—**A power down involves decreasing the number of airguns in use such that the radius of the 180-dB (or 190-dB) zone is decreased to the extent that marine mammals or turtles are no longer in or about to enter the exclusion zone. A power down of the airgun array can also occur when the vessel is moving from one seismic line to another. During a power down for mitigation, one airgun will be operated. The continued operation of one airgun is intended to alert marine mammals and turtles to the presence of the seismic vessel in the area. In contrast, a shut down occurs when all airgun activity is suspended.

If a marine mammal (other than right whales—see *Shut-down Procedures* below) or turtle is detected outside the exclusion zone but is likely to enter the exclusion zone, the airguns will be powered down before the animal is within the exclusion zone. Likewise, if a mammal or turtle is already within the safety zone when first detected, the airguns will be powered down immediately. During a power down of the airgun array, the 40-in^3 airgun will be operated. If a marine mammal or turtle is detected within or near the smaller exclusion zone around that single airgun (Table 1), it will be shut down (see next subsection).

Following a power down, airgun activity will not resume until the marine mammal or turtle has cleared the safety zone. The animal will be considered to have cleared the safety zone if

- it is visually observed to have left the exclusion zone, or
- it has not been seen within the zone for 15 min in the case of small odontocetes (or pinnipeds), or
- it has not been seen within the zone for 30 min in the case of mysticetes and large odontocetes, including sperm, pygmy sperm, dwarf sperm, and beaked whales, or

TABLE 1. Measured (array) or predicted (single airgun) distances to which sound levels ≥190, 180, 170, and 160 dB re 1 μPa$_{rms}$ could be received in deep (>1000 m) water during the proposed Shatsky Rise survey, 23 July–6 September 2010. Measured radii for the array are based on Tolstoy at al. (2009), and predicted radii for a single airgun are based on Figure 3, assuming that received levels on an RMS basis are, numerically, 10 dB higher than the SEL values shown in Figure 3.

Source and Volume	Tow depth (m)	Predicted RMS Distances (m) in deep (>1000 m) water			
		190 dB	180 dB	170 dB	160 dB
Single Bolt airgun, 40 in^3	9-12	12	40	120	385
4 strings, 36 airguns, 6600 in^3	9	400	940	2200	3850
4 strings, 36 airguns, 6600 in^3	12	460	1100	2510	4400

- the vessel has moved outside the exclusion zone for turtles, e.g., if a turtle is sighted close to the vessel and the ship speed is 7.4 km/h, it would take the vessel ~8 min to leave the turtle behind].

During airgun operations following a power down (or shut down) whose duration has exceeded the time limits specified above, the airgun array will be ramped up gradually. Ramp-up procedures are described below.

***Shut-down Procedures*.—**The operating airgun(s) will be shut down if a marine mammal or turtle is seen within or approaching the exclusion zone for the single airgun. Shut downs will be implemented (1) if an animal enters the exclusion zone of the single airgun after a power down has been initiated, or (2) if an animal is initially seen within the exclusion zone of the single airgun when more than one airgun (typically the full array) is operating. Airgun activity will not resume until the marine mammal or turtle has cleared the safety zone, or until the MMO is confident that the animal has left the vicinity of the vessel. Criteria for judging that the animal has cleared the safety zone will be as described in the preceding subsection.

Considering the conservation status for the North Pacific right whale, the airgun(s) will be shut down immediately in the unlikely event that this species is observed, regardless of the distance from the *Langseth*. Ramp up will only begin if the whale has not been seen for 30 min.

***Ramp-up Procedures*.—**A ramp-up procedure will be followed when the airgun array begins operating after a specified period without airgun operations or when a power down has exceeded that period. It is proposed that, for the present cruise, this period would be ~8 min. This period is based on the 180-dB radius (940 m) for the 36-airgun array towed at 9 m in relation to the minimum planned speed of the *Langseth* while shooting (7.4 km/h). Similar periods (~8–10 min) were used during previous L-DEO surveys.

Ramp up will begin with the smallest airgun in the array (40 in^3). Airguns will be added in a sequence such that the source level of the array will increase in steps not exceeding 6 dB per 5-min period over a total duration of ~35 min. During ramp up, the MMOs will monitor the exclusion zone, and if

marine mammals or turtles are sighted, a power down or shut down will be implemented as though the full array were operational.

If the complete exclusion zone has not been visible for at least 30 min prior to the start of operations in either daylight or nighttime, ramp up will not commence unless at least one airgun (40 in^3 or similar) has been operating during the interruption of seismic survey operations. Given these provisions, it is likely that the airgun array will not be ramped up from a complete shut down at night or in thick fog, because the outer part of the safety zone for that array will not be visible during those conditions. If one airgun has operated during a power-down period, ramp up to full power will be permissible at night or in poor visibility, on the assumption that marine mammals and turtles will be alerted to the approaching seismic vessel by the sounds from the single airgun and could move away. Ramp up of the airguns will not be initiated if a sea turtle or marine mammal is sighted within or near the applicable exclusion zones during the day or close to the vessel at night.

Alternative Action: Another Time

An alternative to issuing the IHA for the period requested and to conducting the project then is to issue the IHA for another time and to conduct the project at that alternative time. The proposed time for the cruise is the most suitable time logistically for the *Langseth* (and the participating scientists) and takes into consideration the timing of the typhoon season. If the IHA is issued for another period, it could result in significant delay and disruption not only of the proposed cruise, but of subsequent geophysical studies that are planned by L-DEO for 2010 and beyond. An evaluation of the effects of this alternative action is given in § IV.

No Action Alternative

An alternative to conducting the proposed activities is the ”No Action” alternative, i.e., do not issue an IHA and do not conduct the research operations. If the research is not conducted, the “No Action” alternative would result in no disturbance to marine mammals due to the proposed activities.

The seismic data from the proposed survey are necessary to decipher the crustal structure of the Shatsky Rise. The sheer scale of plateau formation implies a potential role in environmental crises such as oceanic anoxia and mass extinctions. Data obtained from the survey will also improve our understanding of tectonics and earthquake occurrence and distribution. Under the “No Action” alternative, this valuable scientific information would not become available.

In addition to forcing cancellation of the planned seismic survey, the “No Action” alternative could also, in some circumstances, result in significant delay of other geophysical studies that are planned by L-DEO for 2010 and beyond, depending on the timing of the decision. The entire proposal, based on the premise of collecting these data, would be compromised. Cancellation (no action) for this cruise would decrease available data and support for the academic institutions involved. Data collection is an essential first step for a much greater effort to analyze and report information concerning the scientifically significant topics indicated. The field effort will provide material for years of analyses involving multiple professors, students, and technicians. The lost opportunity to collect valuable scientific information would be compounded by lost opportunities for support of research infrastructure, training, and professional career growth.

III. AFFECTED ENVIRONMENT

Oceanography

Shatsky Rise is an enormous underwater feature comprising three seamounts and spanning ~750,000 km^2 of the sea floor; it is the second largest plateau in the Pacific Ocean (Sliter and Brown 1993). Water depth varies from ~2000 m above the largest bathymetric feature to more than 6000 m in the adjacent Northwest Pacific Basin. The largest and southernmost of the three seamounts is located at ~32ºN, 157ºE and at the approximate intersection of three oceanographic provinces: the Kuroshio Current Province to the northwest, the North Pacific Polar Front Province to the northeast, and the North Pacific Subtropical Gyre Province to the south (Longhurst 2007). Or, according to a newer classification of ocean provinces, the Shatsky Rise is in the high-seas west of the Cold Temperate Northwest Pacific Province (Spalding et al. 2007).

Below depths of 3500 m and between Shatsky Rise and the Mariana Trench (to the southwest) is cold water (<1.2ºC) associated with the Lower Circumpolar Deep Water current. Upper Circumpolar Deep Water and North Pacific Deep Water (1.3 to 2.2ºC) interact at depths between 2000 and 3500 m south of the seamounts (Kawabe et al. 2009).

The prominent oceanic feature above the Shatsky Rise is associated with the Kuroshio Extension – a warm-water surface current that jets eastward from Japan across the Pacific Basin. Free from coastal influence, the Kuroshio Current (called the Kuroshio Extension once offshore) forms a meandering, inertial jet and series of back-eddies that transports large amounts of heat energy into the north Pacific (Nishida and White 1982; Mizuno and White 1983; Qiu 2000; Yasuda 2003). The Extension meanders directly over the Shatsky Rise, where it bifurcates and gradually dissipates eastward (Nishida and White 1982; Mizuno and White 1983; Qu et al. 2001).

There are multiple current fronts where this meandering jet collides with the cold Oyashio Current and oceanic Polar Frontal Zone (Longhurst 2007). Although the Kuroshio is considered oligotrophic (i.e., low nutrients), these oceanic fronts are sharp boundaries between physical and chemical parameters that tend to aggregate pelagic organisms as the colder, nutrient-rich water cascades beneath the warmer surface water. Low trophic level predators like jellies can maintain position in these downwelling zones and capitalize on the influx of prey like copepods, smaller jellies, larval fish, and diatoms (Polovina et al. 2000). According to Sea Around Us (2009), the primary productivity of the Kuroshio Current Large Marine Ecosystem (LME) is 402 $mgC \cdot m^{-2} \cdot day^{-1}$, and for the Oyashio Current LME, it is 697 $mgC \cdot m^{-2} \cdot day^{-1}$. For the exclusive economic zone (EEZ) of Japan, the main islands have a primary production of 572 $mgC \cdot m^{-2} \cdot day^{-1}$, and the outer islands of the EEZ have a primary production of 271 $mgC \cdot m^{-2} \cdot day^{-1}$.

Other regions of increased productivity appear in the vortices of the warm-core rings and immediately west of Shatsky Rise, where the Kuroshio Extension bifurcates and chlorophyll concentrations bloom in April and May (Komatsu et al. 2002). This spring bloom near Shatsky Rise fades in late summer, before a gradual increase and sharp drop off again in the dark winter months (Polovina et al. 2006; Longhurst 2007). This complex system of fronts and back-eddies — and the escalated levels of biomass they support — have long been known by Japanese fishers seeking optimal fishing grounds for swordfish, tuna, Pacific saury, pelagic sharks, sardine, and other commercially important fish (Komatsu et al. 2002; Yokota et al. 2006).

Marine Mammals

Thirty-three cetacean species, including 26 odontocete (dolphins and small- and large-toothed whales) species and seven mysticetes (baleen whales) may occur in the Shatsky Rise study area (Table 2). In addition, the southern extent of the pelagic range for the northern fur seal overlaps with the study area. Information on the occurrence, distribution, population size, and conservation status for each of the 34 marine mammal species that may occur in the proposed study area is presented in Table 2. The status of these species is based on the ESA, the IUCN Red List of Threatened Species, and the Convention on International Trade in Endangered Species (CITES). Several of these species are listed under the ESA as endangered, including the North Pacific right, sperm, humpback, fin, sei, and blue whales.

The Western North Pacific gray whale also occurs in the Northwest Pacific Ocean; it is listed as endangered under the ESA and as critically endangered by the IUCN. Its migration route is believed to include the Pacific coast of Japan (Reilly et al. 2008a). Although the offshore limit of this route is not well documented, gray whales are known to prefer nearshore coastal waters. Hence, it is extremely unlikely that this species would occur within the proposed study area. Therefore, the gray whale is not analyzed further and is not included in the density table (see below) or as take requests.

(1) Mysticetes

North Pacific Right Whale

The North Pacific right whale is listed as ***endangered*** under the ESA, ***endangered*** on the 2009 IUCN Red List of Threatened Species (IUCN 2009), and it is listed in CITES Appendix I (UNEP-WCMC 2009) (Table 2). It is considered by NMFS (1991) to be the most endangered baleen whale in the world. Although protected from commercial whaling since 1935, there has been little indication of recovery. The pre-exploitation stock may have exceeded 11,000 animals (NMFS 1991). There are no reliable current population estimates for this species. Wada (1973; see also Braham and Rice 1984) provided an estimate of 100–200 right whales in the North Pacific. More recently, Miyashita and Kato (1998 *in* Kato et al. 2005) suggested an abundance of 420–2100 right whales for the Sea of Okhotsk, and Jefferson et al. (2008) indicate that there are “no more than a few hundred right whales alive today”.

North Pacific right whales summer in the northern North Pacific and Bering Sea, apparently feeding off southern and western Alaska from May to September (e.g., Tynan et al. 2001). Wintering and breeding areas are unknown, but have been suggested to include the Hawaiian Islands, the Ryukyu Islands, and the Sea of Japan (Allen 1942; Banfield 1974; Gilmore 1978; Reeves et al. 1978; Herman et al. 1980; Omura 1986), as well as Guangdong province, southern China (Rudolph and Smeenk 2002). The Hawaiian Islands were not a major calving ground for right whales in the last 200 years, but mid-ocean whaling records of right whales during winter suggest that right whales may have wintered and calved far offshore in the Pacific Ocean (Scarff 1986, 1991; Clapham et al. 2004). In April 1996, a right whale was sighted off Maui, the first documented sighting of a right whale in Hawaiian waters since 1979 (Herman et al. 1980; Rowntree et al. 1980).

Whaling records indicate that right whales once ranged across the entire North Pacific Ocean north of 35ºN and occasionally occurred as far south as 20ºN. In the western Pacific, most sightings in the 1900s were reported from Japanese waters, followed by the Kuril Islands, and the Okhotsk Sea (Brownell et al. 2001). However, since the 1960s sightings have been relatively rare (e.g., Clapham et al. 2004; Shelden et al. 2005). Nonetheless, in the western Pacific, significant numbers of right whales have been

TABLE 2. The habitat, regional population sizes, and conservation status of marine mammals that could occur in or near the proposed seismic survey area on the Shatsky Rise in the Northwest Pacific Ocean.

Species	Habitat	Regional pop. Size [a]	U.S. ESA [b]	IUCN [c]	CITES [d]
Mysticetes					
North Pacific right whale (*Eubalaena japonica*)	Pelagic and coastal	few 100 [e]	EN	EN	I
Humpback whale (*Megaptera novaeangliae*)	Mainly nearshore waters and banks	938–1107 [f]	EN	LC	I
Minke whale (*Balaenoptera acutorostrata*)	Pelagic and coastal	25,000 [g]	NL	LC	I
Bryde's whale (*Balaenoptera edeni* and *B. brydei*)	Pelagic and coastal	20,501 [h]	NL	DD	I
Sei whale (*Balaenoptera borealis*)	Primarily offshore, pelagic	7260-12,620 [i]	EN	EN	I
Fin whale (*Balaenoptera physalus*)	Continental slope, mostly pelagic	13,620–18,680 [j]	EN	EN	I
Blue whale (*Balaenoptera musculus*)	Pelagic and coastal	3500 [k]	EN	EN	I
Odontocetes					
Sperm whale (*Physeter macrocephalus*)	Usually pelagic and deep seas	29,674 [l]	EN	VU	I
Pygmy sperm whale (*Kogia breviceps*)	Deep waters off the shelf	N.A.	NL	DD	II
Dwarf sperm whale (*Kogia sima*)	Deep waters off the shelf	11,200 [m]	NL	DD	II
Cuvier's beaked whale (*Ziphius cavirostris*)	Pelagic	20,000 [m]	NL	LC	II
Baird's beaked whale (*Berardius bairdii*)	Deep water	N.A.	NL	DD	II
Longman's beaked whale (*Indopacetus pacificus*)	Deep water	N.A.	NL	DD	II
Hubb's beaked whale (*Mesoplodon carlhubbsi*)	Deep water	25,300 [n]	NL	DD	II
Ginkgo-toothed beaked whale (*Mesoplodon ginkgodens*)	Pelagic	25,300 [n]	NL	DD	II
Blainville's beaked whale (*Mesoplodon densirostris*)	Pelagic	25,300 [n]	NL	DD	II
Stejneger's beaked whale (*Mesoplodon stejnegeri*)	Deep water	25,300 [n]	NL	DD	II
Rough-toothed dolphin (*Steno bredanensis*)	Deep water	145,900 [m]	NL	LC	II
Common bottlenose dolphin (*Tursiops truncatus*)	Coastal and oceanic, shelf break	168,000 [o]	NL	LC	II
Pantropical spotted dolphin (*Stenella attenuata*)	Coastal and pelagic	438,000 [o]	NL	LC	II
Spinner dolphin (*Stenella longirostris*)	Coastal and pelagic	801,000 [p]	NL	DD	II
Striped dolphin (*Stenella coeruleoalba*)	Off continental shelf	570,000 [o]	NL	LC	II
Fraser's dolphin (*Lagenodelphis hosei*)	Waters >1000 m	289,300 [m]	NL	LC	II
Short-beaked common dolphin (*Delphinus delphis*)	Shelf and pelagic, seamounts	2,963,000 [q]	NL	LC	II

Species	Habitat	Regional pop. Size [a]	U.S. ESA [b]	IUCN [c]	CITES [d]
Pacific white-sided dolphin (*Lagenorhynchus obliquidens*)	Continental slope and pelagic	988,000 [r]	NL	LC	II
Northern right whale dolphin (*Lissodelphis borealis*)	Deep water	307,000 [r]	NL	LC	II
Risso's dolphin (*Grampus griseus*)	Waters >1000 m, seamounts	838,000 [o]	NL	LC	II
Melon-headed whale (*Peponocephala electra*)	Oceanic	45,400 [m]	NL	LC	II
Pygmy killer whale (*Feresa attenuata*)	Deep, pantropical waters	38,900 [m]	NL	DD	II
False killer whale (*Pseudorca crassidens*)	Pelagic	16,000 [o]	NL	DD	II
Killer whale (*Orcinus orca*)	Widely distributed	8500 [m]	NL	DD	II
Short-finned pilot whale (*Globicephala macrorhynchus*)	Mostly pelagic, high-relief topography	53,000 [o]	NL	DD	II
Dall's porpoise (*Phocoenoides dalli*)	Deep water	1,337,224 [s]	NL	LC	II
Pinnipeds Northern fur seal (*Callorhinus ursinus*)	Coastal and pelagic	1.1 million [t]	NL	VU	-

N.A. - Data not available or species status was not assessed.
[a] Region for population size, in order of preference based on available data, is Western North Pacific, North Pacific, or Eastern Tropical Pacific; see footnotes below.
[b] U.S. Endangered Species Act; EN = Endangered, NL = Not listed.
[c] Codes for IUCN (2009) classifications; EN = Endangered; VU = Vulnerable; LC = Least Concern; DD = Data Deficient.
[d] Convention on International Trade in Endangered Species of Wild Fauna and Flora (UNEP-WCMC 2009): Appendix I = Threatened with extinction; Appendix II = not necessarily now threatened with extinction but may become so unless trade is closely controlled.
[e] North Pacific (Jefferson et al. 2008).
[f] Western North Pacific (Calambokidis et al. 2008).
[g] Northwest Pacific and Okhotsk Sea (Buckland et al. 1992; IWC 2009).
[h] Western North Pacific (Kitakado et al. 2008; IWC 2009).
[i] North Pacific (Tillman 1977).
[j] North Pacific (Ohsumi and Wada 1974).
[k] North Pacific (NMFS 1998).
[l] Western North Pacific (Whitehead 2002b).
[m] Eastern Tropical Pacific (ETP) (Wade and Gerrodette 1993).
[n] ETP; all *Mesoplodon* spp. (Wade and Gerrodette 1993).
[o] Western North Pacific (Miyashita 1993a).
[p] Whitebelly spinner dolphin in the ETP in 2000 (Gerrodette et al. 2005 *in* Hammond et al 2008a).
[q] ETP (Gerrodette and Forcada 2002 *in* Hammond et al 2008b).
[r] North Pacific (Miyashita 1993b).
[s] North Pacific (Buckland et al 1993).
[t] North Pacific, 2004–2005 (Gelatt and Lowry 2008).

seen in the Okhotsk Sea during the 1990s, suggesting that the adjacent Kuril Islands and Kamchatka coast are a major feeding ground (Brownell et al. 2001). Right whales were also seen near Chichi-jima Island (Bonin Islands), Japan, in the 1990s (Mori et al. 1998). During 1994-2007, right whale sightings were also reported off northern Japan, the Kuril Islands, and Kamchatka (Matsuoka et al. 2009). Sightings were reported for the months of April through August, with highest densities occurring in May and August (Matsuoka et al. 2009). All sightings were north of 37ºN (Matsuoka et al. 2009). Right whale sightings were made directly north of the proposed Shatsky Rise study area during May (Matsuoka et al.

2009). However, given the timing of the proposed seismic survey and the relatively small number of whales in this population, it is unlikely that any right whales would be encountered in the study area at the time of the survey.

Humpback Whale

The humpback whale is found throughout all of the oceans of the world (Clapham 2002). The species is listed as ***endangered*** under the ESA, ***least concern*** on the 2009 IUCN Red List of Threatened Species (IUCN 2009), and it is listed in CITES Appendix I (UNEP-WCMC 2009) (Table 2). The worldwide population of humpback whales is divided into northern and southern ocean populations, but genetic analyses suggest some gene flow (either past or present) between the North and South Pacific oceans (e.g., Baker et al. 1993; Caballero et al. 2001). Based on a collaborative study involving numerous jurisdictions, the North Pacific stock has been recently estimated at 18,302 whales, excluding calves (Calambokidis et al. 2008; IUCN 2009). Overall, the North Pacific stock is considered to be increasing. The western Pacific stock is estimated at 938–1107 (Calambokidis et al. 2008). The low population estimate for the western North Pacific subpopulation is a cause for concern for the IUCN (2009). Calambokidis et al. (2008) noted that humpbacks along the coast of Asia appear to be subject to high incidental mortality.

Although considered to be mainly a coastal species, humpback whales often traverse deep pelagic areas while migrating. Humpback whales spend spring through fall on mid- or high-latitude feeding grounds, and winter on low-latitude breeding grounds, with limited interchange between regions (Baker et al. 1998; Clapham 2002; Garrigue et al. 2002). On winter breeding grounds, humpback dives have been recorded at depths >100 m (Baird et al. 2000). In summer feeding areas, humpbacks typically forage in the upper 120 m of the water column, with a maximum recorded dive depth of 500 m (Dolphin 1987; Dietz et al. 2002). Humpback whales are often sighted singly or in groups of two or three; however, while on their breeding and feeding ranges, they may occur in groups of up to 15 (Leatherwood and Reeves 1983; Donoghue 1996).

North Pacific humpback whales migrate between summer feeding grounds along the Pacific Rim and the Bering and Okhotsk seas, and winter calving and breeding areas in subtropical and tropical waters (Pike and MacAskie 1969; Rice 1978). North Pacific humpback whales are known to assemble in three different winter breeding areas: (1) the eastern North Pacific along the coast of Mexico and central America, and near the Revillagigedo Islands; (2) around the main Hawaiian Islands; and (3) in the west Pacific, particularly around the Ogasawara and Ryukyu Islands in southern Japan and the northern Philippines (Perry et al. 1999a; Calambokidis et al. 2008).

In the western North Pacific, most humpback whales winter and calve near Okinawa (Ryukyu Island) and Ogasawara (Bonin Islands) (Nishiwaki 1959; Rice 1989; Darling and Mori 1993). Calambokidis et al. (2008) also included the waters of Taiwan and the Mariana Islands as part of the humpback winter range. There is potential for the mixing of the western and eastern North Pacific humpback populations, as several individuals have been seen in the wintering areas of Japan and Hawaii in separate years (Darling and Cerchio 1993; Salden et al. 1999; Calambokidis et al. 2001, 2008). Whales from these wintering areas have been shown to travel to summer feeding areas in British Columbia (B.C.), Canada, and Kodiak Island, Alaska (Darling et al. 1996; Calambokidis et al. 2001), but feeding areas in Russian waters may be most important (Calambokidis et al. 2008). There appears to be a very low level of interchange between wintering and feeding areas in Asia and those in the eastern and central Pacific (Calambokidis et al. 2008).

During Japanese sighting surveys from 1994 to 2007, numerous humpback whales sightings were made off northern Japan, the Kuril Islands, and Kamchatka (Matsuoka et al. 2009). Sightings were reported for the months of April through September, with lowest densities in April and September (Matsuoka et al. 2009). In May and June, sightings were concentrated east of northern Japan; highest densities were reported for July and August off the Kuril Islands and Kamchatka (Mutsuoka et al. 2009). Humpback whales were encountered directly north of the proposed Shatsky Rise study area in May; some sightings reported in June and July were also near the study area (Matsuoka et al. 2009). In August, sightings were farther to the north (Matsuoka et al. 2009). Most of the animals in this population are on their way to northern feeding grounds in June and July; thus, few individuals are expected to occur within the proposed study area at the time of the surey.

Minke Whale

The minke whale has a cosmopolitan distribution that spans polar, temperate, and tropical regions (Jefferson et al. 2008). In the Northern Hemisphere, minke whales are usually seen in coastal areas, but can also be seen in pelagic waters during northward migrations in spring and summer, and southward migration in autumn (Stewart and Leatherwood 1985).

In the North Pacific, the summer range of the minke whale extends to the Chukchi Sea; in the winter, the whales move further south to within 2º of the equator (Perrin and Brownell 2002). Three stocks of minke whales are currently recognized in the North Pacific: the Sea of Japan/East China Sea, the rest of the western Pacific west of 180ºN, and the remainder of the Pacific (Donovan 1991). The current abundance estimate for the Northwest Pacific and Okhotsk Sea is 25,000 minkes (Buckland et al. 1992; IWC 2009).

The minke whale is a small baleen whale and tends to be solitary or in groups of 2–3, but can occur in much larger aggregations around prey resources (Jefferson et al. 2008). The small size, inconspicuous blows, and brief surfacing times of minke whales mean that they are easily overlooked in heavy sea states, although they are known to approach vessels in some circumstances (Stewart and Leatherwood 1985). Little is known about the diving behavior of minke whales, but they are not known to make prolonged deep dives (Leatherwood and Reeves 1983).

North Pacific minke whales are known to occur in the Yellow, East China and South China Seas (Parsons et al. 1995), as well as in the waters of the open Pacific (Hakamada et al. 2009). Minke whales have been hunted off Japan for many years (see IWC 2008). They are seen regularly during Japanese sighting surveys in the summer (Hakamada et al. 2009). They have been sighted near the Shatsky Rise survey area in the greatest numbers in May (Hakamada et al. 2009). During July and August, most minke whales will have already moved through the area on their annual northern migration, and numbers in the study area are expected to be low.

Bryde's Whale

Bryde's whale is found in tropical and subtropical waters throughout the world between 40ºN and 40ºS, generally in waters warmer than 20ºC, but at minimum 15ºC (Reeves et al. 1999; Kato 2002; Kanda et al. 2007). Long confused with sei whales, *Balaenoptera edeni* was named in 1913 and *B. brydei* was named in 1950, although it is still uncertain whether the two are distinct species or subspecies (Kato 2002). The smaller *B. edeni* (the pygmy Bryde's or Eden's whale) may be a distinct species from the larger *B. brydei* or Bryde's whale (Wada et al. 2003; Sasaki et al. 2006). The small form is known to occur in southwestern Japan, Hong Kong/Macau, and Australia, but this form has not been distinguished from the common Bryde's whale (Jefferson et al. 2008). Populations in the western North Pacific,

western South Pacific, eastern South Pacific, and eastern Indian Ocean currently show low levels of genetic interchange (Kanda et al. 2007).

Bryde's whales are known to occur in both shallow coastal and deeper offshore waters (Jefferson et al. 2008). Some populations show a general pattern of movement toward the equator in winter and toward higher latitudes in summer, though the locations of actual winter breeding grounds are unknown (Reeves et al. 1999; Kato 2002; Kanda et al. 2007). Bryde's whales are usually solitary or in pairs, although groups of 10–20 are known from feeding grounds (Jefferson et al. 2008). Wade and Gerrodette (1993) reported a mean group size of 1.7 for the ETP. The durations of Bryde's whale dives are 1–20 min (Cummings 1985).

In the western North Pacific, Bryde's whales occur off the Pacific coasts of Japan, Taiwan, and the Philippines (Kato 2002), in Hong Kong (Parsons et al. 1995; Jefferson and Hung 2007), as well as in the Yellow, East China, and South China Seas (Parsons et al. 1995; Chou 2004). Whales in the East China Sea and coastal waters of Kochi, Japan, differ from the whales in offshore waters of the western North Pacific, perhaps at the subspecific level (Yoshida and Kato 1999). However, the reclassification of Bryde's whales remains unresolved (Jefferson et al. 2008). Bryde's whales are hunted off the coast of Japan (see IWC 2008). The current population estimate for the western North Pacific is 20,501 (Kitakado et al. 2008; IWC 2009). Bryde's whales are seen regularly during Japanese summer sighting surveys (Shimada 2004; Hakamada et al. 2009). Near the Shatsky Rise survey area, sightings are highest during July and August (Shimada 2004; Hakamada et al. 2009).

Sei Whale

The sei whale is listed as ***endangered*** under the U.S. ESA and on the 2009 IUCN Red List of Threatened Species (IUCN 2009); it is listed in CITES Appendix I (UNEP-WCMC 2009) (Table 2). Sei whale populations were depleted by whaling, and their current status is generally uncertain (Horwood 1987). The global population is thought to be ~80,000 (Horwood 2002), with up to ~12,620 animals in the North Pacific (Tillman 1977). Although Hakamada et al. (2004) extrapolated an abundance estimate for the entire Northwest Pacific based on one part of that region, this estimate (68,000) has not yet been accepted (Reilly et al. 2008b). The sei whale is poorly known because of confusion with Bryde's whale and unpredictable distribution patterns, such that it may be common in an area for several years and then seemingly disappears (Schilling et al. 1992; Jefferson et al. 2008).

The distribution of the sei whale is not well known, but this whale is found in all oceans and appears to prefer mid-latitude temperate waters (Jefferson et al. 2008). Sei whales migrate from temperate zones occupied in winter to higher latitudes in the summer, where most feeding takes place (Gambell 1985a). In the North Pacific, the sei whale can be found across the Bering Sea and off the coasts of Japan and Korea in the summer. Its winter distribution is concentrated at about 20°N. No breeding grounds have been identified for sei whales; however, calving is thought to occur from September to March.

The sei whale is pelagic and generally not found in coastal waters (Harwood and Wilson 2001). It is found in deeper waters characteristic of the continental shelf edge region (Hain et al. 1985) and in other regions of steep bathymetric relief such as seamounts and canyons (Kenney and Winn 1987; Gregr and Trites 2001). On feeding grounds, sei whales associate with oceanic frontal systems (Horwood 1987) such as the cold eastern currents in the North Pacific (Perry et al. 1999a). Sei whales are frequently seen in groups of 2–5 (Jefferson et al. 2008), although larger groups sometimes form on feeding grounds (Gambell 1985a). Sei whales generally do not dive deeply, and dive durations are 15 min or longer (Gambell 1985a).

Sei whales are hunted off Japan (see IWC 2008). They are seen regularly during Japanese sighting surveys in the summer (Hakamada et al. 2009). Sei whales have been sighted in and near the Shatsky Rise survey area in greatest numbers in May, June, and July; in August, sightings occur farther to the north (Hakamada et al. 2009). During the summer, sei whales travel northward. The Shatksy Rise survey area is at the southern extent of the sei whale's range during the proposed study period. Thus, the sei whale is not expected to occur in high densities in the study area at the time of the proposed survey.

Fin Whale

The fin whale is widely distributed in all the world's oceans (Gambell 1985b), but typically occurs in temperate and polar regions from 20° to 70° north and south of the equator (Perry et al. 1999b). It is listed as ***endangered*** under the U.S. ESA and on the 2009 IUCN Red List of Threatened Species (IUCN 2009); it is listed in CITES Appendix I (UNEP-WCMC 2009) (Table 2). Northern and southern fin whale populations are distinct and are sometimes recognized as different subspecies (Aguilar 2002). Abundance estimates for the northern populations are 13,620–18,680 for the North Pacific (Ohsumi and Wada 1974), 30,000 for the central and northeastern Atlantic (IWC 2009), and 3200 for West Greenland (IWC 2009). Miyashita and Kato (2005 *in* Kato et al. 2005) provided an abundance estimate of 13,000 for the Sea of Okhotsk.

Fin whales occur in coastal, shelf, and oceanic waters. Sergeant (1977) proposed that fin whales tend to follow steep slope contours, either because they detect them readily or because biological productivity is high along steep contours because of tidal mixing and perhaps current mixing. They can be found as individuals or groups of 2–7, but can form much larger feeding aggregations, sometimes with humpback and minke whales (Jefferson et al. 2008). Foraging fin whales reach mean dive depths and times of 98 m and 6.3 min, respectively, while recorded mean dive depths and times for non-foraging fin whales in the Pacific are 59 m and 4.2 min, respectively (Croll et al. 2001). Dive depths of >150 m coinciding with the diel migration of krill were reported by Panigada et al. (1999).

The current distribution of fin whales in the western North Pacific is largely unknown. Fin whales undergo seasonal migrations, and are known to winter in the Yellow, East China, and South China Seas (Parsons et al. 1995; Rudoph and Smeenk 2002). A recent review of fin whale distribution in the North Pacific noted the lack of sightings across the pelagic waters between eastern and western winter areas (Mizroch et al. 2009). In the summer, fin whales are seen off northern Japan, the Kuril Islands, and Kamchatka (Matsuoka et al. 2009). During Japanese sightings surveys in the western North Pacific from 1994 to 2007, the fin whale was sighted more frequently than the blue, humpback or right whale (Matsuoka et al. 2009). Most sightings were made in July and August; sightings in August were concentrated towards the northern parts of the area (Matsuoka et al. 2009). During these sighting surveys, fin whales were seen in and near the proposed Shatsky Rise study area during May, June, and July; in August and September, fin whale sightings were farther to the noth (Matsuoka et al. 2009). Thus, fin whales could be encountered during the proposed seismic survey.

Blue Whale

The blue whale has a cosmopolitan distribution and tends to be pelagic, only coming nearshore to feed and possibly to breed (Jefferson et al. 2008). It is listed as ***endangered*** under the U.S. ESA and on the 2009 IUCN Red List of Threatened Species (IUCN 2009); it is listed in CITES Appendix I (UNEP-WCMC 2009) (Table 2). All blue whale populations have been exploited commercially, and many have been severely depleted as a result. Blue whale abundance has been estimated at 2300 for the Southern Hemisphere (IWC 2009), up to 1000 in the central and northeast Atlantic (Pike et al. 2009), and ~3500 in the eastern North Pacific (NMFS 1998).

Blue whales are typically found singly or in groups of two or three (Yochem and Leatherwood 1985; Jefferson et al. 2008). Matsuoka et al. (2009) reported a mean group size of 1.4 for the western North Pacific, and Wade and Gerrodette (1993) reported a mean group size of 1.5 for the ETP. Croll et al. (2001) reported mean dive depths and times of 140 m and 7.8 min for foraging blue whales, and 68 m and 4.9 min for non-foraging individuals. Dives of up to 300 m were recorded for tagged blue whales (Calambokidis et al. 2003).

Generally, blue whales are seasonal migrants between high latitudes in the summer, where they feed, and low latitudes in the winter, where they mate and give birth (Lockyer and Brown 1981). However, little information is available on blue whale wintering areas (Perry et al. 1999a). Some individuals may stay in low or high latitudes throughout the year (Reilly and Thayer 1990; Watkins et al. 2000b). Moore et al. (2002) reported that blue whale calls are received in the North Pacific year-round. Although it has been suggested that there are at least five subpopulations of blue whales in the North Pacific (NMFS 1998), analysis of blue whale calls monitored from the U.S. Navy Sound Surveillance System (SOSUS) and other offshore hydrophones (see Stafford et al. 1999, 2001, 2007; Watkins et al. 2000a; Stafford 2003) suggest that there are two separate populations—one in the eastern and one in the western North Pacific (Sears 2002).

The current distribution of blue whales in the western North Pacific is largely unknown. However, numerous blue whale sightings have been made in the western North Pacific during recent Japanese sighting surveys during 1994-2007 (Matsuoka et al. 2009). The highest blue whale densities were seen southeast of Kamchatka (Matsuoka et al. 2009). Most sightings were made in July and August; sightings in August were concentrated towards the northern parts of the area (Matsuoka et al. 2009). Blue whales were seen in and near the proposed Shatsky Rise survey area during May, June, and July; sightings in August and September were farther to the north (Matsuoka et al. 2009). Thus, it is possible that blue whales could be encountered at Shatsky Rise during the proposed seismic survey.

(2) Odontocetes

Sperm Whale

Sperm whales are the largest of the toothed whales, with an extensive worldwide distribution (Rice 1989). The species is listed as ***endangered*** under the U.S. ESA, but on a worldwide basis it is abundant and not biologically endangered. It is listed as ***vulnerable*** on the 2009 IUCN Red List of Threatened Species (IUCN 2009), and it is listed in CITES Appendix I (UNEP-WCMC 2009) (Table 2). There currently is no accurate estimate for the size of any sperm whale population (Whitehead 2002a). Best estimates probably are those of Whitehead (2002b), who provided a sperm whale population size estimate of 29,674 for the western North Pacific.

Sperm whale distribution is linked to social structure—mixed groups of adult females and juvenile animals of both sexes generally occur in tropical and subtropical waters, whereas adult males are commonly found alone or in same-sex aggregations, often occurring in higher latitudes outside the breeding season (Best 1979; Watkins and Moore 1982; Arnbom and Whitehead 1989; Whitehead and Waters 1990). Mature male sperm whales migrate to warmer waters to breed when they are in their late twenties (Best 1979). They spend periods of at least months on the breeding grounds, moving between mixed groups of 20–30 on average (Whitehead 1993, 2003). Mean group sizes were reported as 3.5 for the western North Pacific (Kato and Miyashita 1998) and 7.9 for the ETP (Wade and Gerrodette 1993).

Sperm whales generally are distributed over large areas that have high secondary productivity and steep underwater topography, in waters at least 1000 m deep (Jaquet and Whitehead 1996; Whitehead

2002a). They are often found far from shore, but can be found closer to oceanic islands that rise steeply from deep ocean waters (Whitehead 2002a). They can dive as deep as ~2 km and possibly deeper on rare occasions for periods of over 1 h; however, most of their foraging occurs at depths of ~300–800 m for 30–45 min (Whitehead 2003). During a foraging dive, sperm whales typically travel ~3 km horizontally and 0.5 km vertically (Whitehead 2003). Whales in the Galápagos Islands typically dove for ~40 min and then spent 10 min at the surface (Papastavrou et al. 1989).

In the western North Pacific, sperm whales are known to occur in the waters of Japan (Kato and Miyashita 1998; Hakamada et al. 2009), Hong Kong (Parsons et al. 1995; Jefferson and Hung 2007), the Philippines (Acebes et al. 2000 *in* Perrin et al. 2005; Acebes and Lesaca 2003), and Taiwan (Chou 2004). During winter, few sperm whales are sighted off the east coast of Japan (Kato and Miyashita 1998), but sperm whales are seen regularly during sighting surveys in the summer (Hakamada et al. 2009). They have been sighted in and near the Shatsky Rise survey area from May through August (Hakamada et al. 2009). Thus, sperm whales could be encountered during the proposed Shatsky Rise seismic program.

Pygmy and Dwarf Sperm Whales

Pygmy sperm whales (*Kogia breviceps*) and dwarf sperm whales (*K. sima*) are distributed widely throughout tropical and temperate seas, but their precise distributions are unknown as most information on these species comes from strandings (McAlpine 2002). They are difficult to sight at sea, perhaps because of their avoidance reactions to ships and behavior changes in relation to survey aircraft (Würsig et al. 1998). The two species are difficult to distinguish from one another when sighted (McAlpine 2002). During sighting surveys and, hence, in population and density estimates, the two species are most often categorized together as *Kogia* spp. (Waring et al. 2009).

Pygmy sperm whales may inhabit waters beyond the continental shelf edge, whereas dwarf sperm whales are thought to inhabit the shelf-edge and slope waters (Rice 1998). Also, the dwarf sperm whale may prefer warmer waters than the pygmy sperm whale (McAlpine 2002). Pygmy sperm whales feed mainly on various species of squid in the deep zones of the continental shelf and slope (McAlpine et al. 1997). Pygmy sperm whales occur in small groups of up to six, and dwarf sperm whales can form groups of up to 10 (Caldwell and Caldwell 1989). Wade and Gerrodette (1993) noted a mean group size of 1.7 for the dwarf sperm whale in the ETP.

Although there are few useful estimates of abundance for pygmy or dwarf sperm whales anywhere in their range, they are thought to be fairly common in some areas. In the western North Pacific, confirmed *Kogia* records exist for the East and South China seas off mainland China, Taiwan, Hong Kong, and the Philippines (Parsons et al. 1995; Zhou et al. 1995; Perrin et al. 2005; Chou 2004; Jefferson and Hung 2007). Although *Kogia* spp. have been seen during Japanese sighting surveys in the western North Pacific in August/September (Kato et al. 2005), to the best of our knowledge, there are no direct data available for the Shatsky Rise survey area with respect to *Kogia* spp. Given their habitat preferences, it is more likely that pygmy sperm whales rather than dwarf sperm whales would be encountered in the study area.

Cuvier's Beaked Whale

Cuvier's beaked whale is probably the most widespread of the beaked whales, although it is not found in polar waters (Heyning 1989). It is rarely observed at sea and is mostly known from strandings. It strands more commonly than any other beaked whale (Heyning 1989). Its inconspicuous blows, deep-diving behavior, and tendency to avoid vessels all help to explain the infrequent sightings (Barlow and

Gisner 2006). Adult males of this species usually travel alone, but these whales can be seen in groups of up to 15 individuals, with a mean group size of 2.3 (MacLeod and D'Amico 2006). Cuvier's beaked whale is an offshore species that feeds on fish and squid (Heyning 2002). Its dives generally last 30–60 min, but dives of 85 min have been recorded (Tyack et al. 2006). Wade and Gerrodette (1993) reported a mean group size of 2.2 for the ETP.

In the western Pacific, Cuvier's beaked whales are known to occur in the waters of Japan (Nishiwaki and Oguro 1972 *in* Wang et al. 1995) and parts of southeast Asia (Heyning 1989). They were also seen during Japanese sighting surveys in August/September in the western North Pacific (Kato et al. 2005). There is very little information on this species for the Shatsky Rise study area, but what is known of its distribution and habitat preferences suggests that it may occur there.

Baird's Beaked Whale

Baird's beaked whale has a fairly extensive range across the North Pacific north of 30°N, and strandings have occurred as far north as the Pribilof Islands (Rice 1986). This species is divided into three distinct stocks: Sea of Japan, Okhotsk Sea, and Bering Sea/eastern North Pacific (Balcomb 1989; Reyes 1991). Concentrations are thought to occur in the Sea of Okhotsk and Bering Sea (Rice 1998; Kasuya 2002a). The whales occur year-round in the Sea of Okhotsk and the Sea of Japan (Kasuya 2002a). Their abundance is estimated at 5029 for the Pacific coast of Japan, 1260 for the eastern Sea of Japan, and 660 for the southern Okhotsk Sea (Kasuya 2002a).

Baird's beaked whales sometimes are seen close to shore, but their primary habitat is over or near the continental slope and oceanic seamounts in waters 1000–3000 m deep (Jefferson et al. 1993; Kasuya and Ohsumi 1984; Kasuya 2002a). Off Japan and California, they primarily feed on benthic fishes and cephalopods, although pelagic fishes are also taken occasionally (Kasuya 2002a). Baird's beaked whales can stay submerged for up to 67 min, although most (66%) dives are <20 min long, and time at the surface is 1–14 min (Kasuya 2002a). They travel in groups of a few to several dozen (Balcomb 1989). Off Japan, they form groups of up to 30 individuals, although groups of 2 to 9 animals are seen most often (Kasuya 2002a). Wade et al. (2003) reported a mean group size of 10.8 for the ETP. There appears to be a calving peak in March and April (Jefferson et al. 1993).

Baird's beaked whales have been hunted for centuries in the far western North Pacific. Before 1840, the annual catch in Japan was <25 animals; after World War II, the fishery expanded to the entire northern Pacific, with a reported catch of over 300, but subsequently declined (Kasuya 2002a). Currently, Baird's beaked whales are hunted off the west coast of Japan in the summer; Kasuya (2002a) reported quotas of eight Baird's beaked whales for the Sea of Japan, two for the southern Okhotsk Sea, and 52 for the Pacific coast. Off Japan's Pacific coast, Baird's beaked whales start to appear in May, numbers increase over the summer, and decrease toward October (Kasuya 2002a). During this time, they are nearly absent in offshore waters (Kasuya 2002a). Kato et al. (2005) also reported the presence of Baird's beaked whales in the western North Pacific in August/September. Thus, it is possible that this species could be encountered at Shatsky Rise during the proposed seismic survey in summer.

Longman's Beaked Whale

Until very recently, Longman's beaked whale was thought to be extremely rare, and it was known only from two skulls (Pitman et al. 1987). Recent morphometric and genetic analyses of those two original specimens and an additional four specimens have allowed a more detailed characterization of the species (Dalebout et al. 2003). It seems likely that it is, in fact, the cetacean that has been seen in Indo-Pacific waters and called the "tropical bottlenose whale". Some authorities place the species in the genus

Mesoplodon, but there now seems to be sufficient information to afford it status as a separate genus (Dalebout et al. 2003). Records of this species exist within an area from 10ºS to 40ºN.

Longman's beaked whales have been sighted in waters with temperatures 21–31ºC and have been seen in the tropics every month of the year except June, indicating year-round residency (Pitman et al. 1999; Jefferson et al. 2008). Although widespread throughout the tropical Pacific, the species must still be considered rare because of a scarcity of sightings despite a great deal of survey effort (Pitman et al. 1999). Longman's beaked whales have been seen alone, but more commonly in groups of at least ten and up to 100, with an average group size of 15–20 (Jefferson et al. 2008). Pitman et al. (1999) reported a mean group size of 18.5 in the tropics. Dives are thought to last 18–33 min (Jefferson et al. 2008).

In eastern Asia, records for this species exist for Japan (Yamada et al. 2004), the Philippines (Acebes et al. 2005), and Taiwan (Yang et al. 2008). Kato et al. (2005) also reported on sightings of this species during Japanese surveys in the western North Pacific in August/September. Given that this species prefers tropical and sub-tropical waters, the Shatsky Rise survey area would be at the limit of its range. Thus, encounters with this species in the proposed study area are considered unlikely.

Mesoplodont Beaked Whales

Four species of mesoplodont whales may occur in deep waters of the Shatsky Rise study area: Blainville's, gingko-toothed, Stejneger's, and Hubb's beaked whales. No population estimates exist for any of these species for the western North Pacific.

Almost everything that is known regarding most mesoplodont species has come from stranded animals (Pitman 2002). The different mesoplodont species are difficult to distinguish in the field, and are most often categorized by genus during sighting surveys, resulting in density and population estimates for *Mesoplodon* spp. They are all thought to be deep-water animals, only rarely seen over the continental shelf. Typical group sizes range from one to six (Pitman 2002). Because of the scarcity of sightings, most are thought to be rare.

Blainville's beaked whale.—This species is found in tropical and temperate waters of all oceans (Jefferson et al. 2008). Blainville's beaked whale has the widest distribution throughout the world of all *Mesoplodon* species (Mead 1989). There is no evidence that Blainville's beaked whales undergo seasonal migrations. Blainville's beaked whales are most often found in singles or pairs, but also in groups of 3–7 (Jefferson et al. 2008).

Like other beaked whales, Blainville's beaked whales are generally found in deep waters 200 m to 1400 m deep (Gannier 2000; Jefferson et al. 2008). Maximum dive depths have been reported as 1251 m (Tyack et al. 2006) and 1408 m (Baird et al. 2006), and dives have lasted as long as 54 min (Baird et al. 2006) to 57 min (Tyack et al. 2006). However, they also can occur in coastal areas and have been known to spend long periods of time at depths <50 m (Jefferson et al. 2008).

In Asia, sighting records exist for Blainville's beaked whale for the East China Sea off mainland China and for the Philippines (Perrin et al. 2005). They are also known to occur off Taiwan (Zhou et al. 1995; Chou 2004; Perrin et al. 2005). To the best of our knowledge there are no published sighting records near the Shatsky Rise, but this area is believed to be within the distribution range for this species (Jefferson et al. 2008).

Ginkgo-toothed beaked whale.—This species is only known from stranding records (Mead 1989; Jefferson et al. 2008). In the South Pacific Ocean, it has stranded in New South Wales, Australia, and the North Island and Chatham Islands, New Zealand (Mead 1989; Baker and van Helden 1999). The ginkgo-

toothed whale is hypothesized to occupy tropical and warm temperate waters of the Indian and Pacific oceans (Pitman 2002). Its occurrence has been confirmed in the Yellow and East China seas off mainland China (Perrin et al. 2005), as well as off Taiwan (Yang 1976 *in* Zhou et al. 1995; Chou 2004; Wang and Yang 2006). The distributional range of this species suggests that any occurrence in the study area would be rare.

Stejneger's beaked whale.—Stejneger's beaked whale occurs in subarctic and cool temperate waters of the North Pacific (Mead 1989). Most records are from Alaskan waters, and the Aleutian Islands appear to be its center of distribution (Mead 1989). The species typically occurs in groups of 3–4, ranging to ~15 (Reeves et al. 2002). It is known to occur in the Sea of Japan and possibly the southern Okhotsk Sea (MacLeod et al. 2006). Stejneger's beaked whale was also seen during Japanese sighting surveys in the western North Pacific during August/September (Kato et al. 2005). Seasonal peaks in strandings along the western coast of Japan suggest that this species may migrate north in the summer from the Sea of Japan (Mead 1989). However, what is known about its range suggests that this species would be unlikely to occur in the Shatsky Rise study area during the summer.

Hubb's beaked whale.—This species occurs in temperate waters of the North Pacific (Mead 1989). Most of the stranding records are from California, but at least seven strandings have been recorded along the B.C. coast as far north as Prince Rupert (Houston 1990; Willis and Baird 1998). Its distribution appears to be correlated with the deep subarctic current (Mead et al. 1982). The range of this species is believed to be continuous across the North Pacific (Macleod et al. 2006), although this has yet to be substantiated because very few direct at-sea observations exist. Hubb's beaked whale was seen during Japanese sighting surveys in the western North Pacific during August/September (Kato et al. 2005). This species has been taken in Japanese hunts for small cetaceans and sold at markets (Dalebout et al. 2001).

Rough-toothed Dolphin

The rough-toothed dolphin is widely distributed around the world, but mainly occurs in tropical and warm temperate waters (Miyazaki and Perrin 1994). Rough-toothed dolphins generally occur in deep, oceanic waters, but can be found in shallower coastal waters in some regions (Jefferson et al. 2008). Rough-toothed dolphins are deep divers and can dive for up to 15 min (Jefferson et al. 2008). They usually form groups of 10–20, but aggregations of hundreds have been seen (Jefferson et al. 2008). Wade and Gerrodette (1993) reported a mean group size of 14.7 for the ETP.

In the Pacific, rough-toothed dolphins occur from central Japan and northern Australia to Baja California, Mexico, and southern Peru (Jefferson 2002). Rough-toothed dolphins are also known to occur in the Philippines (Acebes et al. 2000 *in* Perrin et al. 2005; Acebes and Lesaca 2003; Perrin et al. 2005) and in the East and South China seas (Parsons et al. 1995; Zhou et al. 1995; Chou 2004; Perrin et al. 2005; Jefferson and Hung 2007). There are no estimates of abundance for rough-toothed dolphins in the western Pacific. Rough-toothed dolphins were seen during Japanese sighting surveys in the western North Pacific during August/September (Kato et al. 2005). In Japan, rough-toothed dolphins have been taken in drive and harpoon hunts (Miyazaki and Perrin 1994). As the Shatsky Rise study area is known to be within this species' range, the rough-toothed dolphin may be encountered during the proposed survey.

Common Bottlenose Dolphin

The bottlenose dolphin is distributed worldwide. It is found mainly where surface temperatures range from 10–32ºC (Reeves et al. 2002). Generally, there are two distinct bottlenose dolphin types: a shallow water type, mainly found in coastal waters, and a deep water type, mainly found in oceanic waters (Duffield et al. 1983; Hoelzel et al. 1998; Walker et al. 1999). As well as inhabiting different

areas, these ecotypes differ in their diving abilities (Klatsky 2004) and prey types (Mead and Potter 1995). Bottlenose dolphins have been reported to regularly dive to depths >450 m for periods of >5 min (Klatsky 2004), and even down to depths of 600–700 m for up to 12 min (Klatsky et al. 2005). Mean group sizes have been reported as 66.9 for the western North Pacific (Miyashita 1993a), 22–24 for the ETP (Wade and Gerrodette 1993; Smith and Whitehead 1999).

In the western Pacific, the bottlenose dolphin is distributed from Japan to Australia and New Zealand. In Japan, bottlenose dolphins are hunted by whalers in drive and harpoon fisheries (Kasuya 2007). Bottlenose dolphins are also known to occur in the Philippines and the Yellow, East, and South China seas off China and Taiwan (Perrin et al. 2005), and Hong Kong (Parsons et al. 1995; Jefferson and Hung 2007). It has been estimated that 168,000 bottlenose dolphins inhabit the western North Pacific (Miyashita 1993a). Bottlenose dolphins were regularly seen during Japanese summer sighting surveys in the western North Pacific (Miyashita 1993a). They were seen in groups of 1 to 500 animals and were often sighted in mixed schools with other dolphin species (Miyashita 1993a). Occurrence in the western North Pacific was patchy, but high densities were generally observed in coastal waters as well as in some offshore areas (Miyashita 1993a). Bottlenose dolphins have been sighted in the proposed Shatsky Rise study area in August, and near the study area in June and July (Miyashita 1993a).

Pantropical Spotted Dolphin

The pantropical spotted dolphin can be found throughout tropical and some subtropical oceans of the world (Perrin and Hohn 1994). The southernmost limit of its range is ~40°S (Perrin 2002a). There are two forms of pantropical spotted dolphin—coastal and offshore—although the coastal form occurs mainly in the ETP from Baja California to South America (Jefferson et al. 2008). In the ETP, this dolphin is associated with warm (>25ºC) tropical surface water (Au and Perryman 1985; Reilly 1990; Reilly and Fiedler 1994; Reeves et al. 1999). The offshore form inhabits tropical, equatorial, and southern subtropical water masses (Perrin 2002a). This species is found primarily in deeper waters, and rarely over the continental shelf or continental shelf edge (Davis et al. 1998).

Pantropical spotted dolphins are extremely gregarious, forming groups of hundreds or even thousands. In the western North Pacific, groups of 3 to 2500 striped dolphins were seen, and the mean group size was 226 (Miyashita 1993a). Wade and Gerrodette (1993) reported a mean group size of 149.4 for the western/southern stock in the ETP. Pantropical spotted and spinner dolphins are commonly seen together in mixed-species groups, e.g., in the ETP (Au and Perryman 1985), off Hawaii (Psarakos et al. 2003), and off the Marquesas Archipelago (Gannier 2002).

In the western Pacific, pantropical spotted dolphins occur from Japan south to Australia; they have been hunted in drive fisheries off Japan for decades (Kasuya 2007). Pantropical spotted dolphins are also known to occur in the Philippines and in the East and South China seas off China (Perrin et al. 2005), in Taiwan (Parsons et al. 1995; Zhou et al. 1995; Chou 2004), and off Hong Kong (Parsons et al. 1995; Jefferson and Hung 2007). Their abundance in the western North Pacific has been estimated at 438,000 (Miyashita 1993a). They were regularly seen during Japanese summer sighting surveys in the western North Pacific (Miyashita 1993a). Densities were highest in offshore waters between 30ºN and 37ºN (Miyshita 1993a). Pantropical spotted dolphins have been sighted in the proposed Shatsky Rise study area in June, August, and September; survey effort was low in July (Miyashita 1993a).

Spinner Dolphin

The spinner dolphin is distributed in oceanic and coastal tropical waters between 40ºN and 40ºS (Jefferson et al. 2008). In the Pacific, two subspecies of spinner dolphin occur in the western Pacific: the

widespread, offshore spinner dolphin (*Stenella longirostris longirostris*) and the dwarf spinner dolphin (*S. l. roseiventris*). There is little or no genetic interchange between the two subspecies (Dizon et al. 1991). *S. l. longirostris* feeds on small mesopelagic fish and squid, whereas *S. l. roseiventris* preys on benthic and coral reef fishes and invertebrates (Perrin et al. 1999). *S. l. longirostris* occurs in the deep inner waters of the Philippines as well as Japan, whereas *S. l. roseiventris* inhabits the shallow waters of inner southeast Asia (Perrin et al. 1999).

Kato et al. (2005) noted that this species was seen during Japanese sighting surveys in the western North Pacific in August/September. Spinner dolphins are also known to occur in the East and South China seas off China and Taiwan (Perrin et al. 2005) and Hong Kong (Parsons et al. 1995; Jefferson and Hung 2007). To the best of our knowledge, there are no known estimates of abundance near the Shatsky Rise. However, the study area is within the known range of the offshore subspecies of spinner dolphins.

Striped Dolphin

The striped dolphin has a cosmopolitan distribution in tropical to warm temperate waters (Perrin et al. 1994a) and is generally seen south of 43ºN (Archer 2002). It is typically found in waters outside the continental shelf and is often associated with convergence zones and areas of upwelling (Archer 2002). Striped dolphins are fairly gregarious (groups of 20 or more are common) and active at the surface (Whitehead et al. 1998). Miyashita (1993a) reported groups as large as 1500 animals and a mean group size of 121.4 for the western North Pacific. Mean group size was reported as 60.9 for the ETP (Wade and Gerrodette 1993) and 50 for the Galápagos Islands (Smith and Whitehead 1999).

In the western North Pacific, striped dolphins are known to occur in the Philippines (Perrin et al. 2005), in the East and South China seas off China and Taiwan (Parsons et al. 1995; Zhou et al. 1995; Chou 2004; Perrin et al. 2005), Hong Kong (Parsons et al. 1995; Jefferson and Hung 2007), and Japan (Miyashita 1993a). In Japan, striped dolphins have been hunted in drive and harpoon fisheries for many decades (Kasuya 2007). The abundance estimate for striped dolphins in the western North Pacific is estimated at 570,000 (Miyashita 1993a). The striped dolphin was one of the most common dolphin species seen during Japanese summer sighting surveys in the western North Pacific (Miyashita 1993a). During these surveys, densities were highest in offshore areas between 35ºN and 40ºN, and in coastal waters of southeastern Japan (Miyashita 1993a). Striped dolphins were seen in the proposed Shatsky Rise study area in July, August, and September; survey effort in June was limited (Miyashita 1993a).

Fraser's Dolphin

Fraser's dolphin is a tropical species found between 30°N and 30°S (Dolar 2002). It only occurs rarely in temperate regions, and then only in relation to temporary oceanographic anomalies such as El Niño events (Perrin et al. 1994b). The species typically occurs in deep, oceanic waters. In the ETP, most sightings were 45–100 km from shore in waters 1500–2500 m deep (Dolar 2002). Off Huahine and Tahiti (Society Islands), it was observed in waters 500–1500 m deep (Gannier 2000).

Fraser's dolphins travel in groups ranging from just a few animals to 100 or even 1000 (Perrin et al. 1994b). Wade and Gerrodette (1993) reported a mean group size of 395 for the ETP. Fraser's dolphins were seen during Japanese sighting surveys in the western North Pacific during August/September (Kato et al. 2005). Fraser's dolphins are also known to occur in the Philippines and in the East and South China seas off China and Taiwan (Perrin et al. 2005), as well as Hong Kong (Parsons et al. 1995; Jefferson and Hung 2007). In the eastern Sulu Sea adjacent to the Philippines, abundance is estimated at 8700 (Dolar 1999 *in* Perrin et al. 2003). Given its habitat preferences, the Shatsky Rise area is probably at the

northern limit of the Fraser's dolphin's range. Therefore, it seems likely that any occurrence in the study area would be rare.

Short-beaked Common Dolphin

The common dolphin is found in tropical and warm temperate oceans around the world (Perrin 2002b). It ranges as far south as 40°S in the Pacific Ocean, is common in coastal waters 200–300 m deep, and is also associated with prominent underwater topography, such as seamounts (Evans 1994). There are two species of common dolphins: the short-beaked common dolphin (*Delphinus delphis*) and the long-beaked common dolphin (*D. capensis*). The short-beaked common dolphin is found in offshore waters, and the long-beaked common dolphin is more prominent in coastal areas. Off northern New Zealand, the short-beaked common dolphin is generally seen at a mean distance <10 km from shore in the summer, but animals move further offshore in winter (Neumann 2001).

Common dolphins often travel in fairly large groups; schools of hundreds or even thousands are common. Smith and Whitehead (1999) noted that common dolphins were frequently seen in waters near the Galápagos Islands, with a mean group size of 125. Wade and Gerrodette reported a mean group size of 472.8 in the southern portion of the ETP.

There are no abundance estimates for *Delphinus* for the western Pacific. During Japanese sighting surveys in the western North Pacific in August/September, both long- and short-beaked common dolphins have been seen (Kato et al. 2005). As the short-beaked common dolphin is found in offshore waters, it is the most likely species of *Delphinus* to occur at the Shatksy Rise study area. Besides Japan, short-beaked common dolphins have also been reported to occur off Taiwan (Rudolph and Smeenk 2002).

Pacific White-sided Dolphin

The Pacific white-sided dolphin is found throughout the temperate North Pacific, in a relatively narrow distribution between 38°N and 47°N (Brownell et al. 1999). From surveys conducted in the North Pacific, Buckland et al. (1993) estimated that there were a total of 931,000 Pacific white-sided dolphins, and Miyashita (1993b) estimated an abundance of 988,000.

The species is common both on the high seas and along the continental margins (see Leatherwood et al. 1984; Dahlheim and Towell 1994; Ferrero and Walker 1996). Pacific white-sided dolphins often associate with other species, including cetaceans (especially Risso's and northern right whale dolphins; Green et al. 1993), pinnipeds, and seabirds. Pacific white-sided dolphins are very inquisitive and may approach stationary boats (Carwardine 1995).

Pacific-white sided dolphins have been seen during Japanese sighting surveys in the western North Pacific in August/September (Kato et al. 2005). During the 1970s and 1980s, Pacific white-sided dolphins were often killed as bycatch in the high-seas drift gillnet fisheries of the western North Pacific. Those fisheries ceased to operate following the United Nations moratorium in 1993. Although the estimates of abundance and levels of removal are not very precise, the number of Pacific white-sided dolphins in the western North Pacific was probably not highly depleted as a result of that bycatch (Hobbs and Jones 1993). Pacific white-sided dolphins are known to occur in the Shatsky Rise study area (Buckland et al 1993).

Northern Right Whale Dolphin

The northern right whale dolphin is found in cool temperate and sub-arctic waters of the North Pacific, ranging from 30°N to 50°N (Reeves et al. 2002). Their abundance has been estimated at 307,000 (Miyashita 1993b). In the North Pacific Ocean, the northern right whale dolphin is one of the most

common marine mammal species, occurring primarily in shelf and slope waters ~100 m to >2000 m deep (see Green et al. 1993; Barlow 2003; Carretta et al. 2007). The northern right whale dolphin does, however, come closer to shore where there is deep water, such as over submarine canyons (Carwardine 1995; Reeves et al. 2002). Northern right whale dolphins are gregarious, and groups of several hundred to over a thousand dolphins are not uncommon (Reeves et al. 2002). They are often seen in mixed-species schools with Pacific white-sided dolphins.

Northern right whale dolphins were seen during Japanese sighting surveys in the western North Pacific in August/September (Kato et al. 2005). Like Pacific white-sided dolphins, northern right whale dolphins were killed in large numbers as bycatch in the high-seas drift gillnet fisheries of the western North Pacific. It seems likely that the number of northern right whale dolphins was noticeably reduced in this region as a result. Although the magnitude of this reduction is uncertain, Mangel (1993) estimates that it is likely to have been 30% or less of the pre-exploitation numbers. Northern right whale dolphins are known to occur near the Shatsky Rise and are most likely to be encountered in the northern half of the study area (Buckland et al. 1993).

Risso's Dolphin

Risso's dolphin is primarily a tropical and mid-temperate species distributed worldwide. It occurs between 60ºN and 60ºS, where surface water temperatures are at least 10ºC (Kruse et al. 1999). In the northern Gulf of Mexico, Risso's dolphin usually occurs over steeper sections of the upper continental slope (Baumgartner 1997) in waters 150–2000 m deep (Davis et al. 1998). In Monterey Bay, California, it is most numerous where there is steep bottom topography (Kruse et al. 1999). Risso's dolphins occur individually or in small to moderate-sized groups, normally ranging from 2 to <250. The majority of groups consist of <50 (Kruse et al. 1999; Miyashita 1993a). In the western North Pacific, Miyashita (1993a) reported groups of 1 to 200 individuals and a mean group size of 32.6. Wade and Gerrodette (1993) reported a mean group size of 12 in the ETP.

In the western Pacific, Risso's dolphins range from the Kuril Islands to New Zealand and Australia. In Japan, Risso's dolphins are hunted in small cetacean drive and hand harpoon fisheries, as well as small-type whaling operations (Kasuya 2007). Risso's dolphins are also known to occur in the Philippines, off mainland China in the Yellow, East, and South China seas (Perrin et al. 2005), and around Taiwan and Hong Kong (Parsons et al. 1995). The abundance in the western North Pacific has been estimated at 838,000 (Miyashita 1993a). Risso's dolphins were regularly seen during Japanese summer sighting surveys in the western North Pacific (Miyashita 1993a). Occurrence was patchy, but high densities were observed in coastal waters, between 148ºE–157ºE, and east of 162ºE (Miyashita 1993a). Risso's dophins have been sighted in the proposed Shatsky Rise study area in August and September; effort in June and July was low, but they were also sighted near the study area during those months (Miyashita 1993a).

Melon-headed Whale

The melon-headed whale is a pantropical and pelagic species that occurs mainly between 20ºN and 20ºS in offshore waters (Perryman et al. 1994). Melon-headed whales tend to occur in groups of 100–500, but have also been seen in groups of up to 2000 (Jefferson et al. 2008). Wade and Gerrodette (1993) reported a mean group size of 199 for the ETP. Melon-headed whales are commonly seen in mixed groups with other cetaceans (Jefferson and Barros 1997).

Melon-headed whales have been seen during Japanese sighting surveys in the western North Pacific in August/September (Kato et al. 2005). In the western North Pacific, melon-headed whales are

known to occur off mainland China in the East and South China seas, off Taiwan, and in the Philippines (Perrin et al. 2005). There is little information on abundance for this species near the Shatsky Rise. The study area is near the northern limit of its range; therefore, any occurrence would likely be rare.

Pygmy Killer Whale

The pygmy killer whale is distributed throughout tropical and subtropical oceans worldwide (Ross and Leatherwood 1994; Donahue and Perryman 2002). In warmer water, it is usually seen close to the coast (Wade and Gerrodette 1993), but it is also found in deep waters. In Hawaiin waters, the pygmy killer whale is found in nearshore waters, but not in the offshore waters (Barlow 2006). In the Marquesas, it was sighted in water 100 m deep (Gannier 2002). Pygmy killer whales tend to travel in groups of 15–50, although herds of a few hundred have been sighted (Ross and Leatherwood 1994). Wade and Gerrodette (1993) reported a mean group size of 27.9 in the ETP.

In the Northwest Pacific, the pygmy killer whale is frequently sighted off Hawaii and Japan (Donahue and Perryman 2002). Kato et al. (2005) reported the occurrence of this species during Japanese sighting surveys in the western North Pacific in August/September. The pygmy killer whale is also known to occur off mainland China in the East China Sea (Perrin et al. 2005), in Taiwan (Zhou et al. 1995; Chou 2004; Wang and Yang 2006), and in the Philippines (Perrin et al. 2005). There is little information on abundance for this species near the Shatsky Rise area. In general, pygmy killer whales are uncommon and are unlikely to be encountered during the proposed seismic survey.

False Killer Whale

The false killer whale is found in all tropical and warmer temperate oceans, especially in deep, off-shore waters (Odell and McClune 1999). However, it is also known to occur in nearshore areas (e.g., Stacey and Baird 1991). False killer whales travel in pods of 20–100 (Baird 2002), although groups of several hundred are sometimes observed. Groups of 1–40 animals were mostly seen during sighting surveys in the western North Pacific, although one group of ~500 animals was also sighted (Miyashita 1993a). Mean group sizes have been reported as 32.2 for the western North Pacific (Miyashita 1993a) and 11.4 for the ETP (Wade and Gerrodette 1993).

Nothing is known of the stock structure of false killer whales in the North Pacific Ocean (Miyashita 1993a). In the western Pacific, the false killer whale is distributed from Japan to Australia. The false killer whale is hunted in Japan (Kasuya 2007). It is also known to occur in the Philippines and in the Yellow, East and South China seas off China and Taiwan (Perrin et al. 2005), and Hong Kong (Parsons et al. 1995; Jefferson and Hung 2007). The abundance estimate for the western North Pacific is 16,000 (Miyashita 1993a). False killer whales have been seen during Japanese summer sighting surveys (Miyashita 1993a). Distribution was patchy, with several high-density areas in offshore waters (Miyashita 1993a). False killer whales have been sighted in the proposed Shatsky Rise study area in August and September; survey effort was low in June and July, but animals were also seen near the study area during those months (Miyashita 1993a).

Killer Whale

The killer whale is cosmopolitan and globally fairly abundant; it has been observed in all oceans of the world (Ford 2002). It is very common in temperate waters, and also frequents tropical waters, at least seasonally (Heyning and Dahlheim 1988; Reeves et al. 1999). High densities of the species occur in high latitudes, especially in areas where prey is abundant. Although resident in some parts of its range, the

killer whale can also be transient. Killer whale movements generally appear to follow the distribution of their prey, which includes marine mammals, fish, and squid. Killer whales are large and conspicuous, often traveling in close-knit matrilineal groups of a few to tens of individuals (Dahlheim and Heyning 1999). Wade and Gerrodette (1993) reported a mean group size of 5.4 in the ETP.

Very little is known about killer whale abundance and distribution in the western Pacific Ocean. Miyashita and Kato (2005 *in* Kato et al. 2005) provided an abundance estimate of 720 for the Sea of Okhotsk. Kato et al. (2005) reported sightings of this species during Japanese sighting surveys in the western North Pacific in August/September. Killer whales are also known to occur off China in the Yellow and East China seas (Zhou et al. 1995; Perrin et al. 2005), off Taiwan (Zhou et al. 1995; Chou 2004; Chou et al. 2007), and in the Philippines (Perrin et al. 2005). It is possible that killer whales could be encountered during the Shatsky Rise survey.

Short-finned Pilot Whales

The short-finned pilot whale is found in tropical and warm temperate waters (Olson and Reilly 2002); it is seen as far south as ~40ºS, but is more common north of ~35ºS (Olson and Reilly 2002). Pilot whales occur on the shelf break, over the slope, and in areas with prominent topographic features; they are usually seen in groups of 20–90 (Olson and Reilly 2002). In the western North Pacifc, Miyashita (1993a) reported sightings of 10–300 animals, although most sightings were of groups with <100 animals. Mean group sizes have been reported as 49.8 for the western North Pacific (Miyashita 1993a) and 18.3 for the ETP (Wade and Gerrodette 1993). Long-finned pilot whales outfitted with time-depth recorders dove to depths up to 828 m, although most of their time was spent above depths of 7 m (Heide-Jørgensen et al. 2002). The species' maximum recorded dive depth is 971 m (Baird pers. comm. *in* DoN 2005).

In the western North Pacific, short-finned pilot whales are known to occur off mainland China in the South China Sea (Perrin et al. 2005), Taiwan (Miyashita et al. 1995 *in* Zhou et al. 1995; Chou 2004), the Philippines (Acebes et al. 2000 *in* Perrin et al. 2005; Acebes and Lesaca 2003; Perrin et al. 2005), and Japan (Miyashita 1993a). In Japan, they are taken by whalers in the drive fishery (Kasuya 2007). The abundance of short-finned pilot whales has been estimated at 53,000 for the western North Pacific (Miyashita 1993a). Stock structure of short-finned pilot whales has not been adequately studied in the North Pacific, except in Japanese waters, where two stocks have been identified based on pigmentation patterns and head shape differences of adult males (Kasuya et al. 1988). The southern stock of short-finned pilot whales has been observed during Japanese summer sightings surveys (Miyashita 1993a). Distribution of short-finned pilot whales in the western North Pacific was patchy, but high densities were observed in coastal waters of central and southern Japan and in some areas offshore (Miyashita 1993a). Short-finned pilot whales have also been seen in the proposed Shatsky Rise survey area in August and September; survey effort in June and July was low, but animals were also seen near the study area during those months (Miyashita 1993a).

Dall's Porpoise

Dall's porpoise is only found in the North Pacific and adjacent seas. It is widely distributed across the North Pacific over the continental shelf and slope waters, and over deep (>2500 m) oceanic waters (Hall 1979), ranging from ~32ºN to 65ºN (Reeves et al. 2002). In general, this species is common throughout its range (Buckland et al. 1993). Dall's porpoises usually occur in small groups of 2 to 12 individuals, characterized by fluid associations (Reeves et al. 2002). Dall's porpoises are fast-swimming and active porpoises, and readily approach vessels to ride the bow wave.

Buckland et al. (1993) provided an abundance estimate of 1.3 million Dall's porpoises for the North Pacific, and Miyashita (1991) estimated the abundance in the Sea of Okhotsk at 443,000. In the western North Pacific, there are two different color morphs which are also considered sub-species: the *truei*-type and the *dalli*-type. They can be distinguished from each other by the extent of their white thoracic patches—the *truei*-type has a much broader patch, which extends nearly the length of the body. They were one of the most common cetaceans in the bycatch of the central and western North Pacific high-seas driftnet fisheries, but that source of mortality is not thought to have substantially depleted their abundance in the region (Hobbs and Jones 1993). Currently, Dall's porpoises are hunted using hand harpoons by Japanese whalers, with annual catch quotas of 17,300 animals from stocks which summer in the Okhotsk Sea (Kasuya 2007). Dall's porpoise (of the the *dalli*-type) which are known to occur at Shatsky Rise during summer are from a different stock than those which summer in the Okhotsk Sea.

(3) Pinnipeds

Northern Fur Seal

The northern fur seal is endemic to the North Pacific Ocean, and it occurs from southern California to the Bering Sea, the Okhotsk Sea, and Honshu Island, Japan. Two stocks are recognized, the Eastern Pacific and the San Miguel Island stocks. The Eastern Pacific stock ranges from the Pribilof Islands and Bogoslof Island in the Bering Sea during summer to the Channel Islands in Southern California during winter. The worldwide population of northern fur seals has declined from a peak of ~2.1 million in the 1950s to ~1.1 million in 2004-2005 (Gelatt and Lowry 2008). The population estimate for the eastern Pacific stock in 2008 was ~665,550 (Angliss and Allen 2009).

During the breeding season, 74% of the worldwide population of northern fur seals inhabits the Pribilof Islands in the southern Bering Sea (Lander and Kajimura 1982). A small percentage of seals breed at San Miguel Island off southern California. When not on rookery islands, northern fur seals are primarily pelagic but occasionally haul out on rocky shorelines. During the breeding season, adult males usually come ashore in May–August and may sometimes be present until November, and adult females are found ashore from June to November (Carretta et al. 2007). After reproduction, northern fur seals spend the next 7–8 months feeding at sea (Roppel 1984). Once weaned, juveniles spend 2–3 years at sea before returning to the rookeries. During that time, animals may migrate off Japan and California. The southern extent of the migration is about 35ºN. Northern fur seals have been sighted in the Shatsky Rise area (Buckland et al. 1993). However, it is likely that any occurrence at Shatsky Rise would be rare; if they do occur, only juveniles would be expected to occur there at that time of year.

Seabirds

Only one ESA-listed seabird species, the endangered short-tailed albatross (*Phoebastria albatrus*), could occur in or near the proposed study area.

(1) Short-tailed Albatross

Historically, millions of short-tailed albatrosses bred in the western North Pacific Ocean on islands off the coast of Japan. This species was the most abundant albatross in the North Pacific. However, the entire population was nearly extirpated during the last century by feather hunters at Japanese breeding colonies. In addition, the breeding grounds of the remaining birds were threatened by volcanic eruptions in the 1930s; this species was believed to be extinct in 1949 until it was rediscovered in 1951 (BirdLife International 2009). Thus, the short-tailed albatross is currently listed as ***endangered*** under the ESA and

is designated as ***vulnerable*** on the 2009 IUCN Red List of Threatened Species (IUCN 2009). However, this population is increasing, and the most recent population estimate is 2406 individuals (USFWS 2008). Current threats to this population include volcanic activity on Torishima, commercial fisheries, and pollutants (USFWS 2008).

Currently, nearly all short-tailed albatrosses breed on two islands off the coast of Japan—Torishima and Minami-kojima (UWFWS 2008; BirdLife International 2009). Single nests have been found in recent years on other islands, including Kita-Kojima, Senkaku; Yomejima Island; and Midway Island, Hawaii (USFWS 2008). During the breeding season (December to May), the highest densities are found around Japan (BirdLife International 2009); parents forage primarily off the east coast of Honshu Island, where the warm Kuroshio and the cold Oyashio currents meet (USWS 2008).

During the non-breeding season, short-tailed albatrosses roam much of the North Pacific Ocean; females spend more time offshore of Japan and Russia, while males and juveniles spend more time around the Aleutian Islands and Bering Sea (Suryan et al. 2007). Post-breeding dispersal occurs from April through August (USWFS 2001). After leaving the breeding areas, short-tailed albatrosses seem to spend the majority of time within the exclusive economic zones of Japan, Russia, and the U.S. (Aleutian Islands and Bering Sea) (Suryan et al. 2007). Thus, they are considered a continental shelf-edge specialist (Piatt et al. 2006). However, Suryan et al. (2006) reported that short-tailed albatrosses occasionally transit the northern boundary of the Kuroshio Extension in May while en route to the Aleutians and Bering Sea, but that they do not spend much time in the area. Thus, some sightings of short-tailed albatrosses have been reported near the study area (USWFS 2001, 2008; Suryan et al. 2006, 2007). Given the relatively small population size, the large pelagic range of this species, and the far offshore location of the study area, the occurrence of short-tailed albatrosses in the study area would be considered rare.

Sea Turtles

Five species of sea turtle may occur in the Shatsky Rise study area. In order of decreasing likelihood they are: the loggerhead (*Caretta caretta*), leatherback (*Dermochelys coriacea*), olive ridley (*Lepidochelys olivacea*), green (*Chelonia mydas*), and hawksbill (*Eretmochelys imbricata*) turtles (Chan et al. 2007). Loggerhead and leatherback turtles can spend substantial amounts of time offshore during migrations or feeding between breeding seasons, including the North Pacific and specifically in the vicinity of Shatsky Rise. Olive ridley turtles tend to remain in coastal areas or offshore at lower latitudes than the Shatsky Rise; however, this species is widespread and little is known of its offshore habits. Green and hawksbill turtles are unlikely to inhabit the Shatsky Rise region in favor of more tropical latitudes. All sea turtle species have special conservation status with the IUCN and under the U.S. ESA.

(1) Loggerhead turtle

The loggerhead sea turtle is listed as threatened under the ESA, primarily because of recent population declines from direct take, incidental capture in various fisheries, and the alteration and destruction of its coastal nesting habitat (NMFS 2002). It is listed as endangered on the 2009 IUCN Red List of Threatened Species (IUCN 2009) and in Appendix I of CITES (UNEP-WCMC 2009). The global loggerhead population is estimated to include 43,320 to 44,560 nesting females (Spotila 2004).

The loggerhead turtle is widely distributed, generally occurring in coastal tropical and subtropical waters around the world. Loggerhead nests in the Pacific Ocean basin are restricted to the western region, principally in Japan and Australia (or New Caledonia) where stocks are genetically distinct (NMFS and USFWS 2007a). They also nest in China (EuroTurtle 2008). In Japan, loggerheads nest on Honshu,

Shikoku, Kyushu, and the Ryukyu Islands (Sea Turtle Association of Japan 2010). Surveys for nesting turtles conducted on Okinawa and adjacent islands of the central Ryukyus between 1995 and 1996 found 47 clutches belonging to loggerheads (Kikukawa et al. 1996). Loggerhead nesting along the Japanese coast occurs from April to August, with a peak in July. Nesting beaches are located at least 1200 km from the proposed survey site at Shatsky Rise.

Loggerheads typically spend two to six years foraging at sea before returning to coastal areas to breed (NMFS 2002). During their sea-going phase, they undertake long migrations and at times occur far offshore and far from their breeding grounds. For example, some loggerheads seen feeding along Baja California have been tracked genetically and by satellite telemetry; these have been shown to come from Japanese breeding sites (Bowen et al. 1995; Resendiz et al. 1998; Nichols et al. 2000). Apparently, they gather along the Baja coast to capitalize on an abundance of nutrient-rich prey, like pelagic red crabs (*Pleuroncodes planipes*) that accumulate in local zones of upwelling (Bowen et al. 1995).

Loggerheads may pass Shatsky Rise on both eastward and westward legs of their trans-Pacific migration. On the eastward leg, juveniles are likely entrained by the Kuroshio Extension and carried directly to the Shatsky Rise where the Kuroshio bifurcates (Polovina et al. 2006). Juvenile loggerheads appear to linger in this area for months to forage in nutrient-rich surface waters (from fall to winter, and spring) (Polovina et al. 2006). In summer, when surface waters are oligotrophic (i.e., depleted of nutrients), it is less likely that loggerheads will be encountered in the Shatsky Rise area.

Once sexually mature, loggerheads depart feeding grounds near California and begin their long, slow journey back to natal beaches in Japan (Bowen et al. 1995; Nichols et al. 2000). Traveling <2 km/h, loggerheads appear to migrate along nutrient-rich, oceanic fronts in the north Pacific (Nichols et al. 2000; Polovina et al. 2000; Kobayashi et al. 2008). This preferred route, counter the North Pacific Current and past the Hawaiian Islands, returns loggerheads to the Shatsky Rise region where they are susceptible as bycatch to local longliners seeking tuna, swordfish, and sharks (Lewison et al. 2004; Yokota et al. 2006). After returning to Japan to breed, adult loggerheads tend to remain in the western Pacific, migrating annually between nesting beaches in Japan and feeding grounds in the South and East China Seas (Sato et al. 1997; Nichols 2005; Parker et al. 2005).

Loggerheads feed in all marine habitats, including coastal bays and estuaries, shallow water along the continental shelves, and high-seas (Bowen et al. 1995; Yokota et al. 2006; Reich et al. 2009). Adult loggerheads feed on a variety of benthic fauna like conchs, crabs, shrimp, sea urchins, sponges, and fish. During migrations through the open sea they feed primarily in surface waters on jellyfish, pteropods, floating mollusks, floating egg clusters, flying fish, and squid (Polovina et al. 2003, 2004).

The Shatsky Rise region tends to accumulate juvenile loggerheads for weeks to months on their outgoing migration to the North and East Pacific (Polovina et al. 2006). Adults likely migrate past this region upon return to nesting sites in Japan. Because loggerheads feed as they migrate, they can be attracted to the juvenile fish and squid used as bait on longlines, and are thus regularly hooked as bycatch by Japanese fishers far offshore in the Kuroshio Extension (Lewison et al. 2004; Yokota et al. 2006).

On average, loggerheads spend over 90% of their time underwater, although diving time and depth varies considerably with age and whether individuals are in coastal or high-sea habitats (Byles 1988; Renaud and Carpenter 1994). Juveniles spend more time on the surface in deep, offshore areas than in shallow, nearshore waters, possibly because they tend to migrate in the former and forage in the latter (Lutcavage and Lutz 1997). In the North Pacific, two loggerheads (tagged with satellite-linked depth recorders) spent about 40% of their time within 1 m of the surface, and although they were recorded plunging as deep as 100 m, 70% of dives were to depths less than 5 m (Polovina et al. 2003; Spotila

2004). Offshore of Japan, two adult loggerheads stayed within 30 m of the surface while feeding between nesting seasons (Sakamoto et al. 1993). Routine dives can last 4 to 172 min (Byles 1988; Sakamoto et al. 1990; Renaud and Carpenter 1994).

(2) Leatherback turtle

Leatherback turtles are listed as critically endangered on the 2009 IUCN Red List of Threatened Species (IUCN 2009), endangered by the U.S. ESA, and in Appendix I of the CITES (UNEP-WCMC 2009). The world leatherback population is estimated to have 35,860 females (Spotila 2004). There has been a significant decline and some extirpations of nesting populations in the Pacific (Spotila et al. 2000; Dutton et al. 2007).

The leatherback is the largest and most widely distributed sea turtle, ranging far from its tropical and subtropical breeding grounds to feed (Plotkin 2003). Frair et al. (1972) and Greer et al. (1973) noted that leatherback turtles have evolved physiological and anatomical adaptations to cold water, allowing them to venture into higher latitudes than other species of turtle. Leatherbacks have been reported from 71°N to 42°S in the Pacific Ocean (NMFS and USFWS 1998a, 2007b).

Similar to loggerhead turtles, adult leatherbacks appear to migrate along bathymetric contours from 200 to 3500 m (Morreale et al. 1994). Adults spend the majority of their time in waters >1000 m deep and possibly swim more than 10,000 km each year (Eckert 1995 *in* NMFS 2002). They appear to use the Kuroshio Extension during migrations from Indonesia to the high seas and East Pacific (Benson et al. 2008). Female leatherbacks approach coastal waters only during the reproductive season (EuroTurtle 2008), whereas males are rarely observed near nesting sites (NMFS 2002).

The largest remaining nesting sites for leatherbacks in the Pacific Ocean occur on the beaches of Birdshead Peninsula in Papua, Indonesia (Benson et al. 2008). Leatherbacks also nest in New Guinea, the Solomon Islands, and Vanuatu, with fewer nesting in Fiji, Malaysia, and Australia (EuroTurtle 2008; NMFS and USFWS 2007b). Nesting leatherbacks were recently discovered in Japan; thus, the closest nesting site to the Shatsky Rise is ~2500 km away, along the coast of the Ryukyu Islands (Kamezaki et al. 2002). In the eastern Pacific, leatherbacks nest along the west coast of Mexico and Central America (EuroTurtle 2008). Hatchling leatherbacks are pelagic, but nothing is known about their distribution for the first four years (Musick and Limpus 1997).

Leatherbacks tend to feed in areas of high productivity, such as current fronts and upwelling areas, along continental margins, and in archipelagic waters (Morreale et al. 1994; Lutcavage 1996). Leatherbacks feed mainly on jellyfish, tunicates, and other epipelagic soft-bodied invertebrates (Davenport and Balazs 1991). Predation on squid is inferred by incidental, long-line catches with squid used as bait (Skillman and Balazs 1992).

Although nesting is limited in Japan, leatherbacks are sighted off the coast at various times of the year (Sea Turtle Association of Japan 2010). Given the patchy distribution of high biomass areas associated with the Kuroshio Extension and bifurcation, combined with the apparent leatherback migration corridor along oceanic fronts in the north Pacific, leatherbacks are likely to appear occasionally in the Shatsky Rise region to feed much like loggerheads and other predators (Polovina et al. 2000; Komatsu et al. 2002; Yokota et al. 2006). However, to the best of our knowledge, leatherbacks have not been seen in the Shatsky Rise region, nor have they been caught by longliners fishing the Kuroshio Extension (e.g., Yokota et al. 2006).

Leatherback turtles are known to dive deeper than 1000 m, spending little time near the surface between subsequent dives (Eckert et al. 1986; Eckert et al. 1989; Southwood et al. 1998). Off Playa Grande, Costa Rica, six inter-nesting female leatherbacks spent 57–68% of their time underwater, diving at a mean depth of 19 m for 7.4 min (Southwood et al. 1998 *in* NMFS 2002). Offshore of St. Croix, six inter-nesting females dove to a mean depth of 61.6 m for an average of 9.9 min, and post-dive surfacing intervals averaged 4.9 min (Eckert et al. 1989). During shallow-water diving in the South China Sea, typical dive durations averaged 6.9 to 14.5 min, with a maximum of 42 min (Eckert et al. 1996). Off central California, leatherbacks dove to 20 to 30 m with a maximum of 92 m, corresponding to the vertical distribution if their prey, and mean dive and surface durations were 2.9 and 2.2 min, respectively (Harvey et al. 2006).

(3) Olive ridley turtle

Olive ridley turtles are categorized as vulnerable on the 2009 IUCN Red List of Threatened Species (IUCN 2009) and are listed in CITES Appendix I (UNEP-WCMC 2009). Under the U.S. ESA, the Mexico-Pacific breeding populations are listed as endangered; all other populations are listed as threatened. The worldwide population is estimated at about two million nesting females, making it the most abundant sea turtle in the world despite ongoing population declines (Spotila 2004).

The olive ridley turtle has a large range in tropical and subtropical regions in the Pacific, Indian, and South Atlantic oceans, and is generally found between 40ºN and 40ºS. In the western Pacific, nesting colonies occur in the Philippines and northern Australia (EuroTurtle 2008), Papua New Guinea (Spring 1995), Bruney, Malaysia, Indonesia, and Vietnam (Spotila 2004). They do not nest in Japan. In the eastern Pacific, the largest nesting concentrations occur in southern Mexico and northern Costa Rica, with stragglers nesting as far north as southern Baja California (Fritts et al. 1982) and as far south as Peru (Brown and Brown 1982). Most olive ridleys nest synchronously in huge colonies (1000s of individuals) called arribadas, although solitary nesting females are also common (Kalb and Owens 1994). Females generally lay two clutches of eggs with an inter-nesting period of one to two months throughout the year, peaking in the eastern Pacific during September to December (Plotkin et al. 1994b; NMFS and USFWS 1998b). Arribadas are not known to occur in the western Pacific (Spotila 2004). The olive ridley is the most abundant sea turtle found in the high seas of the ETP, where it can be seen foraging or mating in groups exceeding 1000 individuals called flotillas (Pitman 1990, 91; Arenas and Hall 1991; Kopitsky et al. 2000; NMFS 2002). Satellite tags on olive ridleys from Costa Rica were tracked more than 3000 km offshore in the central Pacific (Plotkin et al. 1994a).

Although olive ridleys aggregate during breeding seasons (peaking in August and September), they tend to disperse offshore when not breeding. Thus, little is know of their behaviors or migratory patterns during these times. In general, it is believed that olive ridleys do not return to specific offshore foraging areas, but that they are nomadic and occupy a series of feeding areas (Plotkin et al. 1994a,b). Presumably, olive ridleys are attracted to offshore areas of high productivity (e.g., current front and back-eddies of the Kuroshio Extension and bifurcation; e.g., akin to loggerheads, Polovina et al. 2006). However, to the best of our knowledge, olive ridleys have not been seen in the Shatsky Rise region, nor have they been caught by longliners fishing the Kuroshio Extension (e.g., Yokota et al. 2006). However, they are known to occur off the coast of Japan at various times of the year (Sea Turtle Association of Japan 2010).

Olive ridleys are primarily carnivorous, feeding on crabs, jellyfish, and fish eggs, resorting to algae when prey is scarce. They are often associated with flotsam in high seas, possibly feeding on associated fish and invertebrates (Pitman 1992). They are generally thought to be surface feeders, but have also

been caught in trawls at depths of 80–110 m (NMFS and USFWS 1998b, 2007c). Coastal fishery bycatch in waters around Penghu showed that coral reefs can also be foraging grounds for olive ridleys (Chen et al. 2004). After feeding (usually in the morning), olive ridleys spend considerable time basking in the sun near the sea surface, presumably in an effort to speed metabolism and digestion after a deep dive (Spotila 2004).

Olive ridleys are primarily a pelagic species (NMFS 2008a), capable of hunting at considerable depths (80–300 m), although ~90% of their time is spent in depths <100 m (Eckert et al. 1986; Polovina et al. 2003). In the ETP, at least 25% of total dive time is within the permanent thermocline, located at a depth of 20 to 100 m (Parker et al. 2003). In the North Pacific, two olive ridleys tagged with satellite-linked depth recorders spent ~20% of time in the top meter and ~10% of time deeper than 100 m; 70% of the dives were no deeper than 5 m (Polovina et al. 2003). Olive ridleys are also found regularly at the sea surface near flotsam, which probably acts as shelter and also habitat for prey items like small fish and invertebrates (Pitman 1992). Olive ridleys generally feed in the morning and bask near the surface in the afternoon sun (Spotila 2004).

(4) Green turtle

Green turtles are listed as endangered on the 2009 IUCN Red List of Threatened Species (IUCN 2009) and in CITES Appendix I (UNEP-WCMC 2009). Except for the endangered population nesting on the Pacific coast of Mexico, this species is listed as threatened under the U.S. ESA throughout its Pacific range. The global population is estimated between 88,520 and 150,000 nesting females (Spotila 2004; NMFS and USFWS 2007d), reduced by 50 to 70% since 1900 (Spotila 2004).

Some authorities treat the black turtle (*Chelonia agassizii*) as a separate species, but most recognize the black turtle as a subspecies of green turtle (Karl and Bowen 2001). Regardless, the green turtle is widely distributed in tropical and subtropical waters near continental coasts and around islands, including mainland China, Taiwan, Philippines, and Japan (Chan et al. 2007). In Japan, these turtles nest at Okinawa and adjacent islands of the central Ryukyus, as well as in the Ogasawara Islands (Chan et al. 2007). To the best of our knowledge, they have not been seen in the Shatsky Rise region, nor have they been caught by longliners fishing the Kuroshio Extension (e.g., Yokota et al. 2006). Shatsky Rise is probably too far north and offshore to be inhabited by green turtles.

Green turtles typically migrate along coastal routes from rookeries in Australia and the South China Sea to their feeding grounds, although some populations exhibit trans-oceanic migrations (EuroTurtle 2008; Chan et al. 2007). The closest nesting ground to Shatsky Rise is at least 1200 km away. In 1995 and 1996, surveys of Okinawa and the central Ryukyus, Japan, found five clutches belonging to green turtles (Kikukawa et al. 1996). The nesting period in this area seems to range from mid-May to mid-July (Kikukawa et al. 1996). In Taiwan, green turtles principally nest on Wan-an Island in the Penghu Archipelago and Lanyu Island in Taitung County (Cheng 1997 *in* Chan et al. 2007). Wan-an Island hosts a small rookery, which has had 2 to 19 nesting females annually from 1992 to 2005 (Chen and Cheng 1995). The small green turtle rookery on Lanyu Island hosts between 5 and 13 nesting females per season. Females show high nest-site fidelity, returning repeatedly to their natal beach to lay eggs. Nesting can occur throughout the year, but peaks between July and August (Cheng 2002). Juvenile and sub-adult green turtles can travel thousands of kilometers before they return to breeding and nesting grounds (Carr et al. 1978).

Green turtles feed during the day on seagrass and algae (Bjorndal 1982), and are thus typically associated with seagrass pastures, shallow inland waters, and coral reefs. However, some green turtles

remain in pelagic regions, feeding mostly on jellyfish and other pelagic prey (NMFS and USFWS 2007d). Satellite telemetry showed that the foraging grounds of adult green turtles nesting at Wan-an Island included the coastal waters off northern Taiwan, Nanao Island, Huidong, Hong Kong, Donsha Archipelago, Hainan Island, east coast of Leizhou Peninsula, northern Philippines, Ryukyu Archipelago (Japan), and Koshiki in southern Japan (Cheng et al. 2000; Cheng and Chen 1997). One post-nesting green turtle from Wan-an Island and another from Gangkou Sea Turtle National Reserve spent time in the nearshore waters of Okinawa Island, Japan (Cheng 2000a; Song et al. 2002). The northeastern waters of Okinawa Island are also known foraging sites for green turtles. The coastal fishery bycatch in Penghu waters showed that coral reefs also act as a foraging site for juvenile and subadult green turtles (Chen et al. 2004).

Hatchling green turtles are epipelagic (surface dwelling in the open sea) for the first one to three years. Subsequently, most inhabit shallow bays and protected shorelines. Green turtles typically dive less than 30 m deep (Hochscheid et al. 1999; Hays et al. 2000), although they have been recorded diving from 73 to 110 m in the eastern Pacific (Berkson 1967). The maximum dive time recorded for a juvenile green turtle was 66 min offshore of Hawaii, with routine dive times of 9 to 23 min (Brill et al. 1995).

(5) Hawksbill turtle

The hawksbill turtle is listed as critically endangered on the 2009 IUCN Red List of Threatened Species (IUCN 2009), in CITES Appendix I (UNEP-WCMC 2009), and it is considered endangered under the U.S. ESA. It is a solitary nester, which makes population estimates difficult. Nonetheless, the global population is thought to consist of 20,000 to 26,000 nesting females, reduced by >90% in the past 100 years (Spotila 2004).

Hawksbill turtles are typically associated with clear, coastal waters of mainland and island shelves, seagrass pastures, and coral reefs (Márquez 1990). Perhaps their closest inhabited range to the Shatsky Rise is in the Yellow and East China seas, including the Ryukyu Islands, Japan (Frazier et al. 1988). Hawksbills are known to nest at the Ryukyu Islands (Sea Turtle Association of Japan 2010). A small rookery (4 to 10 females) is also known on the Dongsha Archipelago, Taiwan (Cheng 1995, 2000b). The closest large rookery (with >1000 females) to the proposed Shatsky Rise study area is probably in Indonesia (Márquez 1990). It is expected that only post-hatchling hawksbills are likely to be found in the offshore waters of Shatsky Rise, taking shelter in weed lines around convergence zones before returning to coastal waters when they are 25 to 35 cm long (NMFS and USFWS 1998c). However, the offshore habit of juvenile hawksbills is not known (NMFS 2008b). It may be more likely to find an adult hawksbill near Shatsky Rise, perhaps transported by the warm Kuroshio Extension during an inter-breeding migration to feed (NMFS and USFWS 1998c, 2007e).

Hawksbill turtles are generalist carnivores, feeding on a variety of prey like corals, tunicates, algae, sponges, hydroids, gastropods, cephalopods, decapods, ascidians, and barnacles (Márquez 1990). In some areas, hawksbills may be specialist sponge feeders (e.g., Vicente 1994). These turtles typically feed by picking prey from substrates like rocks and reefs; thus, they are found regularly in coastal areas with suitable habitats for this feeding strategy like coral reefs and shallow seagrass pastures (Chen et al. 2004). Closest to the Shatsky Rise region, hawksbills appear to feed in waters surrounding Nanao Island and Dongshan Island in the East and South China seas (Xu and Zheng 2000 *in* Chan et al. 2007), and the inshore waters of Pingtan Island, Dongshan Island, and the Ryukyus, Japan (Zheng 1985; AFCD 2005).

Hawksbills move from shallow to deeper water (<200 m) as they grow (NMFS and USFWS 1998c). They have very long routine dive times; inter-nesting females in St. Croix averaged 56 min

underwater with a maximum dive time of 73.5 min and an average surface interval of about 2 min (Starbird et al. 1999). Average day and night dive times were 34 to 65 and 42 to 74 min, respectively. Based on time-depth recorder studies in Puerto Rico, foraging dives of immature hawksbills varied between 8.6 to 14 min with a mean depth of 4.7 m (van Dam and Diez 1996).

(6) Summary

Loggerhead, leatherback, and possibly olive ridley turtles could be encountered near Shatsky Rise. Green and hawksbill turtles are distributed in lower latitudes, tend to remain closer to shore, and are thus less likely to be encountered unless carried offshore to Shatsky Rise by a strong easterly current like the Kuroshio Extension.

The only sea turtle species identified in the vicinity of Shatsky Rise is the loggerhead, caught as bycatch by longliners fishing the Kuroshio Extension (see Lewison et al. 2004; Polovina et al. 2006; Yokota et al. 2006). Loggerheads are likely attracted to the various oceanic fronts and eddies associated with the Kuroshio Extension and its bifurcation near Shatsky Rise, because fronts and eddies tend to accumulate pelagic organisms and promote upwelling (and primary production), respectively. Moreover, these biological hotspots appear to be important for species spending prolonged periods offshore to migrate and feed, like loggerhead and leatherback turtles (Reich et al. 2009). The productive surface waters of the Kuroshio Extension also attract other top predators like swordfish and blue sharks (Yokota et al. 2006).

The Kuroshio bifurcation (west of Shatsky Rise) may be an important nursery area for anchovy and sardine spawn that are carried offshore from Japan by the Kuroshio Extension, especially during periods of high stock abundance (Komatsu et al. 2002). Incidentally, juvenile loggerheads—known to feed on small fish (Yokota et al. 2006)—also aggregate in this area in fall, winter, and spring when surface waters have high productivity; in summer, when surface productivity near Shatsky Rise is low, they migrate north (Polovina et al. 2006).

Sea surface temperature and chlorophyll *a* concentration (the latter is a measure of primary productivity) are the two best predictors of loggerhead migration corridors in the north Pacific (Kobayashi et al. 2008). For example, loggerheads aggregate within the Kuroshio Extension at temperatures between 19 to 24.5ºC, and along 17 and 20ºC current fronts near Hawaii during trans-Pacific migrations (Polovina et al. 2000). This corroborates observations nearshore, since loggerheads tend to accumulate in areas of coastal upwelling where ocean productivity is high (Bowen et al. 1995).

Loggerhead turtles departing from nesting sites along Japan are known to drift with strong currents offshore, as far as the Kuroshio Extension bifurcation near the Shatsky Rise (Ikeda 2008). Similarly, leatherbacks appear to use the Kuroshio Extension during migrations from Indonesia to the high seas and East Pacific (Benson et al. 2008). Conversely, loggerheads and leatherbacks may migrate past the Shatsky Rise upon return from high seas to Japanese nesting grounds (Bowen et al. 1995; Nichols et al. 2000). Accordingly, satellite telemetry has shown that loggerheads are capable of trans-Pacific migrations, from Baja California to Japan, possibly using the subtropical frontal zone as a migratory corridor (Resendiz et al. 1998; Nichols et al. 2000). Moreover, loggerheads have been followed while on against-current migrations (i.e., westward across the Pacific), apparently favoring corridors along current fronts, like that between the Subarctic and Subtropical Gyres in the north Pacific (Polovina et al. 2000).

All turtle species nest on island and mainland beaches, not at sea. Thus, the offshore Shatsky Rise study area is located far from any nesting beaches. The closest nesting site to Shatsky Rise is at least 2500 km away.

IV. ENVIRONMENTAL CONSEQUENCES

Proposed Action

(1) Direct Effects and Their Significance on Marine Mammals and Sea Turtles

The material in this section includes a summary of the anticipated effects (or lack thereof) on marine mammals and sea turtles of the airgun system to be used by L-DEO. A more detailed review of airgun effects on marine mammals appears in Appendix B. That Appendix is similar to corresponding parts of previous EAs and associated IHA applications concerning other L-DEO seismic surveys since 2003, but was updated in 2009. Appendix C contains a general review of the effects of seismic pulses on sea turtles. This section (along with Appendix B) also includes a discussion of the potential impacts of operations by L-DEO's MBES and SBP.

Finally, this section includes estimates of the numbers of marine mammals that could be affected by the proposed activity during the proposed seismic survey. A description of the rationale for L-DEO's estimates of the numbers of exposures to various received sound levels that could occur during the planned seismic program is also provided.

(a) Summary of Potential Effects of Airgun Sounds

The effects of sounds from airguns could include one or more of the following: tolerance, masking of natural sounds, behavioral disturbance, and at least in theory, temporary or permanent hearing impairment, or non-auditory physical or physiological effects (Richardson et al. 1995; Gordon et al. 2004; Nowacek et al. 2007; Southall et al. 2007). Permanent hearing impairment, in the unlikely event that it occurred, would constitute injury, but temporary threshold shift (TTS) is not an injury (Southall et al. 2007). Although the possibility cannot be entirely excluded, it is unlikely that the project would result in any cases of temporary or especially permanent hearing impairment, or any significant non-auditory physical or physiological effects. Some behavioral disturbance is expected, but this would be localized and short-term.

Tolerance.—Numerous studies have shown that pulsed sounds from airguns are often readily detectable in the water at distances of many kilometers. For a summary of the characteristics of airgun pulses, see Appendix B (3). Several studies have shown that marine mammals at distances more than a few kilometers from operating seismic vessels often show no apparent response—see Appendix B (5). That is often true even in cases when the pulsed sounds must be readily audible to the animals based on measured received levels and the hearing sensitivity of that mammal group. Although various baleen whales and toothed whales have been shown to react behaviorally to airgun pulses under some conditions, at other times mammals of both types have shown no overt reactions. The relative responsiveness of baleen and toothed whales are quite variable. During active seismic surveys, sea turtles typically do not show overt reactions to airgun pulses.

Masking.—Masking effects of pulsed sounds (even from large arrays of airguns) on marine mammal calls and other natural sounds are expected to be limited, although there are very few specific data on this. Because of the intermittent nature and low duty cycle of seismic pulses, animals can emit and receive sounds in the relatively quiet intervals between pulses. However, in exceptional situations, reverberation occurs for much or all of the interval between pulses (e.g., Simard et al. 2005; Clark and Gagnon 2006) which could mask calls. Some baleen and toothed whales are known to continue calling in the presence of seismic pulses, and their calls usually can be heard between the seismic pulses (e.g., Richardson et al. 1986; McDonald et al. 1995; Greene et al. 1999a,b; Nieukirk et al. 2004; Smultea et al.

2004; Holst et al. 2005a,b, 2006; Dunn et al. 2009). However, Clark and Gagnon (2006) reported that fin whales in the northeast Pacific Ocean went silent for an extended period starting soon after the onset of a seismic survey in the area. Similarly, there has been one report that sperm whales ceased calling when exposed to pulses from a very distant seismic ship (Bowles et al. 1994). However, more recent studies found that they continued calling in the presence of seismic pulses (Madsen et al. 2002; Tyack et al. 2003; Smultea et al. 2004; Holst et al. 2006; Jochens et al. 2008). Dolphins and porpoises commonly are heard calling while airguns are operating (e.g., Gordon et al. 2004; Smultea et al. 2004; Holst et al. 2005a,b; Potter et al. 2007). The sounds important to small odontocetes are predominantly at much higher frequencies than are the dominant components of airgun sounds, thus limiting the potential for masking. In general, masking effects of seismic pulses are expected to be minor, given the normally intermittent nature of seismic pulses. Masking effects on marine mammals are discussed further in Appendix B (4). We are not aware of any information concerning masking of hearing in sea turtles.

Disturbance Reactions.—Disturbance includes a variety of effects, including subtle to conspicuous changes in behavior, movement, and displacement. Based on NMFS (2001, p. 9293), NRC (2005), and Southall et al. (2007), we assume that simple exposure to sound, or brief reactions that do not disrupt behavioral patterns in a potentially significant manner, do not constitute harassment or "taking". By potentially significant, we mean "in a manner that might have deleterious effects to the well-being of individual marine mammals or their populations".

Reactions to sound, if any, depend on species, state of maturity, experience, current activity, reproductive state, time of day, and many other factors (Richardson et al. 1995; Wartzok et al. 2004; Southall et al. 2007; Weilgart 2007). If a marine mammal does react briefly to an underwater sound by changing its behavior or moving a small distance, the impacts of the change are unlikely to be significant to the individual, let alone the stock or population. However, if a sound source displaces marine mammals from an important feeding or breeding area for a prolonged period, impacts on individuals and populations could be significant (e.g., Lusseau and Bejder 2007; Weilgart 2007). Given the many uncertainties in predicting the quantity and types of impacts of noise on marine mammals, it is common practice to estimate how many mammals would be present within a particular distance of industrial activities and/or exposed to a particular level of industrial sound. In most cases, this approach likely overestimates the numbers of marine mammals that would be affected in some biologically-important manner.

The sound criteria used to estimate how many marine mammals might be disturbed to some biologically-important degree by a seismic program are based primarily on behavioral observations of a few species. Detailed studies have been done on humpback, gray, bowhead, and sperm whales. Less detailed data are available for some other species of baleen whales, small toothed whales, and sea otters, but for many species there are no data on responses to marine seismic surveys.

Baleen Whales

Baleen whales generally tend to avoid operating airguns, but avoidance radii are quite variable. Whales are often reported to show no overt reactions to pulses from large arrays of airguns at distances beyond a few kilometers, even though the airgun pulses remain well above ambient noise levels out to much longer distances. However, as reviewed in Appendix B (5), baleen whales exposed to strong noise pulses from airguns often react by deviating from their normal migration route and/or interrupting their feeding and moving away. In the cases of migrating gray and bowhead whales, the observed changes in behavior appeared to be of little or no biological consequence to the animals. They simply avoided the sound source by displacing their migration route to varying degrees, but within the natural boundaries of the migration corridors.

Studies of gray, bowhead, and humpback whales have shown that seismic pulses with received levels of 160–170 dB re 1 μPa_{rms} seem to cause obvious avoidance behavior in a substantial fraction of the animals exposed (Richardson et al. 1995). In many areas, seismic pulses from large arrays of airguns diminish to those levels at distances ranging from 4 to 15 km from the source. A substantial proportion of the baleen whales within those distances may show avoidance or other strong behavioral reactions to the airgun array. Subtle behavioral changes sometimes become evident at somewhat lower received levels, and studies summarized in Appendix B (5) have shown that some species of baleen whales, notably bowhead and humpback whales, at times show strong avoidance at received levels lower than 160–170 dB re 1 μPa_{rms}.

Responses of *humpback whales* to seismic surveys have been studied during migration, on summer feeding grounds, and on Angolan winter breeding grounds; there has also been discussion of effects on the Brazilian wintering grounds. McCauley et al. (1998, 2000a) studied the responses of humpback whales off Western Australia to a full-scale seismic survey with a 16-airgun, 2678-in^3 array, and to a single 20-in^3 airgun with source level 227 dB re 1 $\mu Pa \cdot m_{p-p}$. McCauley et al. (1998) documented that avoidance reactions began at 5–8 km from the array, and that those reactions kept most pods ~3–4 km from the operating seismic boat. McCauley et al. (2000a) noted localized displacement during migration of 4–5 km by traveling pods and 7–12 km by more sensitive resting pods of cow-calf pairs. Avoidance distances with respect to the single airgun were smaller but consistent with the results from the full array in terms of the received sound levels. The mean received level for initial avoidance of an approaching airgun was 140 dB re 1 μPa_{rms} for humpback pods containing females, and at the mean closest point of approach (CPA) distance the received level was 143 dB re 1 μPa_{rms}. The initial avoidance response generally occurred at distances of 5–8 km from the airgun array and 2 km from the single airgun. However, some individual humpback whales, especially males, approached within distances of 100–400 m, where the maximum received level was 179 dB re 1 μPa_{rms}.

Humpback whales on their summer feeding grounds in southeast Alaska did not exhibit persistent avoidance when exposed to seismic pulses from a 1.64-L (100-in^3) airgun (Malme et al. 1985). Some humpbacks seemed "startled" at received levels of 150–169 dB re 1 μPa. Malme et al. (1985) concluded that there was no clear evidence of avoidance, despite the possibility of subtle effects, at received levels up to 172 re 1 μPa on an approximate rms basis.

It has been suggested that South Atlantic humpback whales wintering off Brazil may be displaced or even strand upon exposure to seismic surveys (Engel et al. 2004). The evidence for this was circumstantial and subject to alternative explanations (IAGC 2004). Also, the evidence was not consistent with subsequent results from the same area of Brazil (Parente et al. 2006), or with direct studies of humpbacks exposed to seismic surveys in other areas and seasons. After allowance for data from subsequent years, there was "no observable direct correlation" between strandings and seismic surveys (IWC 2007:236).

There are no data on reactions of *right whales* to seismic surveys, but results from the closely-related *bowhead whale* show that their responsiveness can be quite variable depending on their activity (migrating vs. feeding). Bowhead whales migrating west across the Alaskan Beaufort Sea in autumn, in particular, are unusually responsive, with substantial avoidance occurring out to distances of 20–30 km from a medium-sized airgun source at received sound levels of around 120–130 dB re 1 μPa_{rms} [Miller et al. 1999; Richardson et al. 1999; see Appendix B (5)]. However, more recent research on bowhead whales (Miller et al. 2005; Harris et al. 2007) corroborates earlier evidence that, during the summer feeding season, bowheads are not as sensitive to seismic sources. Nonetheless, subtle but statistically significant changes in surfacing–respiration–dive cycles were evident upon statistical analysis

(Richardson et al. 1986). In summer, bowheads typically begin to show avoidance reactions at received levels of about 152–178 dB re 1 μPa_{rms} (Richardson et al. 1986, 1995; Ljungblad et al. 1988; Miller et al. 2005).

Reactions of migrating and feeding (but not wintering) *gray whales* to seismic surveys have been studied. Malme et al. (1986, 1988) studied the responses of feeding eastern Pacific gray whales to pulses from a single 100-in^3 airgun off St. Lawrence Island in the northern Bering Sea. They estimated, based on small sample sizes, that 50% of feeding gray whales stopped feeding at an average received pressure level of 173 dB re 1 μPa on an (approximate) rms basis, and that 10% of feeding whales interrupted feeding at received levels of 163 dB re 1 μPa_{rms}. Those findings were generally consistent with the results of experiments conducted on larger numbers of gray whales that were migrating along the California coast (Malme et al. 1984; Malme and Miles 1985), and western Pacific gray whales feeding off Sakhalin Island, Russia (Würsig et al. 1999; Gailey et al. 2007; Johnson et al. 2007; Yazvenko et al. 2007a,b), along with data on gray whales off British Columbia, Canada (Bain and Williams 2006).

Various species of *Balaenoptera* (blue, sei, fin, and minke whales) have occasionally been seen in areas ensonified by airgun pulses (Stone 2003; MacLean and Haley 2004; Stone and Tasker 2006), and calls from blue and fin whales have been localized in areas with airgun operations (e.g., McDonald et al. 1995; Dunn et al. 2009). Sightings by observers on seismic vessels off the United Kingdom from 1997 to 2000 suggest that, during times of good sightability, sighting rates for mysticetes (mainly fin and sei whales) were similar when large arrays of airguns were shooting vs. silent (Stone 2003; Stone and Tasker 2006). However, these whales tended to exhibit localized avoidance, remaining significantly further (on average) from the airgun array during seismic operations compared with non-seismic periods (Stone and Tasker 2006). In a study off Nova Scotia, Moulton and Miller (2005) found little difference in sighting rates (after accounting for water depth) and initial sighting distances of balaenopterid whales when airguns were operating vs. silent. However, there were indications that these whales were more likely to be moving away when seen during airgun operations. Similarly, ship-based monitoring studies of blue, fin, sei and minke whales offshore of Newfoundland (Orphan Basin and Laurentian Sub-basin) found no more than small differences in sighting rates and swim directions during seismic vs. non-seismic periods (Moulton et al. 2005, 2006a,b).

Data on short-term reactions by cetaceans to impulsive noises are not necessarily indicative of long-term or biologically significant effects. It is not known whether impulsive sounds affect reproductive rate or distribution and habitat use in subsequent days or years. However, gray whales have continued to migrate annually along the west coast of North America with substantial increases in the population over recent years, despite intermittent seismic exploration (and much ship traffic) in that area for decades (Appendix A *in* Malme et al. 1984; Richardson et al. 1995; Angliss and Allen 2009). The western Pacific gray whale population did not seem affected by a seismic survey in its feeding ground during a previous year (Johnson et al. 2007). Similarly, bowhead whales have continued to travel to the eastern Beaufort Sea each summer, and their numbers have increased notably, despite seismic exploration in their summer and autumn range for many years (Richardson et al. 1987; Angliss and Allen 2009).

Toothed Whales

Little systematic information is available about reactions of toothed whales to noise pulses. Few studies similar to the more extensive baleen whale/seismic pulse work summarized above and (in more detail) in Appendix B have been reported for toothed whales. However, there are recent systematic studies on sperm whales (e.g., Gordon et al. 2006; Madsen et al. 2006; Winsor and Mate 2006; Jochens et al. 2008; Miller et al. 2009). There is an increasing amount of information about responses of various

odontocetes to seismic surveys based on monitoring studies (e.g., Stone 2003; Smultea et al. 2004; Moulton and Miller 2005; Bain and Williams 2006; Holst et al. 2006; Stone and Tasker 2006; Potter et al. 2007; Hauser et al. 2008; Holst and Smultea 2008; Weir 2008; Barkaszi et al. 2009; Richardson et al. 2009).

Seismic operators and marine mammal observers on seismic vessels regularly see dolphins and other small toothed whales near operating airgun arrays, but in general there is a tendency for most delphinids to show some avoidance of operating seismic vessels (e.g., Goold 1996a,b,c; Calambokidis and Osmek 1998; Stone 2003; Moulton and Miller 2005; Holst et al. 2006; Stone and Tasker 2006; Weir 2008; Richardson et al. 2009; see also Barkaszi et al. 2009). Some dolphins seem to be attracted to the seismic vessel and floats, and some ride the bow wave of the seismic vessel even when large arrays of airguns are firing (e.g., Moulton and Miller 2005). Nonetheless, small toothed whales more often tend to head away, or to maintain a somewhat greater distance from the vessel, when a large array of airguns is operating than when it is silent (e.g., Stone and Tasker 2006; Weir 2008). In most cases the avoidance radii for delphinids appear to be small, on the order of 1 km less, and some individuals show no apparent avoidance. The beluga is a species that (at least at times) shows long-distance avoidance of seismic vessels. Aerial surveys conducted in the southeastern Beaufort Sea during summer found that sighting rates of beluga whales were significantly lower at distances 10–20 km compared with 20–30 km from an operating airgun array, and observers on seismic boats in that area rarely see belugas (Miller et al. 2005; Harris et al. 2007).

Captive bottlenose dolphins and beluga whales exhibited changes in behavior when exposed to strong pulsed sounds similar in duration to those typically used in seismic surveys (Finneran et al. 2000, 2002, 2005). However, the animals tolerated high received levels of sound before exhibiting aversive behaviors.

Results for porpoises depend on species. The limited available data suggest that harbor porpoises show stronger avoidance of seismic operations than do Dall's porpoises (Stone 2003; MacLean and Koski 2005; Bain and Williams 2006; Stone and Tasker 2006). Dall's porpoises seem relatively tolerant of airgun operations (MacLean and Koski 2005; Bain and Williams 2006), although they too have been observed to avoid large arrays of operating airguns (Calambokidis and Osmek 1998; Bain and Williams 2006). This apparent difference in responsiveness of these two porpoise species is consistent with their relative responsiveness to boat traffic and some other acoustic sources (Richardson et al. 1995; Southall et al. 2007).

Most studies of sperm whales exposed to airgun sounds indicate that the sperm whale shows considerable tolerance of airgun pulses (e.g., Stone 2003; Moulton et al. 2005, 2006a; Stone and Tasker 2006; Weir 2008). In most cases the whales do not show strong avoidance, and they continue to call (see Appendix B for review). However, controlled exposure experiments in the Gulf of Mexico indicate that foraging behavior was altered upon exposure to airgun sound (Jochens et al. 2008; Miller et al. 2009; Tyack 2009).

There are almost no specific data on the behavioral reactions of beaked whales to seismic surveys. However, some northern bottlenose whales remained in the general area and continued to produce high-frequency clicks when exposed to sound pulses from distant seismic surveys (Gosselin and Lawson 2004; Laurinolli and Cochrane 2005; Simard et al. 2005). Most beaked whales tend to avoid approaching vessels of other types (e.g., Würsig et al. 1998). They may also dive for an extended period when approached by a vessel (e.g., Kasuya 1986), although it is uncertain how much longer such dives may be as compared to dives by undisturbed beaked whales, which also are often quite long (Baird et al. 2006;

Tyack et al. 2006). In any event, it is likely that most beaked whales would also show strong avoidance of an approaching seismic vessel, although this has not been documented explicitly.

There are increasing indications that some beaked whales tend to strand when naval exercises involving mid-frequency sonar operation are ongoing nearby (e.g., Simmonds and Lopez-Jurado 1991; Frantzis 1998; NOAA and USN 2001; Jepson et al. 2003; Hildebrand 2005; Barlow and Gisiner 2006; see also the "Strandings and Mortality" subsection, later). These strandings are apparently at least in part a disturbance response, although auditory or other injuries or other physiological effects may also be involved. Whether beaked whales would ever react similarly to seismic surveys is unknown (see "Strandings and Mortality", below). Seismic survey sounds are quite different from those of the sonars in operation during the above-cited incidents.

Odontocete reactions to large arrays of airguns are variable and, at least for delphinids and Dall's porpoises, seem to be confined to a smaller radius than has been observed for the more responsive of the mysticetes, belugas, and harbor porpoises (Appendix B). A ≥170 dB re 1 μPa disturbance criterion (rather than ≥160 dB) is considered appropriate for delphinids (and pinnipeds), which tend to be less responsive than the more responsive cetaceans.

Sea Turtles

The limited available data indicate that sea turtles will hear airgun sounds and sometimes exhibit localized avoidance (see Appendix C). Based on available data, it is likely that sea turtles will exhibit behavioral changes and/or avoidance within an area of unknown size near a seismic vessel (e.g., Holst et al. 2005a, 2006; Holst and Smultea 2008). Observed responses of sea turtles to airguns are reviewed in Appendix C. To the extent that there are any impacts on sea turtles, seismic operations in or near areas where turtles concentrate are likely to have the greatest impact. There are no specific data that demonstrate the consequences to sea turtles if seismic operations with large or small arrays of airguns occur in important areas at biologically important times of year.

Additional details on the behavioral reactions (or the lack thereof) by all types of marine mammals to seismic vessels can be found in Appendix B (5). Corresponding details for sea turtles can be found in Appendix C.

Hearing Impairment and Other Physical Effects.—Temporary or permanent hearing impairment is a possibility when marine mammals are exposed to very strong sounds. TTS has been demonstrated and studied in certain captive odontocetes and pinnipeds exposed to strong sounds (reviewed in Southall et al. 2007). However, there has been no specific documentation of TTS let alone permanent hearing damage, i.e., permanent threshold shift (PTS), in free-ranging marine mammals exposed to sequences of airgun pulses during realistic field conditions. Current NMFS policy regarding exposure of marine mammals to high-level sounds is that cetaceans should not be exposed to impulsive sounds with received levels ≥180 dB re 1 μPa_{rms} (NMFS 2000). This criterion has been used in establishing the exclusion (=shut-down) zones planned for the proposed seismic survey. However, this criterion was established before there was any information about minimum received levels of sounds necessary to cause auditory impairment in marine mammals. As discussed in Appendix B (6) and summarized here,

- the 180-dB criterion for cetaceans is probably quite precautionary, i.e., lower than necessary to avoid temporary auditory impairment let alone permanent auditory injury, at least for delphinids.
- TTS is not injury and does not constitute "Level A harassment" in U.S. MMPA terminology.

- the minimum sound level necessary to cause permanent hearing impairment ("Level A harassment") is higher, by a variable and generally unknown amount, than the level that induces barely-detectable TTS.
- the level associated with the onset of TTS is often considered to be a level below which there is no danger of permanent damage. The actual PTS threshold is likely to be well above the level causing onset of TTS (Southall et al. 2007).

Recommendations for new science-based noise exposure criteria for marine mammals, frequency-weighting procedures, and related matters were published recently (Southall et al. 2007). Those recommendations have not, as of late 2009, been formally adopted by NMFS for use in regulatory processes and during mitigation programs associated with seismic surveys. However, some aspects of the recommendations have been taken into account in certain EISs and small-take authorizations. NMFS has indicated that it may issue new noise exposure criteria for marine mammals that account for the now-available scientific data on TTS, the expected offset between the TTS and PTS thresholds, differences in the acoustic frequencies to which different marine mammal groups are sensitive (e.g., M-weighting or generalized frequency weightings for various groups of marine mammals, allowing for their functional bandwidths), and other relevant factors. Preliminary information about possible changes in the regulatory and mitigation requirements, and about the possible structure of new criteria, was given by Wieting (2004) and NMFS (2005).

Several aspects of the planned monitoring and mitigation measures for this project are designed to detect marine mammals occurring near the airgun array, and to avoid exposing them to sound pulses that might, at least in theory, cause hearing impairment (see § II, "Monitoring and Mitigation Measures"). In addition, many cetaceans and (to a limited degree) sea turtles show some avoidance of the area where received levels of airgun sound are high enough such that hearing impairment could potentially occur. In those cases, the avoidance responses of the animals themselves will reduce or (most likely) avoid any possibility of hearing impairment.

Non-auditory physical effects may also occur in marine mammals exposed to strong underwater pulsed sound. Possible types of non-auditory physiological effects or injuries that might (in theory) occur in mammals close to a strong sound source include stress, neurological effects, bubble formation, and other types of organ or tissue damage. It is possible that some marine mammal species (i.e., beaked whales) may be especially susceptible to injury and/or stranding when exposed to strong transient sounds. However, as discussed below, there is no definitive evidence that any of these effects occur even for marine mammals in close proximity to large arrays of airguns. It is unlikely that any effects of these types would occur during the present project given the brief duration of exposure of any given mammal, the deep water in the study area, and the planned monitoring and mitigation measures (see below). The following subsections discuss in somewhat more detail the possibilities of TTS, PTS, and non-auditory physical effects.

Temporary Threshold Shift

TTS is the mildest form of hearing impairment that can occur during exposure to a strong sound (Kryter 1985). While experiencing TTS, the hearing threshold rises and a sound must be stronger in order to be heard. At least in terrestrial mammals, TTS can last from minutes or hours to (in cases of strong TTS) days. For sound exposures at or somewhat above the TTS threshold, hearing sensitivity in both terrestrial and marine mammals recovers rapidly after exposure to the noise ends. Few data on sound levels and durations necessary to elicit mild TTS have been obtained for marine mammals, and none of

the published data concern TTS elicited by exposure to multiple pulses of sound. Available data on TTS in marine mammals are summarized in Southall et al. (2007). Based on these data, the received energy level of a single seismic pulse (with no frequency weighting) might need to be ~186 dB re 1 $\mu Pa^2 \cdot s$ (i.e., 186 dB SEL or ~196–201 dB re 1 μPa_{rms}) in order to produce brief, mild TTS[1]. Exposure to several strong seismic pulses that each have received levels near 190 dB re 1 μPa_{rms} might result in cumulative exposure of ~186 dB SEL and thus slight TTS in a small odontocete assuming the TTS threshold is (to a first approximation) a function of the total received pulse energy; however, this 'equal-energy' concept is an oversimplification. The distances from the *Langseth*'s airguns at which the received energy level (per pulse, flat-weighted) would be expected to be ≥190 dB re 1 μPa_{rms} are estimated in Table 1. Levels ≥190 dB re 1 μPa_{rms} are expected to be restricted to radii no more than 460 m (Table 1). For an odontocete closer to the surface, the maximum radius with ≥190 dB re 1 μPa_{rms} would be smaller.

The above TTS information for odontocetes is derived from studies on the bottlenose dolphin and beluga. For the one harbor porpoise tested, the received level of airgun sound that elicited onset of TTS was lower (Lucke et al. 2009). If these results from a single animal are representative, it is inappropriate to assume that onset of TTS occurs at similar received levels in all odontocetes (*cf.* Southall et al. 2007). Some cetaceans apparently can incur TTS at considerably lower sound exposures than are necessary to elicit TTS in the beluga or bottlenose dolphin.

For baleen whales, there are no data, direct or indirect, on levels or properties of sound that are required to induce TTS. The frequencies to which baleen whales are most sensitive are assumed to be lower than those to which odontocetes are most sensitive, and natural background noise levels at those low frequencies tend to be higher. As a result, auditory thresholds of baleen whales within their frequency band of best hearing are believed to be higher (less sensitive) than are those of odontocetes at their best frequencies (Clark and Ellison 2004). From this, it is suspected that received levels causing TTS onset may also be higher in baleen whales (Southall et al. 2007). In any event, no cases of TTS are expected given three considerations: (1) the low abundance of baleen whales in the planned study area at the time of the survey; (2) the strong likelihood that baleen whales would avoid the approaching airguns (or vessel) before being exposed to levels high enough for TTS to occur; and (3) the mitigation measures that are planned.

NMFS (1995, 2000) concluded that cetaceans should not be exposed to pulsed underwater noise at received levels exceeding 180 dB re 1 μPa_{rms}. This sound level is ***not*** considered to be the level above which TTS might occur. Rather, it was the received levels above which, in the view of a panel of bioacoustics specialists convened by NMFS before TTS measurements for marine mammals started to become available, one could not be certain that there would be no injurious effects, auditory or otherwise, to cetaceans. As summarized above and in Southall et al. (2007), data that are now available imply that TTS is unlikely to occur in most odontocetes (and probably mysticetes as well) unless they are exposed to a sequence of several airgun pulses stronger than 190 dB re 1 μPa_{rms}.

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[1] If the low frequency components of the watergun sound used in the experiments of Finneran et al. (2002) are downweighted as recommended by Miller et al. (2005) and Southall et al. (2007) using their M_{mf}-weighting curve, the effective exposure level for onset of mild TTS was 183 dB re 1 $\mu Pa^2 \cdot s$ (Southall et al. 2007).

Permanent Threshold Shift

When PTS occurs, there is physical damage to the sound receptors in the ear. In severe cases, there can be total or partial deafness, whereas in other cases, the animal has an impaired ability to hear sounds in specific frequency ranges (Kryter 1985).

There is no specific evidence that exposure to pulses of airgun sound can cause PTS in any marine mammal, even with large arrays of airguns. However, given the possibility that mammals close to an airgun array might incur at least mild TTS, there has been further speculation about the possibility that some individuals occurring very close to airguns might incur PTS (e.g., Richardson et al. 1995, p. 372*ff*; Gedamke et al. 2008). Single or occasional occurrences of mild TTS are not indicative of permanent auditory damage, but repeated or (in some cases) single exposures to a level well above that causing TTS onset might elicit PTS.

Relationships between TTS and PTS thresholds have not been studied in marine mammals, but are assumed to be similar to those in humans and other terrestrial mammals. PTS might occur at a received sound level at least several decibels above that inducing mild TTS if the animal were exposed to strong sound pulses with rapid rise time—see Appendix B (6). Based on data from terrestrial mammals, a precautionary assumption is that the PTS threshold for impulse sounds (such as airgun pulses as received close to the source) is *at least* 6 dB higher than the TTS threshold on a peak-pressure basis, and probably >6 dB (Southall et al. 2007). On an SEL basis, Southall et al. (2007:441-4) estimated that received levels would need to exceed the TTS threshold by at least 15 dB for there to be risk of PTS. Thus, for cetaceans they estimate that the PTS threshold might be an M-weighted SEL (for the sequence of received pulses) of ~198 dB re 1 $\mu Pa^2 \cdot s$ (15 dB higher than the M_{mf}-weighted TTS threshold, in a beluga, for a watergun impulse), where the SEL value is cumulated over the sequence of pulses.

Southall et al. (2007) also note that, regardless of the SEL, there is concern about the possibility of PTS if a cetacean received one or more pulses with peak pressure exceeding 230 or 218 dB re 1 μPa (peak), respectively. Thus, PTS might be expected upon exposure of cetaceans to <u>either</u> SEL ≥198 dB re 1 $\mu Pa^2 \cdot s$ <u>or</u> peak pressure ≥230 dB re 1 μPa. Corresponding proposed dual criteria for pinnipeds (at least harbor seals) are ≥186 dB SEL and ≥ 218 dB peak pressure (Southall et al. 2007). These estimates are all first approximations, given the limited underlying data, assumptions, species differences, and evidence that the "equal energy" model is not be entirely correct. A peak pressure of 230 dB re 1 μPa (3.2 bar·m, 0-pk) would only be found within a few meters of the largest (360-in^3) airguns in the planned airgun array (e.g., Caldwell and Dragoset 2000). A peak pressure of 218 dB re 1 μPa could be received somewhat farther away; to estimate that specific distance, one would need to apply a model that accurately calculates peak pressures in the near-field around an array of airguns.

Given the higher level of sound necessary to cause PTS as compared with TTS, it is considerably less likely that PTS would occur. Baleen whales generally avoid the immediate area around operating seismic vessels, as do some other marine mammals and sea turtles. The planned monitoring and mitigation measures, including visual monitoring, PAM, power downs, and shut downs of the airguns when mammals are seen within or approaching the "exclusion zones", will further reduce the probability of exposure of marine mammals to sounds strong enough to induce PTS.

Strandings and Mortality

Marine mammals close to underwater detonations of high explosives can be killed or severely injured, and the auditory organs are especially susceptible to injury (Ketten et al. 1993; Ketten 1995). However, explosives are no longer used for marine waters for commercial seismic surveys or (with rare

exceptions) for seismic research; they have been replaced entirely by airguns or related non-explosive pulse generators. Airgun pulses are less energetic and have slower rise times, and there is no specific evidence that they can cause serious injury, death, or stranding even in the case of large airgun arrays. However, the association of strandings of beaked whales with naval exercises and, in one case, an L-DEO seismic survey (Malakoff 2002; Cox et al. 2006), has raised the possibility that beaked whales exposed to strong "pulsed" sounds may be especially susceptible to injury and/or behavioral reactions that can lead to stranding (e.g., Hildebrand 2005; Southall et al. 2007). Appendix B (6) provides additional details.

Specific sound-related processes that lead to strandings and mortality are not well documented, but may include (1) swimming in avoidance of a sound into shallow water; (2) a change in behavior (such as a change in diving behavior) that might contribute to tissue damage, gas bubble formation, hypoxia, cardiac arrhythmia, hypertensive hemorrhage or other forms of trauma; (3) a physiological change such as a vestibular response leading to a behavioral change or stress-induced hemorrhagic diathesis, leading in turn to tissue damage; and (4) tissue damage directly from sound exposure, such as through acoustically mediated bubble formation and growth or acoustic resonance of tissues. Some of these mechanisms are unlikely to apply in the case of impulse sounds. However, there are increasing indications that gas-bubble disease (analogous to "the bends"), induced in supersaturated tissue by a behavioral response to acoustic exposure, could be a pathologic mechanism for the strandings and mortality of some deep-diving cetaceans exposed to sonar. The evidence for this remains circumstantial and associated with exposure to naval mid-frequency sonar, not seismic surveys (Cox et al. 2006; Southall et al. 2007).

Seismic pulses and mid-frequency sonar signals are quite different, and some mechanisms by which sonar sounds have been hypothesized to affect beaked whales are unlikely to apply to airgun pulses. Sounds produced by airgun arrays are broadband impulses with most of the energy below 1 kHz. Typical military mid-frequency sonars emit non-impulse sounds at frequencies of 2–10 kHz, generally with a relatively narrow bandwidth at any one time. A further difference between seismic surveys and naval exercises is that naval exercises can involve sound sources on more than one vessel. Thus, it is not appropriate to assume that there is a direct connection between the effects of military sonar and seismic surveys on marine mammals. However, evidence that sonar signals can, in special circumstances, lead (at least indirectly) to physical damage and mortality (e.g., Balcomb and Claridge 2001; NOAA and USN 2001; Jepson et al. 2003; Fernández et al. 2004, 2005; Hildebrand 2005; Cox et al. 2006) suggests that caution is warranted when dealing with exposure of marine mammals to any high-intensity "pulsed" sound.

There is no conclusive evidence of cetacean strandings or deaths at sea as a result of exposure to seismic surveys, but a few cases of strandings in the general area where a seismic survey was ongoing have led to speculation concerning a possible link between seismic surveys and strandings. Suggestions that there was a link between seismic surveys and strandings of humpback whales in Brazil (Engel et al. 2004) were not well founded (IAGC 2004; IWC 2007). In Sept. 2002, there was a stranding of two Cuvier's beaked whales in the Gulf of California, Mexico, when the L-DEO vessel R/V *Maurice Ewing* was operating a 20-airgun, 8490-in^3 airgun array in the general area. The link between the stranding and the seismic surveys was inconclusive and not based on any physical evidence (Hogarth 2002; Yoder 2002). Nonetheless, the Gulf of California incident plus the beaked whale strandings near naval exercises involving use of mid-frequency sonar suggests a need for caution in conducting seismic surveys in areas occupied by beaked whales until more is known about effects of seismic surveys on those species (Hildebrand 2005). No injuries of beaked whales are anticipated during the proposed study because of (1) the high likelihood that any beaked whales nearby would avoid the approaching vessel before being exposed to high sound levels, (2) the proposed monitoring and mitigation measures, and (3) differences

between the sound sources operated by L-DEO and those involved in the naval exercises associated with strandings.

Non-auditory Physiological Effects

Non-auditory physiological effects or injuries that theoretically might occur in marine mammals exposed to strong underwater sound include stress, neurological effects, bubble formation, resonance, and other types of organ or tissue damage (Cox et al. 2006; Southall et al. 2007). Studies examining such effects are limited. However, resonance effects (Gentry 2002) and direct noise-induced bubble formation (Crum et al. 2005) are implausible in the case of exposure to an impulsive broadband source like an airgun array. If seismic surveys disrupt diving patterns of deep-diving species, this might perhaps result in bubble formation and a form of "the bends", as speculated to occur in beaked whales exposed to sonar. However, there is no specific evidence of this upon exposure to airgun pulses.

In general, very little is known about the potential for seismic survey sounds (or other types of strong underwater sounds) to cause non-auditory physical effects in marine mammals. Such effects, if they occur at all, would presumably be limited to short distances and to activities that extend over a prolonged period. The available data do not allow identification of a specific exposure level above which non-auditory effects can be expected (Southall et al. 2007), or any meaningful quantitative predictions of the numbers (if any) of marine mammals that might be affected in those ways. Marine mammals that show behavioral avoidance of seismic vessels, including most baleen whales and some odontocetes, are especially unlikely to incur non-auditory physical effects. Also, the planned mitigation measures [§ II (3)], including shut downs of the airguns, will reduce any such effects that might otherwise occur.

Sea Turtles

The limited available data indicate that the frequency range of best hearing sensitivity by sea turtles extends from roughly 250–300 Hz to 500–700 Hz. Sensitivity deteriorates as one moves away from that range to either lower or higher frequencies. However, there is some sensitivity to frequencies as low as 60 Hz, and probably as low as 30 Hz. Thus, there is substantial overlap in the frequencies that sea turtles detect vs. the frequencies in airgun pulses. We are not aware of measurements of the absolute hearing thresholds of any sea turtle to waterborne sounds similar to airgun pulses. In the absence of relevant absolute threshold data, we cannot estimate how far away an airgun array might be audible. Moein et al. (1994) and Lenhardt (2002) reported TTS for loggerhead turtles exposed to many airgun pulses (Appendix C). This suggests that sounds from an airgun array might cause temporary hearing impairment in sea turtles if they do not avoid the (unknown) radius where TTS occurs. However, exposure duration during the planned surveys would be much less than during the aforementioned studies. Also, recent monitoring studies show that some sea turtles do show localized movement away from approaching airguns (Holst et al. 2005a, 2006; Holst and Smultea 2008). At short distances from the source, received sound level diminishes rapidly with increasing distance. In that situation, even a small-scale avoidance response could result in a significant reduction in sound exposure.

As noted above, the MMOs stationed on the *Langseth* will also watch for sea turtles, and airgun operations will be shut down if a turtle enters the designated exclusion zone.

(b) Possible Effects of Multibeam Echosounder Signals

The Kongsberg EM 122 MBES will be operated from the source vessel during the planned study. Information about this equipment was provided in § II. Sounds from the MBES are very short pulses, occurring for 2–15 ms once every 5–20 s, depending on water depth. Most of the energy in the sound pulses emitted by this MBES is at frequencies near 12 kHz, and the maximum source level is 242 dB re 1

$\mu Pa_{rms} \cdot m_{rms}$. The beam is narrow (1–2º) in fore-aft extent and wide (150º) in the cross-track extent. Each ping consists of eight (in water >1000 m deep) or four (<1000 m deep) successive fan-shaped transmissions (segments) at different cross-track angles. Any given mammal at depth near the trackline would be in the main beam for only one or two of the nine segments. Also, marine mammals that encounter the Kongsberg EM 122 are unlikely to be subjected to repeated pulses because of the narrow fore–aft width of the beam and will receive only limited amounts of pulse energy because of the short pulses. Animals close to the ship (where the beam is narrowest) are especially unlikely to be ensonified for more than one 2–15 ms pulse (or two pulses if in the overlap area). Similarly, Kremser et al. (2005) noted that the probability of a cetacean swimming through the area of exposure when an MBES emits a pulse is small. The animal would have to pass the transducer at close range and be swimming at speeds similar to the vessel in order to receive the multiple pulses that might result in sufficient exposure to cause TTS.

Navy sonars that have been linked to avoidance reactions and stranding of cetaceans (1) generally have a longer pulse duration than the Kongsberg EM 122, and (2) are often directed close to horizontally vs. more downward for the MBES. The area of possible influence of the MBES is much smaller—a narrow band below the source vessel. The duration of exposure for a given marine mammal can be much longer for a naval sonar. During L-DEO's operations, the individual pulses will be very short, and a given mammal would not receive many of the downward-directed pulses as the vessel passes by. Possible effects of an MBES on marine mammals are outlined below.

Masking.—Marine mammal communications will not be masked appreciably by the MBES signals given the low duty cycle of the echosounder and the brief period when an individual mammal is likely to be within its beam. Furthermore, in the case of baleen whales, the MBES signals (12 kHz) do not overlap with the predominant frequencies in the calls, which would avoid any significant masking.

Behavioral Responses.—Behavioral reactions of free-ranging marine mammals to sonars, echosounders, and other sound sources appear to vary by species and circumstance. Observed reactions have included silencing and dispersal by sperm whales (Watkins et al. 1985), increased vocalizations and no dispersal by pilot whales (Rendell and Gordon 1999), and the previously-mentioned beachings by beaked whales. During exposure to a 21–25 kHz "whale-finding" sonar with a source level of 215 dB re 1 $\mu Pa \cdot m$, gray whales reacted by orienting slightly away from the source and being deflected from their course by ~200 m (Frankel 2005). When a 38-kHz echosounder and a 150-kHz acoustic Doppler current profiler were transmitting during studies in the Eastern Tropical Pacific, baleen whales showed no significant responses, while spotted and spinner dolphins were detected slightly more often and beaked whales less often during visual surveys (Gerrodette and Pettis 2005).

Captive bottlenose dolphins and a white whale exhibited changes in behavior when exposed to 1-s tonal signals at frequencies similar to those that will be emitted by the MBES used by L-DEO, and to shorter broadband pulsed signals. Behavioral changes typically involved what appeared to be deliberate attempts to avoid the sound exposure (Schlundt et al. 2000; Finneran et al. 2002; Finneran and Schlundt 2004). The relevance of those data to free-ranging odontocetes is uncertain, and in any case, the test sounds were quite different in duration as compared with those from an MBES.

Hearing Impairment and Other Physical Effects.—Given recent stranding events that have been associated with the operation of naval sonar, there is concern that mid-frequency sonar sounds can cause serious impacts to marine mammals (see above). However, the MBES proposed for use by L-DEO is quite different than sonars used for navy operations. Pulse duration of the MBES is very short relative to the naval sonars. Also, at any given location, an individual marine mammal would be in the beam of the

MBES for much less time given the generally downward orientation of the beam and its narrow fore-aft beamwidth; navy sonars often use near-horizontally-directed sound. Those factors would all reduce the sound energy received from the MBES rather drastically relative to that from the sonars used by the navy.

Given the maximum source level of 242 dB re 1 $\mu Pa \cdot m_{rms}$ (see § II), the received level for an animal within the MBES beam 100 m below the ship would be ~202 dB re 1 μPa_{rms}, assuming 40 dB of spreading loss over 100 m (circular spreading). Given the narrow beam, only one pulse is likely to be received by a given animal as the ship passes overhead. The received energy level from a single pulse of duration 15 ms would be about 184 dB re 1 $\mu Pa^2 \cdot s$, i.e., 202 dB + 10 log (0.015 s). That is below the TTS threshold for a cetacean receiving a single non-impulse sound (195 dB re 1 $\mu Pa^2 \cdot s$) and even further below the anticipated PTS threshold (215 dB re 1 $\mu Pa^2 \cdot s$) (Southall et al. 2007). In contrast, an animal that was only 10 m below the MBES when a ping is emitted would be expected to receive a level ~20 dB higher, i.e., 204 dB re 1 $\mu Pa^2 \cdot s$ in the case of the EM120. That animal might incur some TTS (which would be fully recoverable), but the exposure would still be below the anticipated PTS threshold for cetaceans. As noted by Burkhardt et al. (2007, 2008), cetaceans are very unlikely to incur PTS from operation of scientific sonars on a ship that is underway.

Sea Turtles.—It is unlikely that MBES operations during the planned seismic survey would significantly affect sea turtles through masking, disturbance, or hearing impairment. Any effects would likely be negligible given the brief exposure and the fact that the MBES frequency is far above the range of optimal hearing by sea turtles (see Appendix C).

(c) Possible Effects of the Sub-bottom Profiler Signals

An SBP will also be operated from the source vessel during the planned study. Details about this equipment were provided in § II. Sounds from the SBP are very short pulses, occurring for 1–4 ms once every second. Most of the energy in the sound pulses emitted by the SBP is at 3.5 kHz, and the beam is directed downward. The sub-bottom profiler on the *Langseth* has a maximum source level of 204 dB re 1 μPa·m (see § II). Kremser et al. (2005) noted that the probability of a cetacean swimming through the area of exposure when a bottom profiler emits a pulse is small—even for an SBP more powerful than that on the *Langseth*—if the animal was in the area, it would have to pass the transducer at close range and in order to be subjected to sound levels that could cause TTS.

Masking.—Marine mammal communications will not be masked appreciably by the SBP signals given the directionality of the signal and the brief period when an individual mammal is likely to be within its beam. Furthermore, in the case of most baleen whales, the SBP signals do not overlap with the predominant frequencies in the calls, which would avoid significant masking.

Behavioral Responses.—Marine mammal behavioral reactions to other pulsed sound sources are discussed above, and responses to the SBP are likely to be similar to those for other pulsed sources if received at the same levels. However, the pulsed signals from the SBP are considerably weaker than those from the MBES. Therefore, behavioral responses are not expected unless marine mammals are very close to the source.

Hearing Impairment and Other Physical Effects.—It is unlikely that the SBP produces pulse levels strong enough to cause hearing impairment or other physical injuries even in an animal that is (briefly) in a position near the source. The SBP operated simultaneously with other higher-power acoustic sources, including the airguns. Many marine mammals will move away in response to the approaching higher-power sources or the vessel itself before the mammals would be close enough for there to be any possibility of effects from the less intense sounds from the SBP. In the case of mammals that do not avoid the

approaching vessel and its various sound sources, mitigation measures that would be applied to minimize effects of other sources [see § II(3)] would further reduce or eliminate any minor effects of the SBP.

Sea Turtles.—It is very unlikely that SBP operations during the planned seismic survey would significantly affect sea turtles through masking, disturbance, or hearing impairment. Any effects likely would be negligible given the brief exposure and relatively low source level. Also, the frequency of the SBP sounds is higher than the frequency range of best hearing by sea turtles.

(d) Possible Effects of Acoustic Release Signals

The acoustic release transponder used to communicate with the OBSs uses frequencies of 9–13 kHz. These signals will be used very intermittently. It is unlikely that the acoustic release signals would have a significant effect on marine mammals or sea turtles through masking, disturbance, or hearing impairment. Any effects likely would be negligible given the brief exposure at presumable low levels.

(2) Mitigation Measures for Marine Mammals and Sea Turtles

Several mitigation measures are built into the proposed seismic survey as an integral part of the planned activities. These measures include the following: ramp ups, minimum of one dedicated observer maintaining a visual watch during all daytime airgun operations, two observers for 30 min before and during ramp ups during the day and at night (and when possible at other times), PAM during the day and night to complement visual monitoring (when practicable), power downs (or if necessary shut downs) when mammals or turtles are detected in or about to enter designated exclusion zones. Also, special mitigation measures are in place for the North Pacific right whale. These mitigation measures are described earlier in this document, in § II(3). The fact that the 36-airgun array, as a result of its design, directs the majority of the energy downward, and less energy laterally, is also an inherent mitigation measure, as is the relatively wide spacing of the airgun shots during OBS operations (~70 s).

Previous and subsequent analysis of the potential impacts take account of these planned mitigation measures. It would not be meaningful to analyze the effects of the planned activities without mitigation, as the mitigation (and associated monitoring) measures are a basic part of the activities.

(3) Numbers of Marine Mammals that Could be "Taken by Harassment"

All anticipated takes would be "takes by harassment", involving temporary changes in behavior. The mitigation measures to be applied will minimize the possibility of injurious takes. (However, as noted earlier, there is no specific information demonstrating that injurious "takes" would occur even in the absence of the planned mitigation measures.) In the sections below, we describe methods to estimate the number of potential exposures to various received sound levels and present estimates of the numbers of marine mammals that could be affected during the proposed seismic program. The estimates are based on a consideration of the number of marine mammals that could be disturbed appreciably by operations with the 36-airgun array to be used during ~3160 km of seismic surveys at the Shatsky Rise. The sources of distributional and numerical data used in deriving the estimates are described in the next subsection.

It is assumed that, during simultaneous operations of the airgun array and the other sources, any marine mammals close enough to be affected by the MBES and SBP would already be affected by the airguns. However, whether or not the airguns are operating simultaneously with the other sources, marine mammals are expected to exhibit no more than short-term and inconsequential responses to the MBES and SBP given their characteristics (e.g., narrow downward-directed beam) and other considerations described in §II and IV(1)(b and c), above. Such reactions are not considered to constitute "taking"

(NMFS 2001). Therefore, no additional allowance is included for animals that could be affected by sound sources other than airguns.

(a) Basis for Estimating "Take by Harassment"

Density data on 18 marine mammal species in the Shatsky Rise area are available from two sources using conventional line transect methods: Japanese sighting surveys conducted since the early 1980s, and fisheries observers in the high-seas driftnet fisheries during 1987–1990 (Table 3). For the 16 other marine mammal species that could be encountered in the proposed survey area, data from the western North Pacific are not available (Table 3). We are not aware of any density estimates for three of those species—Hubb's, Stejneger's, and gingko-toothed beaked whales. For the remaining 13 species (Table 3), density estimates are available from other areas of the Pacific: 11 species from the offshore stratum of the 2002 Hawaiian Islands survey (Barlow 2006) and two species from surveys of the California Current ecosystem off the U.S. west coast between 1991 and 2005 (Barlow and Forney 2007). Those estimates are based on standard line-transect protocols developed by NMFS Southwest Fisheries Science Center (SWFSC).

Densities for 14 species are available from Japanese sighting surveys in the Shatsky Rise survey area. Miyashita (1993a) provided estimates for six dolphin species in this area that have been taken in the Japanese drive fisheries. The densities used here are Miyashita's (1993a) estimates for the 'Eastern offshore' survey area (30–42°N, 145°E–180°). Kato and Miyashita (1998) provided estimates for sperm whale densities from Japanese sightings data during 1982–1996 in the western North Pacific (20–50°N, 130°E–180°), and Hakamada et al. (2004) provided density estimates for sei whales during August–September in the JARPN II sub-areas 8 and 9 (35–50ºN, 150–170ºE excluding waters in the EEZ of Russia) during 2002–2003. We used density estimates during 1994–2007 for minke whales at 35–40ºN, 157–170ºE from Hakamada et al. (2009), density estimates during 1998–2002 for Bryde's whales at 31–43ºN, 145–165ºE from Kitakado et al. (2008), and density estimates during 1994–2007 for blue, fin, humpback, and North Pacific right whales during at 31–51ºN, 140–170ºE from Matsuoka et al. (2009).

For four species (northern fur seal, Dall's porpoise, Pacific white-sided dolphin, northern right-whale dolphin), estimates of densities in the Shatsky Rise area are available from sightings data collected by observers in the high-seas driftnet fisheries during 1987–1990 (Buckland et al. 1993). Those data were analysed for 5° x 5° blocks, and the densities used here are from blocks for which available data overlap the proposed survey area. In general, those data represent the average annual density in the northern half of the Shatsky Rise survey area (35–40°N).

The densities mentioned above had been corrected by the original authors for detectability bias and, with the exception of Kitakado et al. 2008 and Hakamada et al. 2009, for availability bias. Detectability bias is associated with diminishing sightability with increasing lateral distance from the track line [$f(0)$]. Availability bias refers to the fact that there is <100% probability of sighting an animal that is present along the survey track line, and it is measured by $g(0)$.

There is some uncertainty about the representativeness of the density data and the assumptions used in the calculations. The available densities in Miyashita (1993a) and Buckland et al. (1993) are from the 1980s; although these densities represent the best available information for the Shatsky Rise area at present, they will be biased if abundance or distributions of those species have changed since the data were collected. Furthermore, the Shatsky Rise survey area represents a transitional zone across which many species migrate (north and south) during a given year; June–July is a period of high migration through the survey area. Therefore, there is uncertainty with respect to the expected marine mammal densities during this time. However, the approach used here is based on the best available data. To

Table 3. Densities of marine mammals from various sources (see text for rationale and details): Japanese sighting surveys in the western North Pacific, North Pacific driftnet fisheries observer coverage, and NMFS surveys offshore from Hawaii or the U.S. west coast. Species listed as endangered under the ESA are in italics. N.A. means not available.

	Density (#/1000 km^2)		
Species	**Density**	**CV[1]**	**Source**
Mysticetes			
North Pacific right whale	*0.06*	*N.A.*	*Western North Pacific[2]*
Humpback whale	*0.70*	*N.A.*	*Western North Pacific[2]*
Minke whale	2.72	0.58	Western North Pacific[3]
Bryde's whale	0.52	0.64	Western North Pacific[4]
Sei whale	*1.78*	*0.28*	*Western North Pacific[5]*
Fin whale	*1.08*	*N.A.*	*Western North Pacific[2]*
Blue whale	*0.58*	*N.A.*	*Western North Pacific[2]*
Odontocetes			
Sperm whale	*1.04*	*0.11*	*Western North Pacific[6]*
Pygmy sperm whale	7.82	0.74	Offshore Hawaii[7]
Dwarf sperm whale	3.19	1.12	Offshore Hawaii[7]
Cuvier's beaked whale	6.80	1.43	Offshore Hawaii[7]
Baird's beaked whale	0.88	0.37	CA/OR/WA[8]
Hubb's beaked whale	0.01	N.A.	N.A.
Longman's beaked whale	0.45	1.26	Offshore Hawaii[7]
Blainville's beaked whale	1.28	1.25	Offshore Hawaii[7]
Mesoplodon spp.[9]	0.01	N.A.	N.A.
Rough-toothed dolphin	3.89	0.45	Offshore Hawaii[7]
Bottlenose dolphin	23.99	0.34	Western North Pacific[10]
Pantropical spotted dolphin	70.41	0.19	Western North Pacific[10]
Spinner dolphin	1.50	0.74	Offshore Hawaii[7]
Striped dolphin	119.07	0.18	Western North Pacific[10]
Fraser's dolphin	4.57	1.16	Offshore Hawaii[7]
Short-beaked common dolphin	309.35	0.18	CA/OR/WA[8]
Pacific white-sided dolphin	36.40	N.A.	North Pacific[11]
Northern right whale dolphin	0.41	N.A.	North Pacific[11]
Risso's dolphin	10.8	0.27	Western North Pacific[10]
Melon-headed whale	1.32	1.17	Offshore Hawaii[7]
Pygmy killer whale	0.43	0.83	Offshore Hawaii[7]
False killer whale	2.05	0.34	Western North Pacific[10]
Killer whale	0.16	0.98	Offshore Hawaii[7]
Short-finned pilot whale	5.00	0.38	Western North Pacific[10]
Dall's porpoise	21.94	N.A.	North Pacific[11]
Pinnipeds			
Northern fur seal	1.79	N.A.	North Pacific[11]

[1]CV (Coefficient of Variation) is a measure of a number's variability, as given by the authors of the density documents. The larger the CV, the higher the variability.
[2] Matsuoka et al. (2009).
[3] Hakamada et al. (2009).
[4] Kitikado et al. (2008).
[5] Hakamada et al. (2004).
[6] Kato and Miyashita (1998).
[7] Barlow (2006).
[8] California/Oregon/Washington (Barlow and Forney 2007).
[9] Could include ginkgo-toothed, Stejneger's, or Hubb's beaked whales; density (N.A.) is an arbitrary low value.
[10] Miyashita (1993a).
[11] Buckland et al. (1993).

provide some allowance for these underlying uncertainties, "maximum estimates" as well as "best estimates" of the densities present and numbers of marine mammals potentially affected have been derived; maximum estimates are 1.5x the best estimates.

The estimated numbers of individuals potentially exposed are based on the 160-dB re 1 μPa_{rms} criterion for all cetaceans and the 170-dB re 1 μPa_{rms} criterion for delphinids, Dall's porpoise, and pinnipeds (Table 4). It is assumed that marine mammals exposed to airgun sounds that strong might change their behavior sufficiently to be considered "taken by harassment".

It should be noted that the following estimates of exposures to various sound levels assume that the surveys will be completed. As is typical during offshore ship surveys, inclement weather and equipment malfunctions are likely to cause delays and may limit the number of useful line-kilometers of seismic operations that can be undertaken. Furthermore, any marine mammal sightings within or near the designated exclusion zones will result in the power down or shut down of seismic operations as a mitigation measure. Thus, the following estimates of the numbers of marine mammals potentially exposed to sound levels of 160- or 170-dB re 1 μPa_{rms} are precautionary and probably overestimate the actual numbers of marine mammals that might be involved. These estimates assume that there will be no weather, equipment, or mitigation delays, which is highly unlikely.

(b) Potential Number of Marine Mammals Exposed to Airgun Sounds

Number of Cetaceans that could be Exposed to ≥160 dB.—The number of different individuals that could be exposed to airgun sounds with received levels ≥160 dB re 1 μPa_{rms} on one or more occasions can be estimated by considering the expected density of animals in the area along with the total marine area that would be within the 160-dB radius around the operating airgun array on at least one occasion. The number of possible exposures (including repeated exposures of the same individuals) can be estimated by considering the total marine area that would be within the 160-dB radius around the operating airguns, including areas of overlap. In the proposed survey, the majority of seismic lines are widely spaced in the survey area, so few individual mammals would be exposed numerous times during the survey; the area including overlap is only 1.1x the area excluding overlap. Moreover, it is unlikely that a particular animal would stay in the area during the entire survey.

The numbers of different individuals potentially exposed to ≥160 dB re 1 μPa_{rms} were calculated by multiplying

- the expected species density, either "mean" (i.e., best estimate) or "maximum", times
- the anticipated minimum area to be ensonified to that level during airgun operations including overlap (exposures), or
- the anticipated area to be ensonified to that level during airgun operations excluding overlap (individuals).

The area expected to be ensonified was determined by entering the planned survey lines into a MapInfo Geographic Information System (GIS), using the GIS to identify the relevant areas by "drawing" the applicable 160-dB (or, in the next subsection, 170-dB) buffer (see Table 1) around each seismic line, and then calculating the total area within the buffers. Areas of overlap were included only once when estimating the number of individuals exposed.

TABLE 4. Estimates of the possible numbers of marine mammals exposed to different sound levels during L-DEO's proposed seismic survey at Shatsky Rise during July–September 2010. The proposed sound source is a 36-airgun array with a discharge volume of ~6600 in³. Received levels of airgun sounds are expressed in dB re 1 µPa (rms, averaged over pulse duration), consistent with NMFS' practice. Not all marine mammals will change their behavior when exposed to these sound levels, but some may alter their behavior when levels are lower (see text). Delphinids, Dall's porpoise, and pinnipeds are unlikely to react to levels less than 170 dB. Species in italics are listed under the ESA as *endangered*.

Species	Number of *Exposures* to Sound Levels >160 dB (>170 db, Delphinids and Pinnipeds)				Number of *Individuals* Exposed to Sound Levels >160 dB (>170 dB, Delphinids and Pinnipeds)					Requested Take Authorization
					Best Estimate[1]					
	Best Estimate		Maximum Estimate		Number		% Regional	Maximum Estimate[1]		
North Pacific right whale	*1*		*2*		*1*		*0.60*	*2*		***1***
Humpback whale	*16*		*24*		*15*		*1.43*	*22*		***15***
Minke whale	62		92		57		0.23	85		**57**
Bryde's whale	12		18		11		0.05	16		**11**
Sei whale	*40*		*60*		*37*		*0.37*	*56*		***37***
Fin whale	*24*		*37*		*22*		*0.14*	*34*		***22***
Blue whale	*13*		*20*		*12*		*0.35*	*18*		***12***
Sperm whale	*24*		*35*		*22*		*0.07*	*32*		***22***
Pygmy sperm whale	72		108		66		<0.01	100		**66**
Dwarf sperm whale	177		265		163		<0.01	244		**163**
Cuvier's beaked whale	154		231		142		0.71	212		**142**
Baird's beaked whale	20		30		18		N.A.	27		**18**
Longman's beaked whale	10		15		9		N.A.	14		**9**
Blainville's beaked whale	29		43		27		0.11	40		**27**
Mesoplodon spp.[3]	2		3		2		0.01	3		***2***
Rough-toothed dolphin	71	(41)	106	(62)	65	(38)	0.04	97	(57)	**65**
Bottlenose dolphin	543	(317)	814	(476)	500	(293)	0.21	750	(440)	**500**
Pantropical spotted dolphin	1592	(932)	2388	(1397	1467	(860)	0.33	2200	(1290	**1467**
Spinner dolphin	19	(11)	28	(17)	17	(10)	<0.01	26	(15)	**17**
Striped dolphin	2693	(1575)	4039	(2363	2480	(1455	0.44	3721	(2182	**2480**
Fraser's dolphin	103	(60)	155	(91)	95	(56)	0.03	143	(84)	**95**
Short-beaked common	6996	(4093)	10,493	(6140	6444	(3780	0.22	9666	(5669	**6444**
Pacific white-sided dolphin	823	(482)	1235	(722)	758	(445)	0.08	1137	(667)	**758**
Northern right whale dolphin	9	(5)	14	(8)	9	(5)	<0.01	13	(8)	**9**
Risso's dolphin	244	(143)	366	(214)	225	(132)	0.03	337	(198)	**225**
Melon-headed whale	30	(17)	45	(26)	27	(16)	0.06	41	(24)	**27**
Pygmy killer whale	0		0		0		0.00	0		**0**
False killer whale	46	(27)	70	(41)	43	(25)	0.27	64	(38)	**43**
Killer whale	4	(2)	5	(3)	3	(2)	0.04	5	(3)	**3**
Short-finned pilot whale	113	(66)	170	(99)	104	(61)	0.20	156	(92)	**104**
Dall's porpoise	496	(290)	744	(435)	457	(268)	0.03	686	(402)	**457**
Northern fur seal	40	(24)	61	(36)	37	(22)	<0.01	56	(33)	**37**

[1] Best and maximum estimates are based on densities in Table 3. [2] Regional population size estimates are from Table 3; NA means not available. [3] Could include ginkgo-toothed, Stejneger's, or Hubb's beaked whales; density (not available) is an arbitrary low value.

Applying the approach described above, ~20,831 km^2 would be within the 160-dB isopleth on one or more occasions during the survey, whereas 22,614 km^2 is the area ensonified to ≥160 dB when overlap is included. Thus, an average individual marine mammal would be exposed only once during the survey. Because this approach does not allow for turnover in the mammal populations in the study area during the course of the survey, the actual number of individuals exposed could be underestimated. However, the approach assumes that no cetaceans will move away from or toward the trackline as the *Langseth* approaches in response to increasing sound levels prior to the time the levels reach 160 dB, which will result in overestimates for those species known to avoid seismic vessels (see § IV a).

Table 4 shows the best and maximum estimates of the number of exposures and the number of different individual cetaceans that potentially could be exposed to ≥160 dB re 1 μPa_{rms} during the seismic survey if no animals moved away from the survey vessel. The ***Requested Take Authorization***, given in the far right column of Table 4, is based on the best estimates rather than the maximum estimates of the numbers exposed, because there was little uncertainty associated with the method of estimating densities.

The 'best estimate' of the number of individual cetaceans that could be exposed to seismic sounds with received levels≥ 160 dB re 1 μPa_{rms} during the proposed survey is 13,299 (Table 4). That total includes 155 baleen whales, 87 of which are ***endangered***: 1 North Pacific right whale or 0.6% of the regional population; 15 humpback whales (1.4%), 37 sei whales (0.4%), 22 fin whales (0.1%), and 12 blue whales (0.4%) (Table 4).

In addition, 22 sperm whales (also listed as ***endangered under*** the ESA) or <0.1% of the regional population could be exposed during the survey, and 198 beaked whales including Cuvier's, Longman's, Baird's, Blainville's, and possibly ginkgo-toothed, Stejneger's, or Hubb's beaked whales (Table 4). Most (96%) of the cetaceans potentially exposed are delphinids; short-beaked common, striped, pantropical spotted, and Pacific white-sided dolphins and melon-headed whales are estimated to be the most common species in the area, with best estimates of 6444 (0.2% of the regional population), 2480 (0.4%), 1467 (0.3%), and 758 (0.1%) exposed to≥160 dB re 1 μPa_{rms}, respectively. However, a more meaningful estimate is the one for sound levels ≥170 dB (see below). The 'Maximum Estimate' column in Table 4 shows an estimated total of 19,948 cetaceans. Again, most of these consist of dolphins.

Number of Delphinids and Dall's Porpoise that could be Exposed to ≥170 dB.—The 160-dB criterion, on which the preceding estimates are based, was derived from studies of baleen whales. Odontocete hearing at low frequencies is relatively insensitive, and delphinids and Dall's porpoises generally appear to be more tolerant of strong low-frequency sounds than are many baleen whales. As summarized in Appendix B (5), delphinids commonly occur within distances where received levels would be expected to exceed 160 dB re 1 μPa_{rms}. There is no generally accepted alternative "take" criterion for delphinids exposed to airgun sounds. However, the estimates in this subsection assume that only those delphinids and Dall's porpoises exposed to≥170 dB re 1 μPa_{rms}, on average, would be affected sufficiently to be considered "taken by harassment". ("On average" means that some individuals might react significantly upon exposure to levels somewhat <170 dB, but others would not do so even upon exposure to levels somewhat >170 dB.)

The best and maximum estimates of the numbers of individual delphinids that could be exposed to ≥170 dB during the survey are 7178 and 10,767, respectively (Table 4). The best and maximum estimates of the numbers of individual Dall's porpoise that could be exposed to ≥170 dB during the survey are 268 and 402, respectively (Table 4). These values are based on the predicted 170-dB radius around the airgun

array to be used during the study, and are considered to be more realistic estimates of the number of individuals that could be affected.

Number of Pinnipeds that might be Exposed to ≥160 dB and ≥170 dB.—The only pinniped species that could occur in the offshore waters of the survey area is the northern fur seal. As summarized in § IV(1)(a) and Appendix B, some studies suggest that most pinnipeds, like delphinids, may be less sensitive to airgun sounds than mysticetes. Thus, the numbers of pinnipeds likely to be exposed to received levels ≥170 dB re 1 μPa_{rms} were also calculated.

The methods described previously for cetaceans were also used to calculate the numbers of individual northern fur seals that may be exposed during the survey. Based on the best estimate, ~37 northern fur seals could be exposed to airgun sounds ≥160 dB re 1 μPa_{rms}. Based on the 170-dB criterion, 22 northern fur seals could be exposed (Table 4).

The 'Maximum Estimate' column in Table 4 shows an estimated 56 northern fur seals that could be exposed to airgun sounds ≥160 dB re 1 μPa_{rms} during the survey. The numbers for which "take authorization" is requested, given in the far right column of Table 4, are for the best estimate.

(4) Conclusions for Marine Mammals and Sea Turtles

The proposed seismic survey will involve towing an airgun array that introduces pulsed sounds into the ocean, along with simultaneous operation of an MBES and SBP. The survey will employ a 36-airgun array similar to the airgun arrays used for typical high-energy seismic surveys. The total airgun discharge volume is ~6600 in^3. Routine vessel operations, other than the proposed airgun operations, are conventionally assumed not to affect marine mammals sufficiently to constitute "taking". No "taking" of marine mammals is expected in association with echosounder operations given the considerations discussed in §IV(1)(b and c), i.e., sounds are beamed downward, the beam is narrow, and the pulses are extremely short.

(a) Cetaceans

Several species of mysticetes show strong avoidance reactions to seismic vessels at ranges up to 6–8 km and occasionally as far as 20–30 km from the source vessel when medium-large airgun arrays have been used. However, reactions at the longer distances appear to be atypical of most species and situations. If mysticetes are encountered, the numbers estimated to occur within the 160-dB isopleth in the survey area are expected to be relatively low.

Odontocete reactions to seismic pulses, or at least the reactions of delphinids and Dall's porpoise, are expected to extend to lesser distances than are those of mysticetes. Odontocete low-frequency hearing is less sensitive than that of mysticetes, and dolphins are often seen from seismic vessels. In fact, there are documented instances of dolphins approaching active seismic vessels. However, delphinids (along with other cetaceans) sometimes show avoidance responses and/or other changes in behavior when near operating seismic vessels.

Taking into account the mitigation measures that are planned (see § II), effects on cetaceans are generally expected to be limited to avoidance of the area around the seismic operation and short-term changes in behavior, falling within the MMPA definition of "Level B harassment".

Varying estimates of the numbers of marine mammals that might be exposed to strong airgun sounds during the proposed program have been presented, depending on the specific exposure criteria (≥160 or ≥170 dB) and density criterion used (best or maximum). The requested "take authorization" for

each species is based on the best estimate of the number of individuals that could be exposed to ≥160 dB re 1 μPa_{rms}. Those figures likely overestimate the actual number of animals that will be exposed to and will react to the seismic sounds. The reasons for that conclusion are outlined above. The relatively short-term exposures are unlikely to result in any long-term negative consequences for the individuals or their populations.

The many cases of apparent tolerance by cetaceans of seismic exploration, vessel traffic, and some other human activities show that co-existence is possible. Mitigation measures such as look outs, ramp ups, and power downs or shut downs when marine mammals are seen within defined ranges, as well as special mitigation measures for right whales, should further reduce short-term reactions, and avoid or minimize any effects on hearing sensitivity. In all cases, the effects are expected to be short-term, with no lasting biological consequence.

(b) Pinnipeds

Only one pinniped species—the northern fur seal—is likely to occur in the offshore waters of the survey area. A best estimate of 37 northern fur seals could be exposed to airgun sounds with received levels ≥160 dB re 1 μPa_{rms}. As for cetaceans, the estimated numbers of pinnipeds that may be exposed to received levels ≥160 dB are probably overestimates of the actual numbers that will be affected significantly. Any effects are expected to be short-term, with no lasting biological consequence.

(c) Sea Turtles

The proposed activity will occur at least ~1200 km from sea turtle nesting beaches in Japan. Loggerheads, leatherbacks, and green turtles are known to nest in Japan. In the Shatsky Rise study area, loggerheads are most likely to be encountered during the survey. However, at the time of the survey, loggerheads are nesting on Okinawa and adjacent islands of the central Ryukyus, Japan; peak nesting occurs in July. Thus, nesting females would be nearshore or on land far from the survey area at the time of the survey. However, migrating or foraging sea turtles could be encountered in the deep waters of the survey area at any time of year. With the implementation of mitigation measures, it is anticipated that the proposed seismic survey will have, at most, a short-term effect on behavior and no long-term impacts on individual sea turtles or their populations.

(5) Direct Effects on Fish and Their Significance

One reason for the adoption of airguns as the standard energy source for marine seismic surveys is that, unlike explosives, they have not been associated with large-scale fish kills. However, existing information on the impacts of seismic surveys on marine fish populations is limited (see Appendix D). There are three types of potential effects of exposure to seismic surveys: (1) pathological, (2) physiological, and (3) behavioral. Pathological effects involve lethal and temporary or permanent sub-lethal injury. Physiological effects involve temporary and permanent primary and secondary stress responses, such as changes in levels of enzymes and proteins. Behavioral effects refer to temporary and (if they occur) permanent changes in exhibited behavior (e.g., startle and avoidance behavior). The three categories are interrelated in complex ways. For example, it is possible that certain physiological and behavioral changes could potentially lead to an ultimate pathological effect on individuals (i.e., mortality).

The specific received sound levels at which permanent adverse effects to fish potentially could occur are little studied and largely unknown. Furthermore, the available information on the impacts of seismic surveys on marine fish is from studies of individuals or portions of a population; there have been no studies at the population scale. The studies of individual fish have often been on caged fish that were

exposed to airgun pulses in situations not representative of an actual seismic survey. Thus, available information provides limited insight on possible real-world effects at the ocean or population scale. This makes drawing conclusions about impacts on fish problematic because, ultimately, the most important issues concern effects on marine fish populations, their viability, and their availability to fisheries.

Hastings and Popper (2005), Popper 2009, and Popper and Hastings (2009a,b) provided recent critical reviews of the known effects of sound on fish. The following sections provide a general synopsis of the available information on the effects of exposure to seismic and other anthropogenic sound as relevant to fish. The information comprises results from scientific studies of varying degrees of rigor plus some anecdotal information. Some of the data sources may have serious shortcomings in methods, analysis, interpretation, and reproducibility that must be considered when interpreting their results (see Hastings and Popper 2005). Potential adverse effects of the program's sound sources on marine fish are then noted.

(a) Pathological Effects

The potential for pathological damage to hearing structures in fish depends on the energy level of the received sound and the physiology and hearing capability of the species in question (see Appendix D). For a given sound to result in hearing loss, the sound must exceed, by some substantial amount, the hearing threshold of the fish for that sound (Popper 2005). The consequences of temporary or permanent hearing loss in individual fish on a fish population are unknown; however, they likely depend on the number of individuals affected and whether critical behaviors involving sound (e.g., predator avoidance, prey capture, orientation and navigation, reproduction, etc.) are adversely affected.

Little is known about the mechanisms and characteristics of damage to fish that may be inflicted by exposure to seismic survey sounds. Few data have been presented in the peer-reviewed scientific literature. As far as we know, there are only two papers with proper experimental methods, controls, and careful pathological investigation implicating sounds produced by actual seismic survey airguns in causing adverse anatomical effects. One such study indicated anatomical damage, and the second indicated TTS in fish hearing. The anatomical case is McCauley et al. (2003), who found that exposure to airgun sound caused observable anatomical damage to the auditory maculae of "pink snapper" (*Pagrus auratus*). This damage in the ears had not been repaired in fish sacrificed and examined almost two months after exposure. On the other hand, Popper et al. (2005) documented only TTS (as determined by auditory brainstem response) in two of three fish species from the Mackenzie River Delta. This study found that broad whitefish (*Coregonus nasus*) that received a sound exposure level of 177 dB re 1 $\mu Pa^2 \cdot s$ showed no hearing loss. During both studies, the repetitive exposure to sound was greater than would have occurred during a typical seismic survey. However, the substantial low-frequency energy produced by the airguns [less than ~400 Hz in the study by McCauley et al. (2003) and less than ~200 Hz in Popper et al. (2005)] likely did not propagate to the fish because the water in the study areas was very shallow (~9 m in the former case and <2 m in the latter). Water depth sets a lower limit on the lowest sound frequency that will propagate (the "cutoff frequency") at about one-quarter wavelength (Urick 1983; Rogers and Cox 1988).

Wardle et al. (2001) suggested that in water, acute injury and death of organisms exposed to seismic energy depends primarily on two features of the sound source: (1) the received peak pressure and (2) the time required for the pressure to rise and decay. Generally, as received pressure increases, the period for the pressure to rise and decay decreases, and the chance of acute pathological effects increases. According to Buchanan et al. (2004), for the types of seismic airguns and arrays involved with the proposed program, the pathological (mortality) zone for fish would be expected to be within a few meters of the seismic source. Numerous other studies provide examples of no fish mortality upon exposure to

seismic sources (Falk and Lawrence 1973; Holliday et al. 1987; La Bella et al. 1996; Santulli et al. 1999; McCauley et al. 2000a,b, 2003; Bjarti 2002; Thomsen 2002; Hassel et al. 2003; Popper et al. 2005; Boeger et al. 2006).

Some studies have reported, some equivocally, that mortality of fish, fish eggs, or larvae can occur close to seismic sources (Kostyuchenko 1973; Dalen and Knutsen 1986; Booman et al. 1996; Dalen et al. 1996). Some of the reports claimed seismic effects from treatments quite different from actual seismic survey sounds or even reasonable surrogates. However, Payne et al. (2009) reported no statistical differences in mortality/morbidity between control and exposed groups of capelin eggs or monkfish larvae. Saetre and Ona (1996) applied a 'worst-case scenario' mathematical model to investigate the effects of seismic energy on fish eggs and larvae. They concluded that mortality rates caused by exposure to seismic surveys are so low, as compared to natural mortality rates, that the impact of seismic surveying on recruitment to a fish stock must be regarded as insignificant.

(b) Physiological Effects

Physiological effects refer to cellular and/or biochemical responses of fish to acoustic stress. Such stress potentially could affect fish populations by increasing mortality or reducing reproductive success. Primary and secondary stress responses of fish after exposure to seismic survey sound appear to be temporary in all studies done to date (Sverdrup et al. 1994; Santulli et al. 1999; McCauley et al. 2000a,b). The periods necessary for the biochemical changes to return to normal are variable and depend on numerous aspects of the biology of the species and of the sound stimulus (see Appendix D).

(c) Behavioral Effects

Behavioral effects include changes in the distribution, migration, mating, and catchability of fish populations. Studies investigating the possible effects of sound (including seismic survey sound) on fish behavior have been conducted on both uncaged and caged individuals (e.g., Chapman and Hawkins 1969; Pearson et al. 1992; Santulli et al. 1999; Wardle et al. 2001; Hassel et al. 2003). Typically, in these studies fish exhibited a sharp "startle" response at the onset of a sound followed by habituation and a return to normal behavior after the sound ceased.

There is general concern about potential adverse effects of seismic operations on fisheries, namely a potential reduction in the "catchability" of fish involved in fisheries. Although reduced catch rates have been observed in some marine fisheries during seismic testing, in a number of cases the findings are confounded by other sources of disturbance (Dalen and Raknes 1985; Dalen and Knutsen 1986; Løkkeborg 1991; Skalski et al. 1992; Engås et al. 1996). In other airgun experiments, there was no change in catch per unit effort (CPUE) of fish when airgun pulses were emitted, particularly in the immediate vicinity of the seismic survey (Pickett et al. 1994; La Bella et al. 1996). For some species, reductions in catch may have resulted from a change in behavior of the fish, e.g., a change in vertical or horizontal distribution, as reported in Slotte et al. (2004).

In general, any adverse effects on fish behavior or fisheries attributable to seismic testing may depend on the species in question and the nature of the fishery (season, duration, fishing method). They may also depend on the age of the fish, its motivational state, its size, and numerous other factors that are difficult, if not impossible, to quantify at this point, given such limited data on effects of airguns on fish, particularly under realistic at-sea conditions.

(6) Direct Effects on Invertebrates and Their Significance

(a) Seismic operations

The existing body of information on the impacts of seismic survey sound on marine invertebrates is very limited. However, there is some unpublished and very limited evidence of the potential for adverse effects on invertebrates, thereby justifying further discussion and analysis of this issue. The three types of potential effects of exposure to seismic surveys on marine invertebrates are pathological, physiological, and behavioral. Based on the physical structure of their sensory organs, marine invertebrates appear to be specialized to respond to particle displacement components of an impinging sound field and not to the pressure component (Popper et al. 2001; see also Appendix E).

The only information available on the impacts of seismic surveys on marine invertebrates involves studies of individuals; there have been no studies at the population scale. Thus, available information provides limited insight on possible real-world effects at the regional or ocean scale. The most important aspect of potential impacts concerns how exposure to seismic survey sound ultimately affects invertebrate populations and their viability, including availability to fisheries.

Literature reviews of the effects of seismic and other underwater sound on invertebrates were provided by Moriyasu et al. (2004) and Payne et al. (2008). The following sections provide a synopsis of available information on the effects of exposure to seismic survey sound on species of decapod crustaceans and cephalopods, the two taxonomic groups of invertebrates on which most such studies have been conducted. The available information is from studies with variable degrees of scientific soundness and from anecdotal information. A more detailed review of the literature on the effects of seismic survey sound on invertebrates is provided in Appendix E.

Pathological Effects.—In water, lethal and sub-lethal injury to organisms exposed to seismic survey sound appears to depend on at least two features of the sound source: (1) the received peak pressure, and (2) the time required for the pressure to rise and decay. Generally, as received pressure increases, the period for the pressure to rise and decay decreases, and the chance of acute pathological effects increases. For the type of airgun array planned for the proposed program, the pathological (mortality) zone for crustaceans and cephalopods is expected to be within a few meters of the seismic source, at most; however, very few specific data are available on levels of seismic signals that might damage these animals. This premise is based on the peak pressure and rise/decay time characteristics of seismic airgun arrays currently in use around the world.

Some studies have suggested that seismic survey sound has a limited pathological impact on early developmental stages of crustaceans (Pearson et al. 1994; Christian et al. 2003; DFO 2004). However, the impacts appear to be either temporary or insignificant compared to what occurs under natural conditions. Controlled field experiments on adult crustaceans (Christian et al. 2003, 2004; DFO 2004) and adult cephalopods (McCauley et al. 2000a,b) exposed to seismic survey sound have not resulted in any significant pathological impacts on the animals. It has been suggested that exposure to commercial seismic survey activities has injured giant squid (Guerra et al. 2004), but there is no evidence to support such claims.

Physiological Effects.—Physiological effects refer mainly to biochemical responses by marine invertebrates to acoustic stress. Such stress potentially could affect invertebrate populations by increasing mortality or reducing reproductive success. Primary and secondary stress responses (i.e., changes in haemolymph levels of enzymes, proteins, etc.) of crustaceans have been noted several days or months after exposure to seismic survey sounds (Payne et al. 2007). The periods necessary for these biochemical

changes to return to normal are variable and depend on numerous aspects of the biology of the species and of the sound stimulus.

Behavioral Effects.—There is increasing interest in assessing the possible direct and indirect effects of seismic and other sounds on invertebrate behavior, particularly in relation to the consequences for fisheries. Changes in behavior could potentially affect such aspects as reproductive success, distribution, susceptibility to predation, and catchability by fisheries. Studies investigating the possible behavioral effects of exposure to seismic survey sound on crustaceans and cephalopods have been conducted on both uncaged and caged animals. In some cases, invertebrates exhibited startle responses (e.g., squid in McCauley et al. 2000a,b). In other cases, no behavioral impacts were noted (e.g., crustaceans in Christian et al. 2003, 2004; DFO 2004). There have been anecdotal reports of reduced catch rates of shrimp shortly after exposure to seismic surveys; however, other studies have not observed any significant changes in shrimp catch rate (Andriguetto-Filho et al. 2005). Similarly, Parry and Gason (2006) did not find any evidence that lobster catch rates were affected by seismic surveys. Any adverse effects on crustacean and cephalopod behavior or fisheries attributable to seismic survey sound depend on the species in question and the nature of the fishery (season, duration, fishing method).

(b) OBS deployment

A total of ~28 OBSs will be deployed during the study. WHOI "D2" OBSs will be used; this type of OBS has a height of ~1 m and a maximum diameter of 50 cm. The anchor is made of hot-rolled steel and weighs 23 kg. The anchor dimensions are 2.5 × 30.5 × 38.1 cm. OBS anchors will be left behind upon equipment recovery. Although OBS placement will disrupt a very small area of seafloor habitat and could disturb benthic invertebrates, the impacts are expected to be localized and transitory.

(7) Direct Effects on Seabirds and Their Significance

Investigations into the effects of airguns on seabirds are extremely limited. Stemp (1985) conducted opportunistic observations on the effects of seismic exploration on seabirds, and Lacroix et al. (2003) investigated the effect of seismic surveys on molting long-tailed ducks in the Beaufort Sea, Alaska. Stemp (1985) did not observe any effects of seismic testing, although he warned that his observations should not be extrapolated to areas with large concentrations of feeding or molting birds. In a more intensive and directed study, Lacroix et al. (2003) did not detect any effects of nearshore seismic exploration on molting long-tailed ducks in the inshore lagoon systems of Alaska's North Slope. Both aerial surveys and radio-tracking indicated that the proportion of ducks that stayed near their marking location from before to after seismic exploration was unaffected by proximity to seismic survey activities. Seismic activity also did not appear to change the diving intensity of long-tailed ducks significantly.

Birds might be affected slightly by seismic sounds from the proposed study, but the impacts are not expected to be significant to individual birds or their populations. The types of impacts that are possible are summarized below:

Localized, temporary displacement and disruption of feeding.—Such displacements would be similar to those caused by other large vessels that passed through the area. Any adverse effects would be negligible.

Modified prey abundance.—It is unlikely that prey species for birds will be affected by seismic activities to a degree that affects the foraging success of birds. If prey species exhibit avoidance of the ship, the avoidance is expected to be transitory and limited to a very small portion of a bird's foraging range.

Disturbance to breeding birds.—A vessel (seismic or otherwise) that approaches too close to a breeding colony could disturb adult birds from nests in response to sonic or visual stimuli. There is little potential for this during the proposed survey, because the seismic vessel will be at least 1200 km from land.

Egg and nestling mortality.—Disturbance of adult birds from nests can lead to egg or nestling mortality *via* temperature stress or predation. There is no potential for this considering the distance that the seismic survey will occur from land.

Chance injury or mortality.—Many species of marine birds feed by diving to depths of several meters or more. Flocks of feeding birds may consist of hundreds or even thousands of individuals. Also, some species of seabirds (particularly alcids) escape from boats by diving when the boat gets too close. It is possible that, during the course of normal feeding or escape behavior, some birds could be near enough to an airgun to be injured by a pulse. Although no specific information is available about the circumstances (if any) where this might occur, the negligible aversive reactions of birds to airguns (see above) suggest that a bird would have to be very close to any airgun to receive a pulse with sufficient energy to cause injury, if that is possible at all.

Induced injury or mortality.—If it disorients, injures, or kills prey species, or otherwise increases the availability of prey species to marine birds, a seismic survey could attract birds. Birds drawn too close to an airgun may be at risk of injury. However, available evidence from other seismic surveys utilizing airguns has not shown a pattern of fish (or other prey) kills from airguns [see § IV(5), above]. Thus, the potential that birds would be attracted and subsequently injured by the proposed seismic survey appears very low.

(8) Indirect Effects on Marine Mammals, Sea Turtles, and Their Significance

The proposed airgun operations will not result in any permanent impact on habitats used by marine mammals or sea turtles, or to the food sources they use. The main impact issue associated with the proposed activities will be temporarily elevated noise levels and the associated direct effects on marine mammals and sea turtles, as discussed above.

During the seismic study, only a small fraction of the available habitat would be ensonified at any given time. Disturbance to fish species and invertebrates would be short-term, and fish would return to their pre-disturbance behavior once the seismic activity ceased [see § IV(5) and § IV(6), above]. Thus, the proposed survey would have little impact on the abilities of marine mammals or sea turtles to feed in the area where seismic work is planned.

Some mysticetes feed on concentrations of zooplankton. A reaction by zooplankton to a seismic impulse would only be relevant to whales if it caused a concentration of zooplankton to scatter. Pressure changes of sufficient magnitude to cause that type of reaction would probably occur only very close to the source. Impacts on zooplankton behavior are predicted to be negligible, and that would translate into negligible impacts on those mysticetes that feed on zooplankton.

(9) Cumulative Effects

Cumulative effects refer to the impacts on the environment that result from a combination of past, existing, and reasonably foreseeable projects and human activities. Causal agents of cumulative effects can include multiple causes, multiple effects, effects of activities in more than one locale, and recurring events. Human activities, when conducted separately or in combination with other activities, could affect

marine mammals and sea turtles in the Shatsky Rise study area. However, understanding the cumulative effects for marine mammals and sea turtles is complex because of the animals' extensive habitat ranges, and the difficulty in monitoring populations and determining the level of impacts that may result from certain activities. For example, to consider all possible stressors on loggerhead turtles we may need to consider all human activity throughout their feeding and migratory ranges (from the coasts of Baja California and Hawaii to Asia and the high seas in between). Instead, here we focus on activities that could impact animals specifically in the region of Shatsky Rise (i.e., vessel traffic, fishing, and whaling and harvesting).

(a) Vessel noise, collisions, entanglement in equipment

Noise from large vessels generally dominates ambient noise at frequencies from 20 to 300 Hz (Richardson et al. 1995). Baleen whales are thought to be more sensitive to sound at these low frequencies than are toothed whales, possibly causing localized avoidance by marine mammals of the study area during seismic operations. Vessel traffic in the proposed study area will generally consist of commercial fishing vessels and potentially other large commercial (cargo) ships.

Many odontocetes show considerable tolerance of vessel traffic, although they sometimes react at long distances if confined by ice or shallow water (not factors in the study area), if previously harassed by vessels, or have had little or no recent exposure to ships (Richardson et al. 1995). Dolphins of many species tolerate and sometimes approach vessels. Some dolphin species approach moving vessels to ride the bow or stern waves (Williams et al. 1992). In Western Australia, bottlenose dolphin behavior became more erratic and dolphin schools tightened in response to controlled boat interactions (Bejder et al. 2006). During vessel interactions with bottlenose dolphins in New Zealand, travelling behavior increased and resting behavior decreased (Lusseau 2003, 2004). Also, dolphins apparently avoided areas and times characterized by high vessel traffic (Lusseau 2005). Common dolphins in New Zealand have also reacted to boats with changes in their overall behavioral budget, including decreases in foraging and resting times and increases in socializing and milling behavior (Stockin et al. 2008). Killer whales rarely show avoidance to boats within 400 m (Duffus and Dearden 1993), but when more than one boat is nearby, they sometimes swim faster towards less confined waters (Kruse 1991; Williams et al. 2002a,b). Killer whales have also been shown to increase travelling and decrease foraging behavior because of the presence of nearby vessels (Williams et al. 2002a,b; Lusseau et al. 2009; Noren et al. 2009).

Sperm whales can often be approached with small motorized or sailing vessels (Papastavrou et al. 1989), but sometimes avoid outboard-powered whale watching vessels up to 2 km away (J. McGibbon *in* Cawthorn 1992). Resident sperm whales that are repeatedly exposed to small vessels show subtle changes in various measures of behavior, and transient individuals (which presumably have less exposure to vessels) react more strongly (Richter et al. 2003, 2006). There are few data on the behavioral reactions of beaked whales to vessel noise, though they seem to avoid approaching vessels (e.g., Würsig et al. 1998) or dive for an extended period when approached by a vessel (e.g., Kasuya 1986). Based on a single observation, Aguilar-Soto et al. (2006) suggest foraging efficiency of Cuvier's beaked whales may be reduced by close approach of vessels.

Reactions of humpback whales to boats are variable, ranging from approach to avoidance (Payne 1978; Salden 1993). In southeast Alaska, concern was raised that increasing vessel traffic in Glacier Bay National Park may have caused humpbacks to leave the bay, particularly early in 1978 (Jurasz and Jurasz 1979). A subsequent detailed study confirmed that humpbacks often move away when vessels are within several km (Baker et al. 1982, 1983; Baker and Herman 1989), although reactions of humpbacks vary considerably. Humpbacks seem less likely to react overtly when actively feeding than when resting

or engaged in other activities (Krieger and Wing 1984, 1986). More recent studies of humpback whale responses to approaching vessels have been carried out on breeding grounds. Off the coast of mainland Ecuador, humpback whales were found to react to the approach of whale-watching boats by increasing swim speeds significantly (Scheidat et al. 2004), and behavioral responses including abrupt course changes and long dive times have also been reported for humpback whales in Hawaiian waters (Green 1998 *in* Nowacek et al. 2007). There is limited information available about the reactions of rorquals to vessels, but in general, cetacean reactions to vessels are varied. Some researchers suggest that vessel disturbances can lead to biologically-significant effects with long-term consequences for individuals or populations (see Lusseau and Bejder 2007), and urge that management schemes be established for populations with multiple potential stressors (e.g., Higham et al. 2009).

Another concern with vessel traffic is the potential for striking marine mammals. Jensen and Silber (2004) assembled a database of whale strikes reported throughout the world. Of the 292 records of confirmed or possible ship strikes to large whales, most were reported in North America, but this may be an artifact of data collection procedures and/or decreased reporting in other global jurisdictions. Two were reported for offshore Japan (Jensen and Silber 2004). The probability of a ship strike resulting in a lethal injury (mortality or severe injury) of a large cetacean increases with ship speed (Laist et al. 2001; Vanderlaan and Taggart 2007). Most lethal and severe injuries to large whales occurr when vessels travel at 14 kt or faster, and the probability of severe or lethal injury to a whale approaches 100% in the event of a direct strike when a ship is traveling faster than 15 kt (Laist et al. 2001; Vanderlaan and Taggart 2007). The probability of a ship strike is a function of vessel density, animal density, and vessel speed. Vessel and animal density (particularly of baleen whales) are expected to be relatively low at Shatsky Rise. In addition, given the slow speed of the seismic vessel (~4 kt), the probability of injurious or fatal strikes with mammals during the proposed operations is considered to be low.

Direct physical effects to sea turtles during seismic operations could include ship collisions and entanglement with seismic gear. Vessels traveling at speeds >4 km/h are more likely to collide with turtles at sea, which can result in turtle injury or death (Hazel et al. 2007). Large species like leatherbacks that spend extended periods near the surface are particularly susceptible to ship strikes. Because the prevalence of ship strikes are a function of vessel density and turtle density—both of which will be low at Shatsky Rise—the probability of collision during the seismic survey is expected to be low. Ship-turtle collisions are more likely in coastal areas where boat traffic is high and during nesting seasons when turtles aggregate.

Entanglement of sea turtles in seismic gear is also a concern; there have been reports of turtles being trapped and killed between the gaps in tail-buoys offshore of West Africa (Weir 2007). Again, the probability of entanglements will be a function of turtle density in the study area, which is expected to be low. Towing of hydrophone streamers or other equipment is not expected to significantly interfere with sea turtle movements, including migration, unless they were to become entrapped as indicated above.

(b) Fisheries

Commercial fishing activities have the potential to affect marine mammals and turtles by reducing prey availability or accidentally entangling or hooking individual animals (Cheng and Chen 1997; Smith et al. 2003; Reeves et al. 2003). In the offshore waters of the Northwest Pacific Ocean, tuna is the primary fishery. The Western and Central Pacific Fisheries Commission (WCPFC) regulates this fishery. Tuna are caught using longlines, pole-and-line, purse seines, and trolls. Japanese longliners land albacore, bigeye, and yellowfin in the WCPFC region (Lawson 2008). In recent years, the majority of the catch by Japanese longliners in the WCPFC consisted of bigeye tuna (Lawson 2008). The number of

distant water and offshore longline vessels have decreased over the years in the WCPFC region, from 973 in 1970 to 401 in 2006 (Lawson 2008). Similarly, the catch has decreased steadily, from ~160,000 t in 1980 to ~40,000 t in 2006 (Lawson 2008). In contrast, the Japanese purse-seine fishery, which mainly targets skipjack, has continued to grow since the early 1970s; the total catch for 2006 was ~253,000 t (Lawson 2008). The Japanese pole-and-line catch also consists primarily of skipjack; the catch has leveled off since 1990 at ~150,000 t annually (Lawson 2008). In 2007, a total of ~2.4 million t of tuna were taken in the WCPFC region; by country, Japan took the largest catch or 20% of that total (Lawson 2008).

In the Shatsky Rise area, most fishing effort takes place by Japan, although some longliners are from Vanuatu and possibly China (Lawson 2008). Wihin or near the study area, Japanese longliners landed mostly bigeye, followed by albacore tuna in 2006; the Vanuatu longliner catch in 2007 consisted only of albacore tuna (Lawson 2008). Albacore tuna and skipjack were landed by pole-and-line methods by Japanese vessels in 2006; in 2007, Japanese purse-seiners landed mainly skipjack to the west of the study area (Lawson 2008).

(c) Bycatch

Bycatch has been recognized as a significant cause of cetacean mortality for the past 30 to 40 years since the worldwide proliferation of synthetic gill nets (Reeves et al. 2003). There is also concern over the potential effects of trawl and longline activities on cetaceans. In many cases, cetacean bycatch is regarded by fishermen as a nuisance since time and effort are required to free animals from nets and resulting damage to equipment. Bycatch is often discarded at seam, although some animals are reported simply as bycatch to government agencies and then sold at markets. Baker et al. (2006) reported inconsistencies when studying mitochondrial DNA from samples of cetacean products at markets in Korea; in 2003, three of eight species identified in markets were not reported, and five of 11 species were not recorded in 2004. This suggests poor record keeping or illegal harvesting.

The level of impacts to cetaceans from entanglement and bycatch and how these impacts may affect populations are unknown. In Japan, up to 130 minke whales are 'incidentally' taken in the trap-net fishery; other baleen whales and small cetaceans are also taken occasionally. Parsons and Jefferson (2000) reported eight of 64 cetaceans examined post-mortem from the waters near Hong Kong exhibited wounds consistent with fisheries bycatch suggesting possible high incidence of cetacean interaction with fishing gear. Off the east coast of Taiwan, entanglement of marine mammals in drift gillnets occurs frequently (Perrin et al. 2005); between 27,000 and 41,000 cetaceans are thought to be taken incidentally by fisheries each year. The critically endangered Western North Pacific gray whale also experiences mortality from entrapment or entanglement in fishing gear. In recent years, there have been several mortalities of gray whales undergoing migration due to coastal net fisheries, particularly off Japan (Weller et al. 2008). It is unknown how fishing activities affect cetaceans in the offshore Shatsky Rise region.

Incidental capture in commercial fishing gear is also a major threat to sea turtles throughout the Pacific Ocean, including coastal waters of southeast Asia (Frazier et al. 1998), offshore of Hawaii (Skillman and Balazs 1992; Polovina et al. 2000), and the Kuroshio Extension (Lewison et al. 2004; Yokota et al. 2006). Prior to the North Pacific drift net fishery moratorium, as many as 4000 loggerheads were taken annually in the North Pacific, and 16,000 turtles of all species in the west Pacific (Bowen et al. 1995). Currently, longline fisheries are a significant threat to leatherbacks and loggerheads in the North Pacific and in the warm water masses of the Kuroshio Extension (Polovina et al. 2000; Lewison et al. 2004; Kaplan 2005; Yokota et al. 2006). In 2002, 2003, and 2004, only loggerheads were caught in the

Kuroshio Extension by the longliners (Yokota et al. 2006). Lewison et al. (2004) estimated that 30,000 to 75,000 loggerheads are bycaught in longlines in 2000 in the Pacific; although the estimate for leatherbacks was lower (20,000 to 40,000).

Nishimura and Nakahigashi (1990) estimated that Japanese research and training vessels captured over 21,200 turtles historically in the western Pacific and South China Sea, of which an estimated 12,296 were killed. Of 395 loggerhead turtles tagged while nesting on Senri Beach in Japan between 1990 and 1995, two were captured by trawler nets in the East China Sea, and seven were captured by set-nets along the coast of Japan (Sato et al. 1997). Set-net fisheries have been the main source of coastal fisheries bycatch in Taiwan, where most turtles caught incidentally were once slaughtered or sold (now they are usually released back into the sea; Chan et al. 2007).

(d) Whaling and Harvesting

Whaling and harvesting directly impacts cetacean and turtle populations. Whales and small cetaceans have been hunted for centuries in the western North Pacific. Legal harvesting of cetaceans still occurs in Japan and Russia (Rudolph and Smeenk 2002). Japan joined the IWC in 1951, and currently conducts whaling under scientific permit; the former USSR (now Russian Federation) joined in 1948 and is engaged in aboriginal subsistence whaling. China and Korea are also members of the IWC.

In Japan, the fishery for cetaceans includes small-type whaling, drive fishery for dolphins, and hand harpoon fishery for dolphins and porpoises (Kasuya 2002b, 2007). Currently, five small-type whaling vessels are in operation in Japan with annual quotas of 62 Baird's beaked whales, 100 short-finned pilot whales, and 20 Risso's dolphins (Kasuya 2007). Drive fisheries for six different dolphin species still occur on the Izu and Kii coasts; the quota is ~3000 dolphins (Kasuya 2002b, 2007). Dolphins and porpoises are also taken in harpoon fisheries; currently ~400 vessels of Hokkaido, Sanriku, Boso, Kii, and Okinawa are in operation (Kasuya 2002b). The quotas for the drive and harpoon fisheries are 17,700 Dall's porpoises, 1300 Risso's dolphins, 1100 bottlenose dolphins, 950 pantropical spotted dolphins, 500 short-finned pilot whales, and 50 false killer whales (Kasuya 2007).

Although the IWC banned commercial whaling in 1985/1986, Japan still conducts large-type whaling. In 1986/87, under the objection of the IWC, Japan took minke, sperm, and Bryde's whales in Japanese waters, totaling 513 whales in coastal areas and 315 Bryde's whales in the Bonin Islands; similar numbers were taken in 1987/88 (IWC 2008). The USSR and Japan also conducted whaling for minkes in the Antarctic in 1985/86 and 1986/87 (IWC 2008). The Japan Institute of Cetacean Research (ICR) started whaling for scientific purposes in the 1987/1988 Antarctic season and in 1994 in the North Pacific (Kasuya 2002b; IWC 2008). In the North Pacific, the catches of minkes has increased from 21 in 1994 to 208 in 2007 (IWC 2008). Since 2000, annual catches have also included up to 101 sei, 51 Bryde's, and 10 sperm whales (IWC 2008). Up to 62 Baird's beaked whales are also taken annually (Kasuya 2007). In 1986, the Republic of Korea also took 69 minke whales in the North Pacific under a 'scientific' permit (IWC 2008). No commercial whaling has taken place in Russia since the moratorium; however, aboriginal subsistence whaling for eastern North Pacific gray whales still continues in the North Pacific by natives of Chukotka, Russia. Catch limits are imposed by the IWC (2008).

Historically cetaceans were hunted in southern Taiwan; baleen whales as well as beaked and killer whales were taken. Up until 1990, a drive fishery of false killer whales occurred in the Penghu Islands, Taiwan, where dozens of whales were taken. Although killing and capturing of cetaceans has been prohibited in Taiwan since August 1990 under the Wildlife Conservation Law (Zhou et al. 1995; Chou 2004), illegal harpooning still occurs (Perrin et al. 2005). From 1993 to 1995, ~600 cetaceans were taken by harpoon per year in Nanfang Ao, in northeast Taiwan, despite this practice being outlawed since 1990

under the Wildlife Conservation Law (Zhou et al. 1995; Chou 2004; Perrin et al. 2005). Bryde's whales have been harvested in the Philippines, and until the 1990s, there was also a significant hunt of small cetaceans (Rudolph and Smeenk 2002). However, this hunt seems to have almost disappeared after successive bans on the harvesting of whales and dolphins by the Philippine Government during the 1990s.

In China, a considerable number of sea turtles were harvested before they were listed as a protected species in 1988 (Liang et al. 1990 *in* Chan et al. 2007). Both the eggs and nesting turtles were harvested for consumption from nesting sites such as those at Gangkou and the Xisha Archipelago (Chan et al. 2007). In Gangkou, 60,000 to 200,000 eggs of green turtles were collected each year before the 1950s (Zhang 1995). Green turtles were also intensively fished, mostly during summer and autumn, in the Xisha Archipelago (Frazier et al. 1988). Direct beach harvesting for meat was common in Taiwan in the early 1970s, especially along the east coast, resulting in the mortality of most of the nesting green turtles (I.J. Cheng, unpubl. data 1995; Chan et al. 2007). Similar to green turtles, the population of hawksbill turtles in China declined dramatically in recent decades due to overharvesting. Currently, the direct harvesting of sea turtles and egg poaching is prohibited in protected nesting sites; however, illegal capture still occurs (Chan et al. 2007).

(e) Summary of Cumulative Impacts

The marine mammals and sea turtles encountered in the Shatsky Rise region will either be migrating elsewhere or temporarily feeding in patches of high productivity associated with the Kuroshio Extension and bifurcation (west of the study area). These same individuals rely heavily on other oceanic regions, distant to the study area, to feed and breed, where other stressors (e.g., marine pollution, habitat loss) may impact populations. Major threats to sea turtles in coastal areas include hunting and poaching, the collection of eggs, coastal development, increased tourism, beach sand mining, ingestion of plastic and marine garbage, and destruction of feeding habitat in coral reefs and seagrass beds (Horrocks 1992; Marcovaldi et al. 2003). Solid debris, oil and tar, organochlorine residues, and heavy metals have also threatened the survivorship of turtles in many areas of the world (Godley et al. 1999).

Impacts of the proposed seismic survey at Shatsky Rise are expected to be no more than a minor (and short-term) increment when viewed in the light of other human activities within and near the study area. Unlike some other activities (e.g., fishing), seismic activities are not expected to result in injuries or deaths of marine mammals and sea turtles. Although airgun sounds do have high source levels, the sounds are pulses rather than continuous tones, and operations will be carried out for only ~17 days. As previously discussed, L-DEO's airgun operations are unlikely to cause any large-scale or prolonged effects. Thus, the combination of L-DEO's operations with the existing shipping, fishing, and whaling operations is expected to produce only a negligible increase in overall disturbance effects on marine mammals and turtles.

(10) Unavoidable Impacts

Unavoidable impacts to the species of marine mammals and turtles occurring in the proposed study area will be limited to short-term, localized changes in behavior of individuals and possibly a few occurrences of TTS in marine mammals that approach close to the operating airgun array. For cetaceans, some of the changes in behavior may be sufficient to fall within the MMPA definition of "Level B Harassment" (behavioral disturbance; no serious injury or mortality). TTS, if it occurs, will be limited to a few individuals, is a temporary phenomenon that does not involve injury, and is unlikely to have long term consequences for the few individuals involved. No long-term or significant impacts are expected on

any of these individual marine mammals or turtles, or on the populations to which they belong. Effects on recruitment or survival are expected to be (at most) negligible.

(11) Coordination with Other Agencies and Processes

This EA has been prepared by LGL on behalf of NSF pursuant to NEPA and assesses potential impacts to endangered species. It will be used to support the ESA Section 7 consultation process with NMFS. This document will also be used as supporting documentation for an IHA application submitted by L-DEO to NMFS, under the U.S. MMPA, for "taking by harassment" (disturbance) of small numbers of marine mammals, for this proposed seismic project. As the project will occur in international waters, there is no Essential Fish Habitat (EFH), Habitat Areas of Particular Concern (HAPC), or critical habitat in the proposed study area.

Dr. Toshihide Kitakado of Tokyo University of Marine Science and Technology was contacted regarding information on Bryde's whale densities in the Shatsky Rise area. L-DEO and NSF will coordinate the planned marine mammal monitoring program associated with the seismic survey with other parties that may have interest in this area. L-DEO and NSF have coordinated, and will continue to coordinate, with other applicable agencies, and will comply with their requirements.

Alternative Action: Another Time

An alternative to issuing the IHA for the period requested, and to conducting the project then, is to issue the IHA for another time, and to conduct the project at that alternative time. The proposed time for the cruise is the period when the personnel and equipment essential to meet the overall project objectives are available, and it takes into consideration the timing of the typhoon season.

Marine mammals and sea turtles are expected to be found throughout the proposed study area. Many cetaceans occur in the survey area throughout the year, but others (some baleen whales) may only migrate though the area during spring and fall; thus, altering the timing of the proposed project likely would result in few net benefits. Loggerhead, leatherback, and green turtles nest on the Ryukyu Islands, Japan, at the time of the survey, so nesting females would be nearshore or on land far from the survey area. However, migrating or foraging loggerhead, leatherback, or green turtles could be encountered in the deep waters of the survey area at any time of year.

No Action Alternative

An alternative to conducting the proposed activities is the "No Action" alternative, i.e., do not issue an IHA and do not conduct the operations. If the research were not conducted, the "No Action" alternative would result in no disturbance to marine mammals or sea turtles attributable to the proposed activities, but geological data of considerable scientific value and relevance in understanding plateau formation and earthquake potential (see § I) would not be acquired.

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APPENDIX A:

L-DEO MODELING FOR MARINE SEISMIC SOURCE ARRAYS FOR SPECIES MITIGATION[2]

1. Summary

To ensure that U.S. academic marine seismic activity does not adversely affect marine wildlife stocks, federal regulations controlling the levels of sound to which those stocks may be exposed are closely followed. These regulations include the establishment of various exclusion zones, which are defined by a priori modeling of the propagation of sound from the proposed seismic source array. To provide realistic results, modeling must include free surface and array effects. This is best accomplished when the near field signature of each airgun array element is propagated separately to the far field and the results summed there. The far field signatures are analyzed to provide measurements that characterize the source's energy as a function of distance and direction. The measure currently required for marine wildlife mitigation is root-mean-square [RMS]. While RMS is an appropriate measure for lengthy signals, it may not accurately represent the energy and impact of a short, impulsive signal. When a comparison is made between RMS and several other metrics, it is apparent that RMS is the least consistent.

2. Introduction

Modern marine seismic profiling is typically carried out using arrays of airguns as the acoustic source. Unlike single airguns or explosive sources, the physical extent and distributed quality of these arrays produce an asymmetric pressure field, which cannot be described accurately by a simple, rule-of-thumb approach.

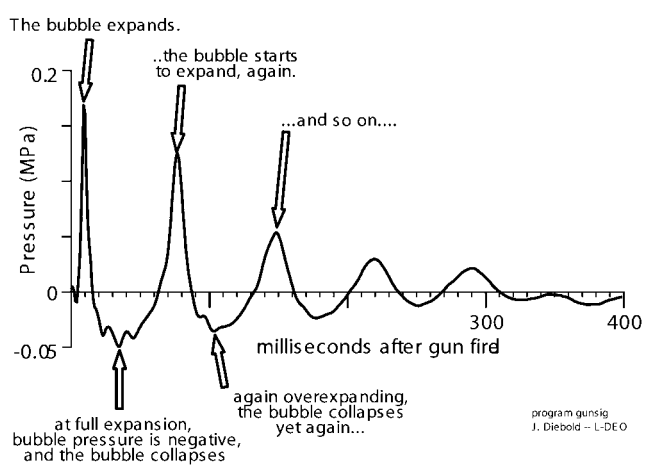

FIGURE A-1. Recording of a single airgun pulse made during R/V *EWING* tests, 1990.

This wavetrain can be seen in its true form only very close to the airgun and it is called the "near field" signal. Airguns are usually towed at a shallow depth (3–9 m) beneath the sea surface, from which

[2] By **John Diebold**, L-DEO, revised May 2006.

sound waves are negatively reflected, and at any significant distance from the airgun, both the direct and its negatively reflected "ghost" are seen, one right after the other. This ghosting imposes a strong and very predictable filter on the received arrivals.

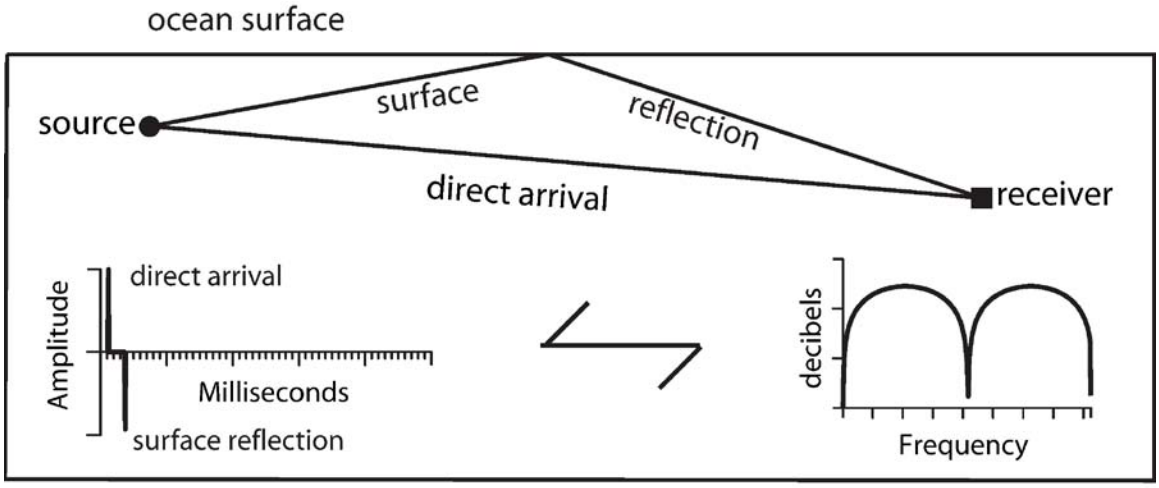

FIGURE A-2. Top: pathways for direct and surface-reflected arrivals used in modeling. Bottom: direct and ghosted arrival amplitudes in the time domain can be considered an operator whose spectrum is predictable, and which acts as a filter on the spectrum of the intrinsic near field source, whatever that may be.

The time interval between the arrivals of the direct and surface-reflected signals depends on the position of observation; it is greatest at any position directly beneath the source. Depending on the location of the point of observation relative to the source array, the appearance and strength of the signal can be extremely variable. In the comparison below, two observation points were chosen, equally distant from a 20-airgun array.

The differences here are caused by two effects. One is directionality resulting from the physical dimensions of the array. The other effect is that the surface ghosting imposes a strong filter on the near field source signatures, and the shape of this filter is controlled by the relative positions of sources and receivers.

3. Modeling

Since the sum of the direct and the surface-reflected signals varies according to position, modeling can only be carried out correctly when near-field source signatures are used, and propagation along all of the pathways between the source and the receiver is considered separately. In the simple half-space model illustrated above (Fig. 3), there are only two pathways. When an array of sources is used, travel time, spreading and reflection losses are calculated for each pathway and for each source element separately. According to the exact distance between the point of observation and the particular airgun, each element's near-field signal is appropriately scaled in amplitude and shifted in time. Then the process is repeated to produce the free surface "ghost" signal of each airgun, and the results are summed.

For R/V ***EWING*** mitigation, the near-field signatures were calculated by extrapolation from a set of measured signals received from Teledyne in 1981. Results of this modeling have been compared to a great number of published signals, and the amplitudes of the library's signals adjusted to provide a close match. Since peak values are highly dependent on an impulsive signal's high frequency content, the comparisons are most accurately made in the spectral domain.

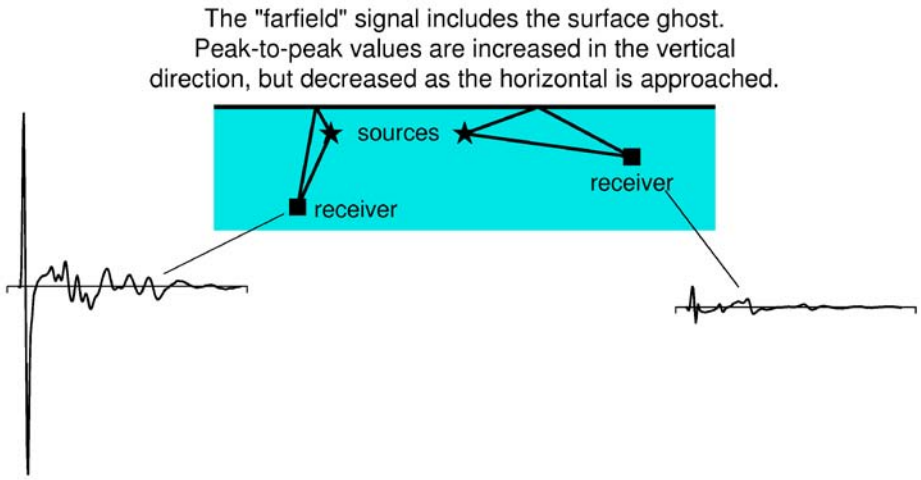

FIGURE A-3. The far field signature of a 20-airgun array modeled at two receiver positions equidistant from the center of the array. Differences are due to array directivity and surface ghosting effects.

Few, if any, of the published examples include airguns with volumes as large as those often included in ***EWING***'s source arrays. There are several very good reasons for this (and for the inclusion of such sizes in ***EWING*** arrays.) Principal among these was the observation by W. Dragoset of Western Geophysical [pers. comm., 1990] that the characteristics of the Bolt 1500C air exhaust ports are such that throttling occurs when air chambers above a certain size are used. The result of this is that peak amplitudes increase only slightly, so that the efficiency of these airguns diminishes with increasing volume. On the other hand, bubble pulse periods do increase according to theory, so that the benefit of larger sizes in array tuning is undiminished. The decrease in efficiency was borne out during testing of ***EWING***'s airguns during the 1990 shakedown legs (Fig. 4).

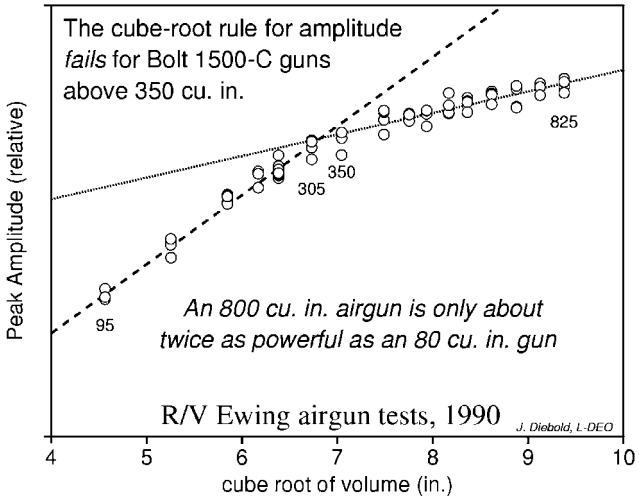

FIGURE A-4. R/V ***EWING*** test results, 1990.

Near-field signatures can be created by a number of commercially available modeling packages, all based in part on the work of Ziolkowski (1978). Those packages were not used for ***EWING*** modeling for two reasons: cost and accuracy. As Figure 5 demonstrates, PGS' Nucleus/Masomo software does not accurately model the large Bolt airguns used in ***EWING*** arrays:

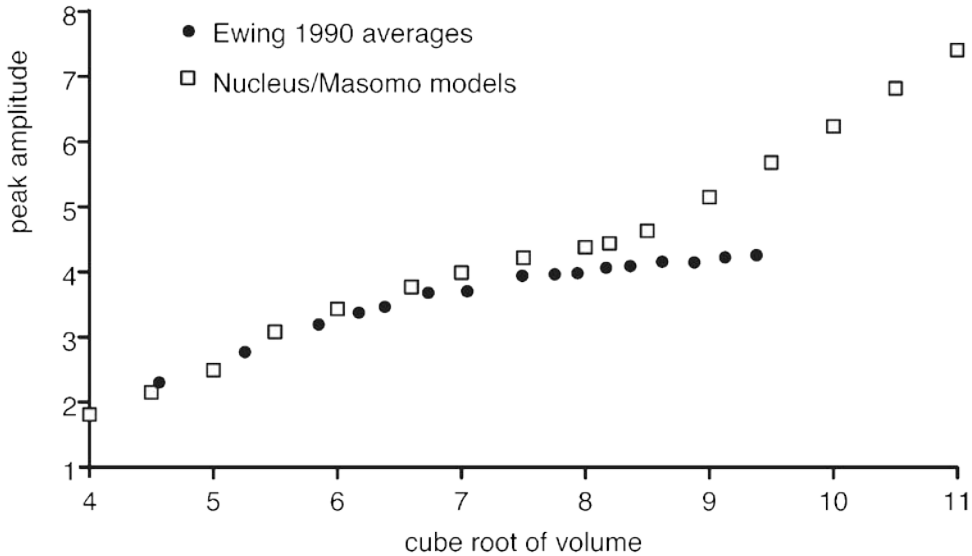

FIGURE A-5. Nucleus/Masomo overestimates peak values for large Bolt airguns.

The R/V ***LANGSETH*** will have source arrays that are quite different than ***EWING***'s: (1) maximum airgun volume will be much smaller, (2) two different kinds of airguns will be combined, (3) airguns will be towed closer together, and (4) two-element "clusters" will be included. The latter three of these features are unsupported by the homebrew modeling used for ***EWING*** arrays, and we are currently using PGS' Nucleus/Masomo software for this purpose [http://www.pgs.com/business/products/nucleus/]. Some of the examples below have been created using the simpler ***EWING*** models, however.

The modeling procedure can be summarized as follows:

1) Define the airgun array in terms of the size and relative location of each airgun [X, Y, Z].
2) Create near field ["notional"] signatures for each airgun.
3) Decide upon a 2D mesh of points, for example within a plane intersecting the center of the airgun array. A typical mesh is 100 x 50.
4) For each of the points in the mesh, create the signal that would be observed there when every airgun in the array was fired simultaneously.
5) For that signal, determine the desired statistic: Peak-to-peak dB, Peak dB, RMS dB, maximum psi, etc.
6) Contour the mesh.

Most of the work lies in step 4) which has steps of its own:

a) For each of the airguns in the array, determine the distances, and thus the time-of-flight between the airgun and the mesh point, as well as the free surface ghost "image" of the airgun and the mesh point.
b) Scale and shift this airgun's near-field signal, dividing by the point-to-point distance and moving forward in time according to time-of-flight.
c) Scale and shift the near-field signal's ghost image, as above, in addition multiplying by the free surface reflection coefficient [typically between -.9 and -.95].

d) Sum the results. For the ***EWING*** 20-airgun array, 40 scaled and shifted signals were created and summed for each mesh point.

4. Units

Exploration industry standard units for seismic source pressures are Bar-meters; an intuitively attractive measure in atmospheres [bars] at one meter from the center of the source array. In SI units, 10 Bar = 1 megaPascal = 10^{-12} μPascal. To convert Bar-m to decibels with respect to μPascal–m we use this formula:

$$\text{dB [wrt } \mu\text{Pascal –m]} = 220 * 20 \log^{10}(\text{B-m})$$

RMS dB and the exclusion zone

A variety of means are used to characterize the strength of seismic source signals. Peak, peak-to-peak, and total energy levels are easy to measure, but historically, all of the research on acoustic avoidance behavior of marine mammals has quantified the sound levels in terms of RMS, a measure which is entirely appropriate for many acoustic signals found in the marine environment (e.g., shipping noise, Navy sonar, etc.). Although it is less appropriate for impulsive airgun signals, the RMS measure has been used in most published studies anyway (cf. Malme et al. 1983a,b), so that meaningful comparisons could be made. The protocols used for the RMS calculation in most published research are diagrammed below (Fig. 6), applied to the signal predicted by our modeling for a point 4000 m aft of *EWING*'s 20 airgun array, at a depth of 1200 m.

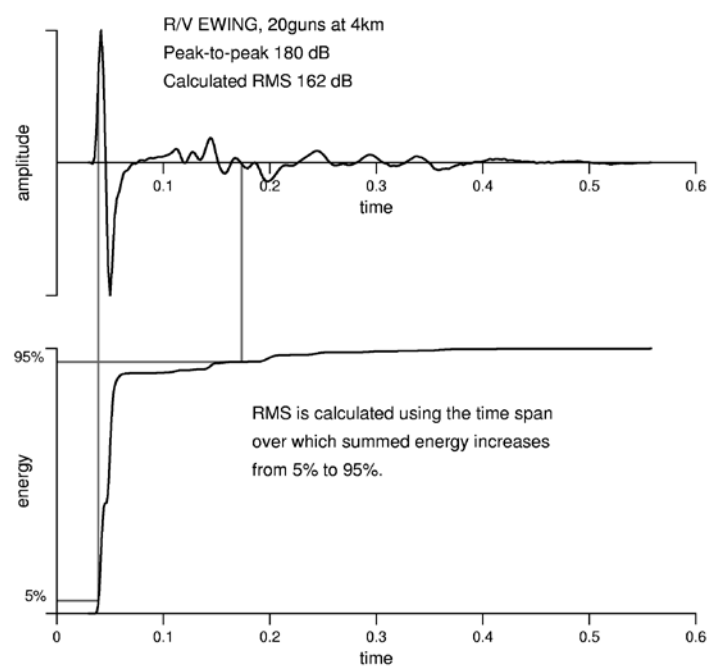

FIGURE A-6. The "standard" 90% RMS calculation. Energy is summed as a function of time for the entire signal. From this result, the times at which 5% and 95% of the total energy are attained define the RMS integration window.

This difference between the peak-to-peak and RMS dB levels for the same signal falls within the 16-18 dB averages reported for impulsive airgun signals by Greene (1997) and McCauley (1998).

5. Calculating the exclusion zone

R/V ***EWING*** source arrays were intended and designed for 2D seismic reflection and refraction work, and were, consequentially, highly directional, focusing energy downwards and in line with the ship's track direction.

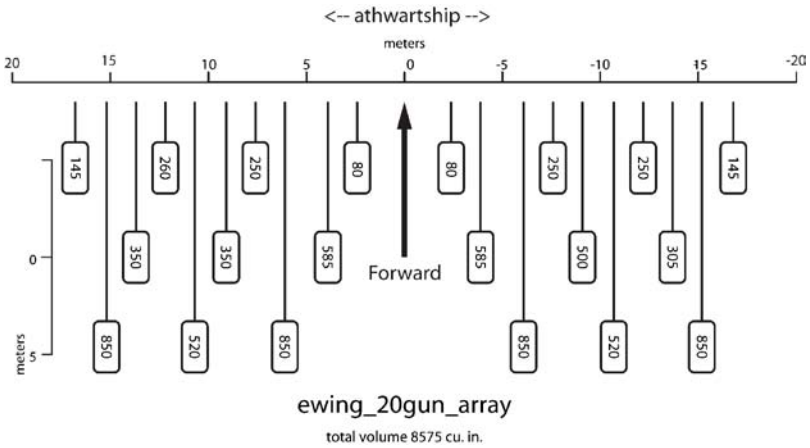

FIGURE A-7. Plan view of the 20-airgun array used to calculate Fig. 3, 4, and 6. Tow depth is 7.5 m.

The RMS calculation is applied to the mesh point signatures resulting from the modeling process described above. When the 90% RMS levels are contoured, the directional nature of the standard R/V ***EWING*** source array is obvious (Fig. 8).

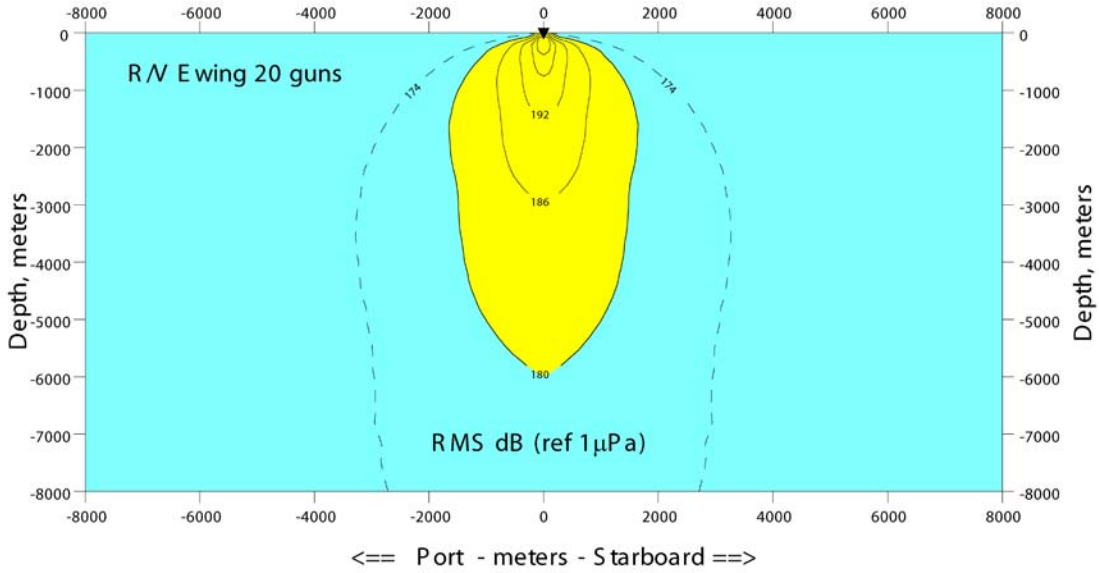

FIGURE A-8a. 90% RMS isopleths calculated in the crosstrack direction for a 20-airun array. Yellow denotes RMS values >180 dB.

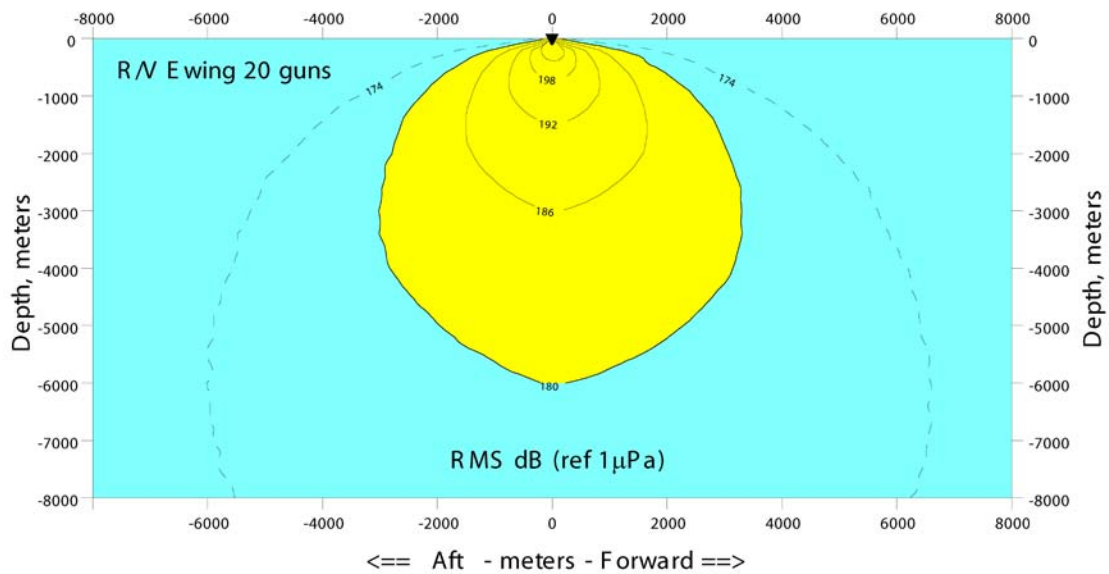

FIGURE A-8b. 90% RMS isopleths calculated in the along track direction for a 20-airun array. Yellow denotes RMS values >180 dB.

Since the fore-and-aft extent of ***EWING***'s array is smaller than the athwartship dimension, directionality is less marked in front of and behind the array. The distances therefore to the 180 dB contours, or isopleths, are greater in the fore-and-aft than athwartship directions, and we use these worst case distances to determine exclusion zones.

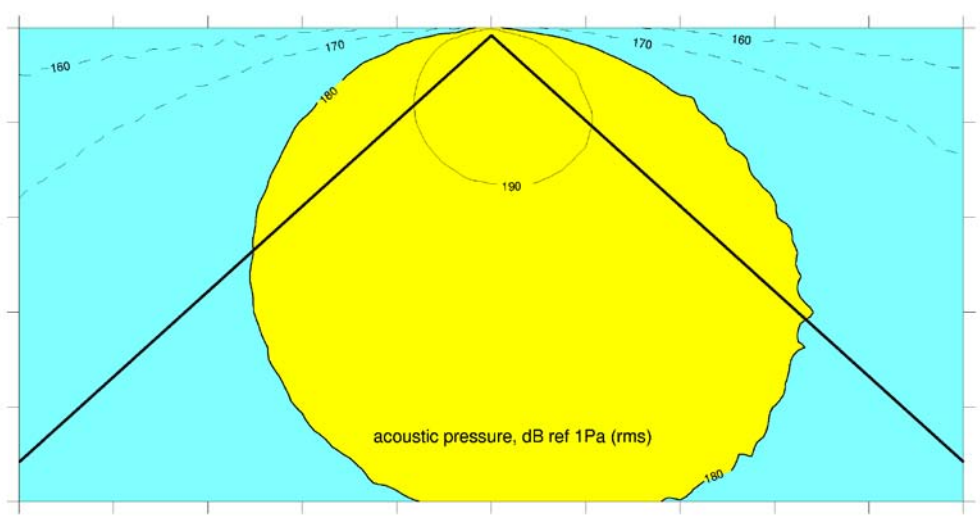

FIGURE A-9. The pathways in offset and depth which intersect maximum-radius isopleths. These are used to calculate radii for various 90% RMS levels.

This modeling approach includes two important simplifications: (1) the assumption of a homogeneous water column (i.e., raypaths are linear), and (2) that interactions with the seafloor are not included. In deep water (i.e., 1000 m and greater] our predicted exclusion zones are conservatively greater than those determined by actual calibration (Tolstoy et al. 2004). In shallow water (100 m and

less) water column reverberations and constructive interference contribute to increase actual levels over those predicted by the modeling techniques described here.

Problems with 90% RMS

The biggest pitfall in the 90% RMS measure is that the RMS value can vary tremendously for signals having similar energy content. If the signal is only a little less "ringy" than the ***EWING*** 20 gun example shown above, the 90% energy time span will be much smaller, which greatly increases the RMS value. The better the "tuning" of a seismic source array, the more impulsive its signature and the shorter its 90% energy window. The resulting problems can be illustrated using a simple source – a two-gun "cluster" as modeled by Nucleus/Masomo. Signals are calculated at hundreds of mesh points, 90% RMS is calculated for each signal, and the resulting levels were contoured (Fig. 10).

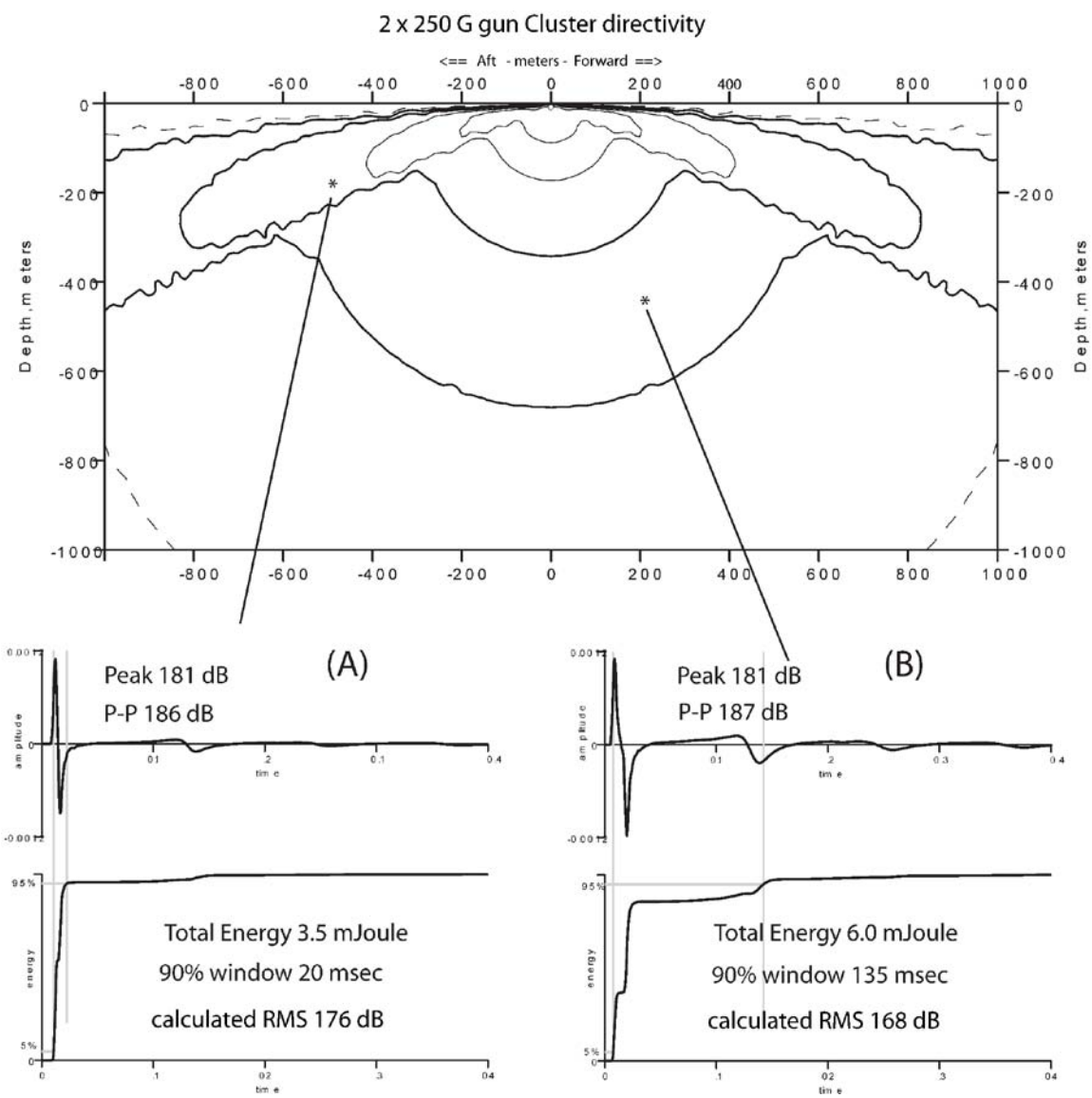

FIGURE A-10. Modeled results from a simple 2-airgun cluster source.

Unlike the ***EWING*** example presented earlier, the RMS contours for this source are pathologically variable. To investigate the reason for this, two signatures, (A) and (B), were calculated at equal distances from the source array, but in high and low RMS zones, respectively. These signals have identical peak levels, but greatly different RMS values. The difference is almost entirely due to the varying length of the automatically determined 90% RMS integration window. This change in window length is in turn due to the effects of surface ghosting, which diminish the bubble pulse in the left-hand signal (A), thus reducing the 90% energy time span. Paradoxically, the right-hand signal (B), which has higher peak-to-peak and total energy levels, has a greatly lower RMS value. This is almost entirely due to large variations in the automatically calculated 90% RMS window length. A contour plot of 90% RMS window length shows that for this source, they vary between 5 and 137 milliseconds (Fig. 11).

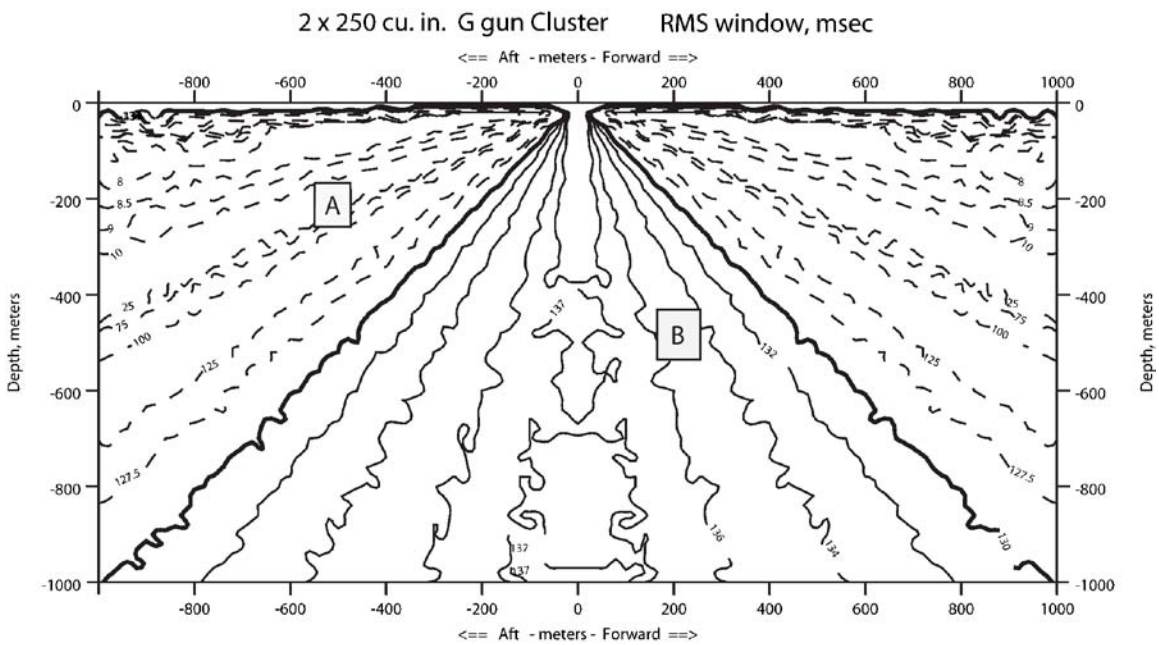

Figure A-11. The locations from which signals (A) and (B) were extracted are shown for reference.

Other measures may be far more appropriate for quantifying airgun signal levels and predicting their effect on marine creatures.

Sound exposure level [SEL] is equal to RMS but with an added factor which is intended to minimize the time windowing effect, and to produce a measure more meaningful for the effects of noise on mammalian ears:

$$DB_{SEL} = dB_{RMS} + 10 * Log_{10} \text{ (window), where the window has units of seconds.}$$

For RMS window lengths less than one second, this additive factor varies between –30 dB for a RMS window length of 1 millisecond, to zero, for a window length of one second.

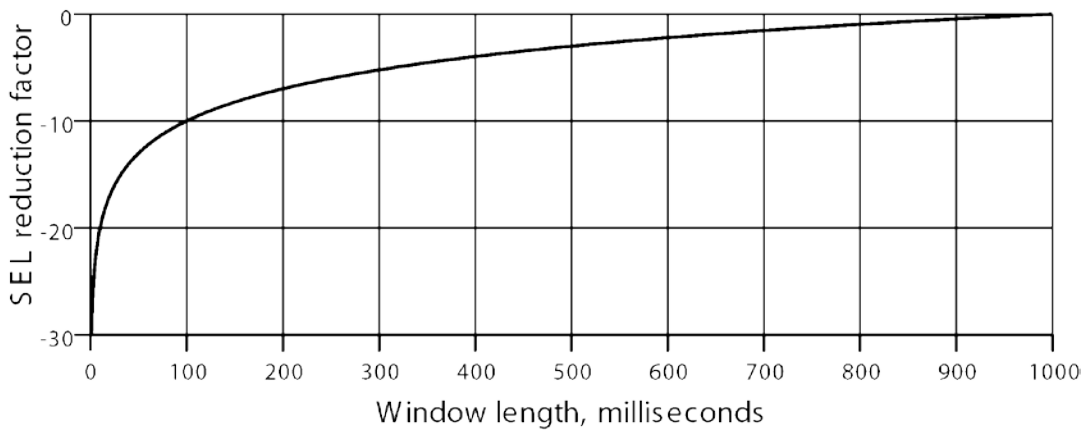

Figure A-12.

Calculation of SEL for the two cluster signatures shown above shows the effect of the calculation's window length correction factor:

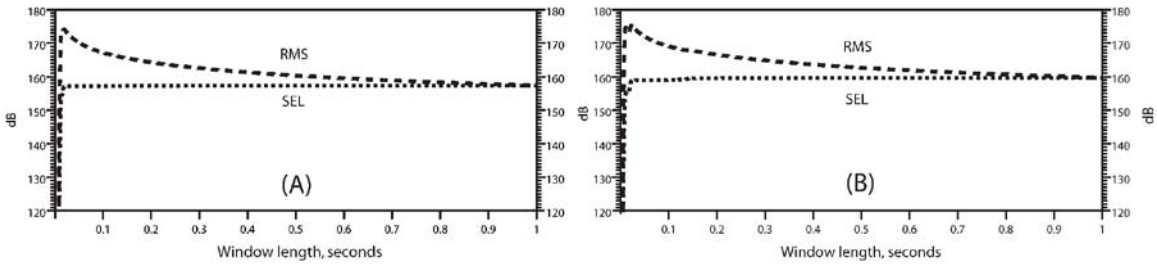

Figure A-13.

While RMS varies continually with window length, SEL tends to approach a stationary level; in this case 157 dB for signal (A), and 160 dB for (B). The effect is to eliminate the dependence of the determined level upon window size; as long as the entire signal is captured, the calculated SEL will be pretty much the same. SEL is considered by many researchers (cf. Patterson 1991) to be a better predictor of hearing threshold shifts than is RMS or peak level.

Neither RMS nor SEL include frequency content, and there are many ways to look at this. Within the exploration seismic community, the cumulative energy flux is a standard measure (Johnston et al. 1988).

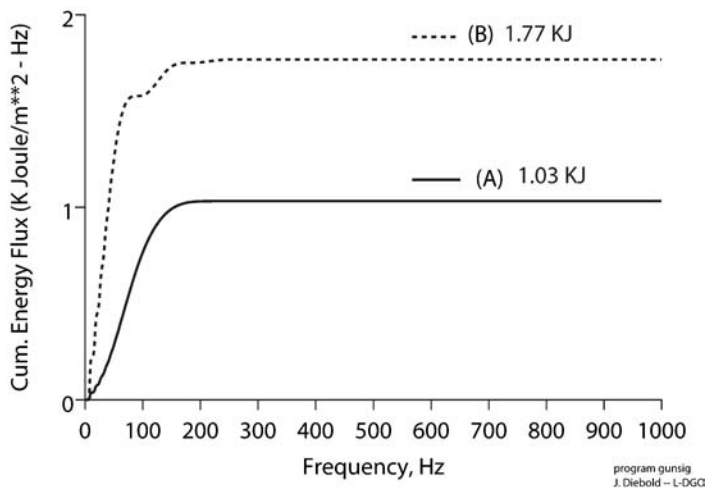

FIGURE A-14.

Two features are immediately apparent from this plot: first, most of the energy in both signals is present at frequencies below several hundred Hz, and second, signal (B) whose 90% RMS level is less than half that of signal (A), actually contains appreciably more total energy. When the total energy of a short, impulsive signal, such as that created by an airgun array in deep water, is expressed in terms of dB, the result is usually equal to SEL.

The 90% RMS measure currently used to characterize possible impact on marine mammals may be severely flawed, especially when marine seismic source arrays are physically compact and/or well-tuned. An energy-based metric would produce more consistent results, and can be implemented in either time or frequency domains.

TABLE A-1.

	A	B	%, A/B
RMS	176	168	166.67%
Peak	181	181	100.00%
P-P	186	187	91.67%
SEL	157	160	75.00%
Energy	3.5	6	58.33%
Energy	1.03	1.77	58.19%

The seismic sources planned and under construction for R/V ***LANGSETH*** are much more highly tuned than those deployed by R/V ***EWING***. Although the total energy content in the signal produced by ***LANGSETH***'s largest array is smaller than that of the "standard" ***EWING*** 20-airgun array, 90% RMS values of modeled signatures are much higher, due entirely to the RMS window length imposed by the improved tuning. Therefore, we propose to use SEL values, at least until new metrics are imposed. The question is: how to convert from SEL to equivalent RMS?

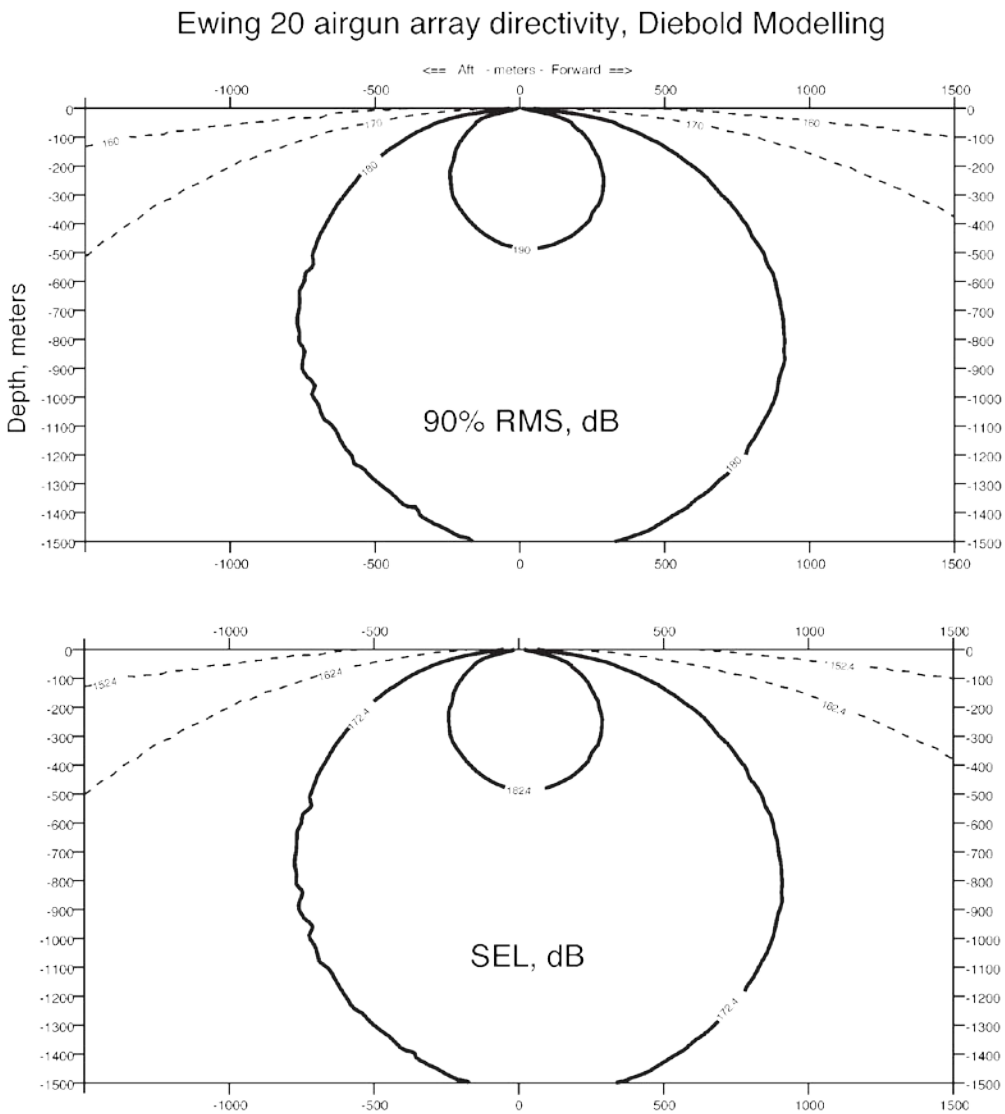

FIGURE A-15. Here we have matched the RMS and SEL contours nearly perfectly by using an SEL value equal to RMS – 7.6 dB, an offset corresponding to the normal 90% energy window length of about 174 msec. Current IHA applications have used an SEL "discount" of 15 dB, which is equivalent to an RMS window of about 32 msec. It might be more appropriate to use a discount factor which corresponds to the natural mammal hearing integration time – it has been suggested, for example [Peter Tyack, pers. comm.] that this is about 200 msec for dolphins. This would be equivalent to an RMS – SEL discount of 7 dB.

Other metrics

When geophysicists investigate signal quality, they are likely to plot spectral energy on a linear frequency scale, as specified in Johnston et al. (1988):

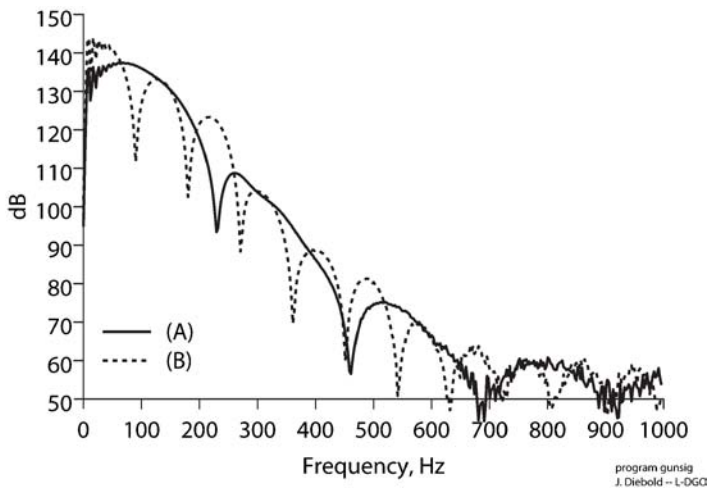

FIGURE A-16.

In studies of noise and its effect on marine animals, a spectral display in terms of 1/3 octave energy levels is often preferred. To obtain such a display, spectral power is integrated within specified bands whose width increases logarithmically with frequency.

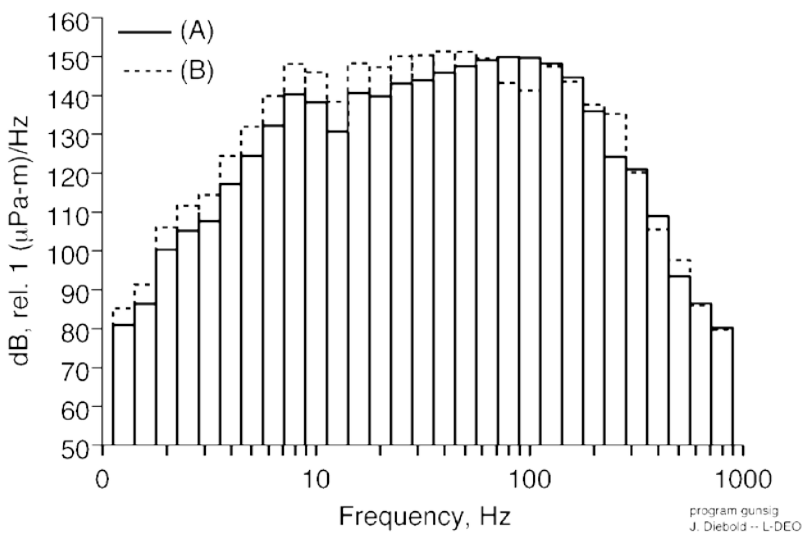

FIGURE A-17.

It is clear from this display that despite its higher calculated 90% RMS level, signal (A) has lower energy than (B) at most frequencies, especially between zero and 100 Hz, where ghosting effects play a major role.

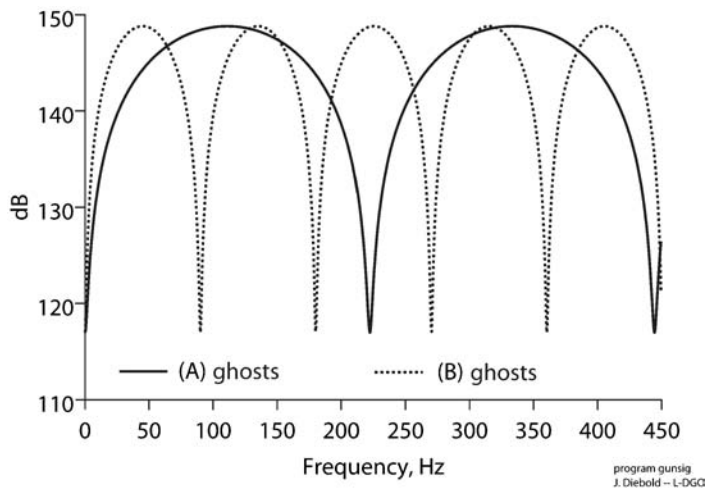

Figure A-18.

The time lag between direct and surface-reflected paths for signal (A) is much smaller than that for signal (B). Therefore the ghost-induced shaping filter superimposed on signal (A) cuts out much of the low-frequency energy seen in signal (B).

If we plot the ghost shaping filters in the third-octave display described above, it is readily apparent that most of the differences between (A) and (B) in the previous third-octave plot are due to ghosting effects:

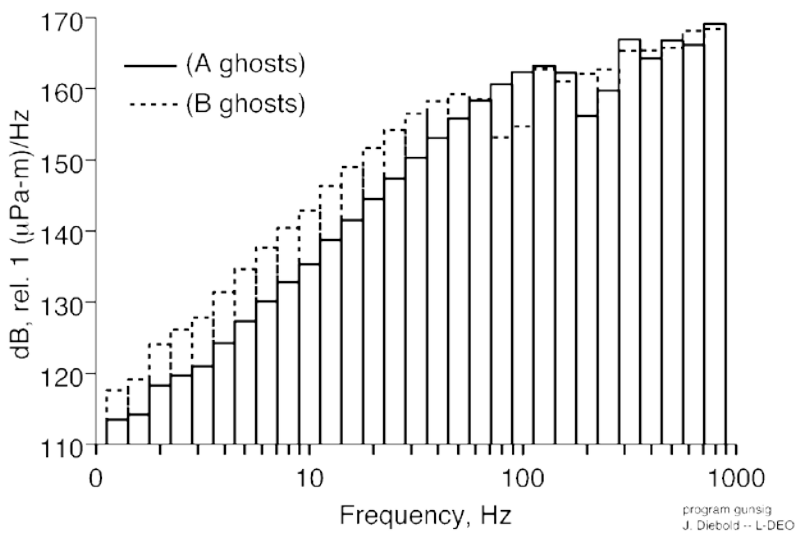

Figure A-19.

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APPENDIX B:
REVIEW OF THE EFFECTS OF AIRGUN SOUNDS ON MARINE MAMMALS[3]

The following subsections review relevant information concerning the potential effects of airguns on marine mammals. Because this review is intended to be of general usefulness, it includes references to types of marine mammals that will not be found in some specific regions.

1. Categories of Noise Effects

The effects of noise on marine mammals are highly variable, and can be categorized as follows (adapted from Richardson et al. 1995):

1. The noise may be too weak to be heard at the location of the animal, i.e., lower than the prevailing ambient noise level, the hearing threshold of the animal at relevant frequencies, or both;
2. The noise may be audible but not strong enough to elicit any overt behavioral response, i.e., the mammal may tolerate it, either without or with some deleterious effects (e.g., masking, stress);
3. The noise may elicit behavioral reactions of variable conspicuousness and variable relevance to the well being of the animal; these can range from subtle effects on respiration or other behaviors (detectable only by statistical analysis) to active avoidance reactions;
4. Upon repeated exposure, animals may exhibit diminishing responsiveness (habituation), or disturbance effects may persist; the latter is most likely with sounds that are highly variable in characteristics, unpredictable in occurrence, and associated with situations that the animal perceives as a threat;
5. Any man-made noise that is strong enough to be heard has the potential to reduce (mask) the ability of marine mammals to hear natural sounds at similar frequencies, including calls from conspecifics, echolocation sounds of odontocetes, and environmental sounds such as surf noise or (at high latitudes) ice noise. However, intermittent airgun or sonar pulses could cause strong masking for only a small proportion of the time, given the short duration of these pulses relative to the inter-pulse intervals;
6. Very strong sounds have the potential to cause temporary or permanent reduction in hearing sensitivity, or other physical or physiological effects. Received sound levels must far exceed the animal's hearing threshold for any temporary threshold shift to occur. Received levels must be even higher for a risk of permanent hearing impairment.

2. Hearing Abilities of Marine Mammals

The hearing abilities of marine mammals are functions of the following (Richardson et al. 1995; Au et al. 2000):

1. Absolute hearing threshold at the frequency in question (the level of sound barely audible in the absence of ambient noise). The "best frequency" is the frequency with the lowest absolute threshold.
2. Critical ratio (the signal-to-noise ratio required to detect a sound at a specific frequency in the presence of background noise around that frequency).

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3. The ability to determine sound direction at the frequencies under consideration.
4. The ability to discriminate among sounds of different frequencies and intensities.

Marine mammals rely heavily on the use of underwater sounds to communicate and to gain information about their surroundings. Experiments and monitoring studies also show that they hear and may react to many man-made sounds including sounds made during seismic exploration (Richardson et al. 1995; Gordon et al. 2004; Nowacek et al. 2007; Tyack 2008).

2.1 Toothed Whales (Odontocetes)

Hearing abilities of some toothed whales (odontocetes) have been studied in detail (reviewed in Chapter 8 of Richardson et al. [1995] and in Au et al. [2000]). Hearing sensitivity of several species has been determined as a function of frequency. The small to moderate-sized toothed whales whose hearing has been studied have relatively poor hearing sensitivity at frequencies below 1 kHz, but extremely good sensitivity at, and above, several kHz. There are very few data on the absolute hearing thresholds of most of the larger, deep-diving toothed whales, such as the sperm and beaked whales. However, Cook et al. (2006) found that a stranded juvenile Gervais' beaked whale showed evoked potentials from 5 kHz up to 80 kHz (the entire frequency range that was tested), with best sensitivity at 40–80 kHz. An adult Gervais' beaked whale had a similar upper cutoff frequency (80–90 kHz; Finneran et al. 2009).

Most of the odontocete species have been classified as belonging to the "mid-frequency" (MF) hearing group, and the MF odontocetes (collectively) have functional hearing from about 150 Hz to 160 kHz (Southall et al. 2007). However, individual species may not have quite so broad a functional frequency range. Very strong sounds at frequencies slightly outside the functional range may also be detectable. The remaining odontocetes—the porpoises, river dolphins, and members of the genera *Cephalorhynchus* and *Kogia*—are distinguished as the "high frequency" (HF) hearing group. They have functional hearing from about 200 Hz to 180 kHz (Southall et al. 2007).

Airguns produce a small proportion of their sound at mid- and high-frequencies, although at progressively lower levels with increasing frequency. In general, most of the energy in the sound pulses emitted by airgun arrays is at low frequencies; strongest spectrum levels are below 200 Hz, with considerably lower spectrum levels above 1000 Hz, and smaller amounts of energy emitted up to ~150 kHz (Goold and Fish 1998; Sodal 1999; Goold and Coates 2006; Potter et al. 2007).

Despite the relatively poor sensitivity of small odontocetes at the low frequencies that contribute most of the energy in pulses of sound from airgun arrays, airgun sounds are sufficiently strong, and contain sufficient mid- and high-frequency energy, that their received levels sometimes remain above the hearing thresholds of odontocetes at distances out to several tens of kilometers (Richardson and Würsig 1997). There is no evidence that most small odontocetes react to airgun pulses at such long distances. However, beluga whales do seem quite responsive at intermediate distances (10–20 km) where sound levels are well above the ambient noise level (see below).

In summary, even though odontocete hearing is relatively insensitive to the predominant low frequencies produced by airguns, sounds from airgun arrays are audible to odontocetes, sometimes to distances of 10s of kilometers.

2.2 Baleen Whales (Mysticetes)

The hearing abilities of baleen whales (mysticetes) have not been studied directly. Behavioral and anatomical evidence indicates that they hear well at frequencies below 1 kHz (Richardson et al. 1995;

Ketten 2000). Frankel (2005) noted that gray whales reacted to a 21–25 kHz whale-finding sonar. Some baleen whales react to pinger sounds up to 28 kHz, but not to pingers or sonars emitting sounds at 36 kHz or above (Watkins 1986). In addition, baleen whales produce sounds at frequencies up to 8 kHz and, for humpbacks, with components to >24 kHz (Au et al. 2006). The anatomy of the baleen whale inner ear seems to be well adapted for detection of low-frequency sounds (Ketten 1991, 1992, 1994, 2000; Parks et al. 2007b). Although humpbacks and minke whales (Berta et al. 2009) may have some auditory sensitivity to frequencies above 22 kHz, for baleen whales as a group, the functional hearing range is thought to be about 7 Hz to 22 kHz and they are said to constitute the "low-frequency" (LF) hearing group (Southall et al. 2007). The absolute sound levels that they can detect below 1 kHz are probably limited by increasing levels of natural ambient noise at decreasing frequencies (Clark and Ellison 2004). Ambient noise levels are higher at low frequencies than at mid frequencies. At frequencies below 1 kHz, natural ambient levels tend to increase with decreasing frequency.

The hearing systems of baleen whales are undoubtedly more sensitive to low-frequency sounds than are the ears of the small toothed whales that have been studied directly. Thus, baleen whales are likely to hear airgun pulses farther away than can small toothed whales and, at closer distances, airgun sounds may seem more prominent to baleen than to toothed whales. However, baleen whales have commonly been seen well within the distances where seismic (or other source) sounds would be detectable and often show no overt reaction to those sounds. Behavioral responses by baleen whales to seismic pulses have been documented, but received levels of pulsed sounds necessary to elicit behavioral reactions are typically well above the minimum levels that the whales are assumed to detect (see below).

2.3 Seals and Sea Lions (Pinnipeds)

Underwater audiograms have been obtained using behavioral methods for three species of phocinid seals, two species of monachid seals, two species of otariids, and the walrus (reviewed in Richardson et al. 1995: 211ff; Kastak and Schusterman 1998, 1999; Kastelein et al. 2002, 2009). The functional hearing range for pinnipeds in water is considered to extend from 75 Hz to 75 kHz (Southall et al. 2007), although some individual species—especially the eared seals—do not have that broad an auditory range (Richardson et al. 1995). In comparison with odontocetes, pinnipeds tend to have lower best frequencies, lower high-frequency cutoffs, better auditory sensitivity at low frequencies, and poorer sensitivity at the best frequency.

At least some of the phocid seals have better sensitivity at low frequencies (≤1 kHz) than do odontocetes. Below 30–50 kHz, the hearing thresholds of most species tested are essentially flat down to ~1 kHz, and range between 60 and 85 dB re 1 µPa. Measurements for harbor seals indicate that, below 1 kHz, their thresholds under quiet background conditions deteriorate gradually with decreasing frequency to ~75 dB re 1 µPa at 125 Hz (Kastelein et al. 2009).

For the otariid (eared) seals, the high frequency cutoff is lower than for phocinids, and sensitivity at low frequencies (e.g., 100 Hz) is poorer than for seals (harbor seal).

2.4 Manatees and Dugong (Sirenians)

The West Indian manatee can apparently detect sounds and low-frequency vibrations from 15 Hz to 46 kHz, based on a study involving behavioral testing methods (Gerstein et al. 1999, 2004). A more recent study found that, in one Florida manatee, auditory sensitivity extended up to 90.5 kHz (Bauer et al. 2009). Thus, manatees may hear, or at least detect, sounds in the low-frequency range where most

seismic energy is released. It is possible that they are able to feel these low-frequency sounds using vibrotactile receptors or because of resonance in body cavities or bone conduction.

Based on measurements of evoked potentials, manatee hearing is apparently best around 1–1.5 kHz (Bullock et al. 1982). However, behavioral tests suggest that best sensitivities are at 6–20 kHz (Gerstein et al. 1999) or 8–32 kHz (Bauer et al. 2009). The ability to detect high frequencies may be an adaptation to shallow water, where the propagation of low frequency sound is limited (Gerstein et al. 1999, 2004).

2.5 Sea Otter and Polar Bear

No data are available on the hearing abilities of sea otters (Ketten 1998), although the in-air vocalizations of sea otters have most of their energy concentrated at 3–5 kHz (McShane et al. 1995; Thomson and Richardson 1995). Sea otter vocalizations are considered to be most suitable for short-range communication among individuals (McShane et al. 1995). However, Ghoul et al. (2009) noted that the in-air "screams" of sea otters are loud signals (source level of 93–118 dB re 20 μPa_{pk}) that may be used over larger distances; screams have a frequency of maximum energy ranging from 2 to 8 kHz. In-air audiograms for two river otters indicate that this related species has its best hearing sensitivity at the relatively high frequency of 16 kHz, with some sensitivity from about 460 Hz to 33 kHz (Gunn 1988). However, these data apply to a different species of otter, and to in-air rather than underwater hearing.

Data on the specific hearing capabilities of polar bears are limited. A recent study of the in-air hearing of polar bears applied the auditory evoked potential method while tone pips were played to anesthetized bears (Nachtigall et al. 2007). Hearing was tested in ½ octave steps from 1 to 22.5 kHz, and best hearing sensitivity was found between 11.2 and 22.5 kHz. Although low-frequency hearing was not studied, the data suggested that medium- and some high-frequency sounds may be audible to polar bears. However, polar bears' usual behavior (e.g., remaining on the ice, at the water surface, or on land) reduces or avoids exposure to underwater sounds.

3. Characteristics of Airgun Sounds

Airguns function by venting high-pressure air into the water. The pressure signature of an individual airgun consists of a sharp rise and then fall in pressure, followed by several positive and negative pressure excursions caused by oscillation of the resulting air bubble. The sizes, arrangement, and firing times of the individual airguns in an array are designed and synchronized to suppress the pressure oscillations subsequent to the first cycle. The resulting downward-directed pulse has a duration of only 10–20 ms, with only one strong positive and one strong negative peak pressure (Caldwell and Dragoset 2000). Most energy emitted from airguns is at relatively low frequencies. For example, typical high-energy airgun arrays emit most energy at 10–120 Hz. However, the pulses contain significant energy up to 500–1000 Hz and some energy at higher frequencies (Goold and Fish 1998; Potter et al. 2007). Studies in the Gulf of Mexico have shown that the horizontally-propagating sound can contain significant energy above the frequencies that airgun arrays are designed to emit (DeRuiter et al. 2006; Madsen et al. 2006; Tyack et al. 2006a). Energy at frequencies up to 150 kHz was found in tests of single 60-in^3 and 250-in^3 airguns (Goold and Coates 2006). Nonetheless, the predominant energy is at low frequencies.

The pulsed sounds associated with seismic exploration have higher peak levels than other industrial sounds (except those from explosions) to which whales and other marine mammals are routinely exposed. The nominal source levels of the 2- to 36-airgun arrays used by Lamont-Doherty Earth Observatory (L-DEO) from the R/V *Maurice Ewing* (now retired) and R/V *Marcus G. Langseth* (36 airguns) are 236–265 dB re 1 μPa_{p-p}. These are the nominal source levels applicable to downward propagation. The

effective source levels for horizontal propagation are lower than those for downward propagation when the source consists of numerous airguns spaced apart from one another. Explosions are the only man-made sources with effective source levels as high as (or higher than) a large array of airguns. However, high-power sonars can have source pressure levels as high as a small array of airguns, and signal duration can be longer for a sonar than for an airgun array, making the source energy levels of some sonars more comparable to those of airgun arrays.

Several important mitigating factors need to be kept in mind. (1) Airgun arrays produce intermittent sounds, involving emission of a strong sound pulse for a small fraction of a second followed by several seconds of near silence. In contrast, some other sources produce sounds with lower peak levels, but their sounds are continuous or discontinuous but continuing for longer durations than seismic pulses. (2) Airgun arrays are designed to transmit strong sounds downward through the seafloor, and the amount of sound transmitted in near-horizontal directions is considerably reduced. Nonetheless, they also emit sounds that travel horizontally toward non-target areas. (3) An airgun array is a distributed source, not a point source. The nominal source level is an estimate of the sound that would be measured from a theoretical point source emitting the same total energy as the airgun array. That figure is useful in calculating the expected received levels in the far field, i.e., at moderate and long distances, but not in the near field. Because the airgun array is not a single point source, there is no one location within the near field (or anywhere else) where the received level is as high as the nominal source level.

The strengths of airgun pulses can be measured in different ways, and it is important to know which method is being used when interpreting quoted source or received levels. Geophysicists usually quote peak-to-peak (p-p) levels, in bar-meters or (less often) dB re 1 μPa · m. The peak (= zero-to-peak, or 0-p) level for the same pulse is typically ~6 dB less. In the biological literature, levels of received airgun pulses are often described based on the "average" or "root-mean-square" (rms) level, where the average is calculated over the duration of the pulse. The rms value for a given airgun pulse is typically ~10 dB lower than the peak level, and 16 dB lower than the peak-to-peak value (Greene 1997; McCauley et al. 1998, 2000a). A fourth measure that is increasingly used is the energy, or Sound Exposure Level (SEL), in dB re 1 $\mu Pa^2 \cdot s$. Because the pulses, even when stretched by propagation effects (see below), are usually <1 s in duration, the numerical value of the energy is usually lower than the rms pressure level. However, the units are different.[4] Because the level of a given pulse will differ substantially depending on which of these measures is being applied, it is important to be aware which measure is in use when interpreting any quoted pulse level. In the past, the U.S. National Marine Fisheries Service (NMFS) has commonly referred to rms levels when discussing levels of pulsed sounds that might "harass" marine mammals.

Seismic sound pulses received at any given point will arrive via a direct path, indirect paths that include reflection from the sea surface and bottom, and often indirect paths including segments through the bottom sediments. Sounds propagating via indirect paths travel longer distances and often arrive later

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[4] The rms value for a given airgun array pulse, as measured at a horizontal distance on the order of 0.1 km to 1–10 km in the units dB re 1 μPa, usually averages 10–15 dB higher than the SEL value for the same pulse measured in dB re 1 $\mu Pa^2 \cdot s$ (e.g., Greene 1997). However, there is considerable variation, and the difference tends to be larger close to the airgun array, and less at long distances (Blackwell et al. 2007; MacGillivray and Hannay 2007a,b). In some cases, generally at longer distances, pulses are "stretched" by propagation effects to the extent that the rms and SEL values (in the respective units mentioned above) become very similar (e.g., MacGillivray and Hannay 2007a,b).

than sounds arriving via a direct path. (However, sound traveling in the bottom may travel faster than that in the water, and thus may, in some situations, arrive slightly earlier than the direct arrival despite traveling a greater distance.) These variations in travel time have the effect of lengthening the duration of the received pulse, or may cause two or more received pulses from a single emitted pulse. Near the source, the predominant part of a seismic pulse is ~10–20 ms in duration. In comparison, the pulse duration as received at long horizontal distances can be much greater. For example, for one airgun array operating in the Beaufort Sea, pulse duration was ~300 ms at a distance of 8 km, 500 ms at 20 km, and 850 ms at 73 km (Greene and Richardson 1988).

The rms level for a given pulse (when measured over the duration of that pulse) depends on the extent to which propagation effects have "stretched" the duration of the pulse by the time it reaches the receiver (e.g., Madsen 2005). As a result, the rms values for various received pulses are not perfectly correlated with the SEL (energy) values for the same pulses. There is increasing evidence that biological effects are more directly related to the received energy (e.g., to SEL) than to the rms values averaged over pulse duration (Southall et al. 2007).

Another important aspect of sound propagation is that received levels of low-frequency underwater sounds diminish close to the surface because of pressure-release and interference phenomena that occur at and near the surface (Urick 1983; Richardson et al. 1995; Potter et al. 2007). Paired measurements of received airgun sounds at depths of 3 vs. 9 or 18 m have shown that received levels are typically several decibels lower at 3 m (Greene and Richardson 1988). For a mammal whose auditory organs are within 0.5 or 1 m of the surface, the received level of the predominant low-frequency components of the airgun pulses would be further reduced. In deep water, the received levels at deep depths can be considerably higher than those at relatively shallow (e.g., 18 m) depths and the same horizontal distance from the airguns (Tolstoy et al. 2004a,b).

Pulses of underwater sound from open-water seismic exploration are often detected 50–100 km from the source location, even during operations in nearshore waters (Greene and Richardson 1988; Burgess and Greene 1999). At those distances, the received levels are usually low, <120 dB re 1 μPa on an approximate rms basis. However, faint seismic pulses are sometimes detectable at even greater ranges (e.g., Bowles et al. 1994; Fox et al. 2002). In fact, low-frequency airgun signals sometimes can be detected thousands of kilometers from their source. For example, sound from seismic surveys conducted offshore of Nova Scotia, the coast of western Africa, and northeast of Brazil were reported as a dominant feature of the underwater noise field recorded along the mid-Atlantic ridge (Nieukirk et al. 2004).

4. Masking Effects of Airgun Sounds

Masking is the obscuring of sounds of interest by interfering sounds, generally at similar frequencies (Richardson et al. 1995). Introduced underwater sound will, through masking, reduce the effective communication distance of a marine mammal species if the frequency of the source is close to that used as a signal by the marine mammal, and if the anthropogenic sound is present for a significant fraction of the time (Richardson et al. 1995). If little or no overlap occurs between the introduced sound and the frequencies used by the species, communication is not expected to be disrupted. Also, if the introduced sound is present only infrequently, communication is not expected to be disrupted much if at all. The duty cycle of airguns is low; the airgun sounds are pulsed, with relatively quiet periods between pulses. In most situations, strong airgun sound will only be received for a brief period (<1 s), with these sound pulses being separated by at least several seconds of relative silence, and longer in the case of deep-penetration surveys or refraction surveys. A single airgun array might cause appreciable masking in only one situation: When propagation conditions are such that sound from each airgun pulse reverberates

strongly and persists for much or all of the interval up to the next airgun pulse (e.g., Simard et al. 2005; Clark and Gagnon 2006). Situations with prolonged strong reverberation are infrequent, in our experience. However, it is common for reverberation to cause some lesser degree of elevation of the background level between airgun pulses (e.g., Guerra et al. 2009), and this weaker reverberation presumably reduces the detection range of calls and other natural sounds to some degree.

Although masking effects of pulsed sounds on marine mammal calls and other natural sounds are expected to be limited, there are few specific studies on this. Some whales continue calling in the presence of seismic pulses and whale calls often can be heard between the seismic pulses (e.g., Richardson et al. 1986; McDonald et al. 1995; Greene et al. 1999a,b; Nieukirk et al. 2004; Smultea et al. 2004; Holst et al. 2005a,b, 2006; Dunn and Hernandez 2009). However, there is one recent summary report indicating that calling fin whales distributed in one part of the North Atlantic went silent for an extended period starting soon after the onset of a seismic survey in the area (Clark and Gagnon 2006). It is not clear from that preliminary paper whether the whales ceased calling because of masking, or whether this was a behavioral response not directly involving masking. Also, bowhead whales in the Beaufort Sea may decrease their call rates in response to seismic operations, although movement out of the area might also have contributed to the lower call detection rate (Blackwell et al. 2009a,b). In contrast, Di Iorio and Clark (2009) found evidence of *increased* calling by blue whales during operations by a lower-energy seismic source—a sparker.

Among the odontocetes, there has been one report that sperm whales ceased calling when exposed to pulses from a very distant seismic ship (Bowles et al. 1994). However, more recent studies of sperm whales found that they continued calling in the presence of seismic pulses (Madsen et al. 2002; Tyack et al. 2003; Smultea et al. 2004; Holst et al. 2006; Jochens et al. 2008). Madsen et al. (2006) noted that airgun sounds would not be expected to mask sperm whale calls given the intermittent nature of airgun pulses. Dolphins and porpoises are also commonly heard calling while airguns are operating (Gordon et al. 2004; Smultea et al. 2004; Holst et al. 2005a,b; Potter et al. 2007). Masking effects of seismic pulses are expected to be negligible in the case of the smaller odontocetes, given the intermittent nature of seismic pulses plus the fact that sounds important to them are predominantly at much higher frequencies than are the dominant components of airgun sounds.

Pinnipeds, sirenians and sea otters have best hearing sensitivity and/or produce most of their sounds at frequencies higher than the dominant components of airgun sound, but there is some overlap in the frequencies of the airgun pulses and the calls. However, the intermittent nature of airgun pulses presumably reduces the potential for masking.

A few cetaceans are known to increase the source levels of their calls in the presence of elevated sound levels, shift their peak frequencies in response to strong sound signals, or otherwise modify their vocal behavior in response to increased noise (Dahlheim 1987; Au 1993; reviewed in Richardson et al. 1995:233*ff*, 364*ff*; Lesage et al. 1999; Terhune 1999; Nieukirk et al. 2005; Scheifele et al. 2005; Parks et al. 2007a, 2009; Di Iorio and Clark 2009; Hanser et al. 2009). It is not known how often these types of responses occur upon exposure to airgun sounds. However, blue whales in the St. Lawrence Estuary significantly increased their call rates during sparker operations (Di Iorio and Clark 2009). The sparker, used to obtain seismic reflection data, emitted frequencies of 30–450 Hz with a relatively low source level of 193 dB re 1 $\mu Pa_{pk\text{-}pk}$. If cetaceans exposed to airgun sounds sometimes respond by changing their vocal behavior, this adaptation, along with directional hearing and preadaptation to tolerate some masking by natural sounds (Richardson et al. 1995), would all reduce the importance of masking by seismic pulses.

5. Disturbance by Seismic Surveys

Disturbance includes a variety of effects, including subtle to conspicuous changes in behavior, movement, and displacement. In the terminology of the 1994 amendments to the U.S. Marine Mammal Protection Act (MMPA), seismic noise could cause "Level B" harassment of certain marine mammals. Level B harassment is defined as "...disruption of behavioral patterns, including, but not limited to, migration, breathing, nursing, breeding, feeding, or sheltering."

There has been debate regarding how substantial a change in behavior or mammal activity is required before the animal should be deemed to be "taken by Level B harassment". NMFS has stated that

> "…a simple change in a marine mammal's actions does not always rise to the level of disruption of its behavioral patterns. … If the only reaction to the [human] activity on the part of the marine mammal is within the normal repertoire of actions that are required to carry out that behavioral pattern, NMFS considers [the human] activity not to have caused a disruption of the behavioral pattern, provided the animal's reaction is not otherwise significant enough to be considered disruptive due to length or severity. Therefore, for example, a short-term change in breathing rates or a somewhat shortened or lengthened dive sequence that are within the animal's normal range and that do not have any biological significance (i.e., do no disrupt the animal's overall behavioral pattern of breathing under the circumstances), do not rise to a level requiring a small take authorization." (NMFS 2001, p. 9293).

Based on this guidance from NMFS, and on NRC (2005), simple exposure to sound, or brief reactions that do not disrupt behavioral patterns in a potentially significant manner, do not constitute harassment or "taking". In this analysis, we interpret "potentially significant" to mean in a manner that might have deleterious effects on the well-being of individual marine mammals or their populations.

Even with this guidance, there are difficulties in defining what marine mammals should be counted as "taken by harassment". Available detailed data on reactions of marine mammals to airgun sounds (and other anthropogenic sounds) are limited to relatively few species and situations (see Richardson et al. 1995; Gordon et al. 2004; Nowacek et al. 2007; Southall et al. 2007). Behavioral reactions of marine mammals to sound are difficult to predict in the absence of site- and context-specific data. Reactions to sound, if any, depend on species, state of maturity, experience, current activity, reproductive state, time of day, and many other factors (Richardson et al. 1995; Wartzok et al. 2004; Southall et al. 2007; Weilgart 2007). If a marine mammal reacts to an underwater sound by changing its behavior or moving a small distance, the impacts of the change are unlikely to be significant to the individual, let alone the stock or population. However, if a sound source displaces marine mammals from an important feeding or breeding area for a prolonged period, impacts on individuals and populations could be significant (e.g., Lusseau and Bejder 2007; Weilgart 2007). Also, various authors have noted that some marine mammals that show no obvious avoidance or behavioral changes may still be adversely affected by noise (Brodie 1981; Richardson et al. 1995:317*ff*; Romano et al. 2004; Weilgart 2007; Wright et al. 2009). For example, some research suggests that animals in poor condition or in an already stressed state may not react as strongly to human disturbance as would more robust animals (e.g., Beale and Monaghan 2004).

Studies of the effects of seismic surveys have focused almost exclusively on the effects on individual species or related groups of species, with little scientific or regulatory attention being given to broader community-level issues. Parente et al. (2007) suggested that the diversity of cetaceans near the Brazil coast was reduced during years with seismic surveys. However, a preliminary account of a more recent

analysis suggests that the trend did not persist when additional years were considered (Britto and Silva Barreto 2009).

Given the many uncertainties in predicting the quantity and types of impacts of sound on marine mammals, it is common practice to estimate how many mammals would be present within a particular distance of human activities and/or exposed to a particular level of anthropogenic sound. In most cases, this approach likely overestimates the numbers of marine mammals that would be affected in some biologically important manner. One of the reasons for this is that the selected distances/isopleths are based on limited studies indicating that some animals exhibited short-term reactions at this distance or sound level, whereas the calculation assumes that all animals exposed to this level would react in a biologically significant manner.

The definitions of "taking" in the U.S. MMPA, and its applicability to various activities, were slightly altered in November 2003 for military and federal scientific research activities. Also, NMFS is proposing to replace current Level A and B harassment criteria with guidelines based on exposure characteristics that are specific to particular groups of mammal species and to particular sound types (NMFS 2005). Recently, a committee of specialists on noise impact issues has proposed new science-based impact criteria (Southall et al. 2007). Thus, for projects subject to U.S. jurisdiction, changes in procedures may be required in the near future.

The sound criteria used to estimate how many marine mammals might be disturbed to some biologically significant degree by seismic survey activities are primarily based on behavioral observations of a few species. Detailed studies have been done on humpback, gray, bowhead, and sperm whales, and on ringed seals. Less detailed data are available for some other species of baleen whales and small toothed whales, but for many species there are no data on responses to marine seismic surveys.

5.1 Baleen Whales

Baleen whales generally tend to avoid operating airguns, but avoidance radii are quite variable among species, locations, whale activities, oceanographic conditions affecting sound propagation, etc. (reviewed in Richardson et al. 1995; Gordon et al. 2004). Whales are often reported to show no overt reactions to pulses from large arrays of airguns at distances beyond a few kilometers, even though the airgun pulses remain well above ambient noise levels out to much longer distances. However, baleen whales exposed to strong sound pulses from airguns often react by deviating from their normal migration route and/or interrupting their feeding and moving away. Some of the major studies and reviews on this topic are Malme et al. (1984, 1985, 1988); Richardson et al. (1986, 1995, 1999); Ljungblad et al. (1988); Richardson and Malme (1993); McCauley et al. (1998, 2000a,b); Miller et al. (1999, 2005); Gordon et al. (2004); Moulton and Miller (2005); Stone and Tasker (2006); Johnson et al. (2007); Nowacek et al. (2007) and Weir (2008a). Although baleen whales often show only slight overt responses to operating airgun arrays (Stone and Tasker 2006; Weir 2008a), strong avoidance reactions by several species of mysticetes have been observed at ranges up to 6–8 km and occasionally as far as 20–30 km from the source vessel when large arrays of airguns were used. Experiments with a single airgun showed that bowhead, humpback and gray whales all showed localized avoidance to a single airgun of 20–100 in^3 (Malme et al. 1984, 1985, 1986, 1988; Richardson et al. 1986; McCauley et al. 1998, 2000a,b).

Studies of gray, bowhead, and humpback whales have shown that seismic pulses with received levels of 160–170 dB re 1 μPa_{rms} seem to cause obvious avoidance behavior in a substantial portion of the animals exposed (Richardson et al. 1995). In many areas, seismic pulses from large arrays of airguns diminish to those levels at distances ranging from 4–15 km from the source. More recent studies have

shown that some species of baleen whales (bowheads and humpbacks in particular) at times show strong avoidance at received levels lower than 160–170 dB re 1 μPa_{rms}. The largest avoidance radii involved migrating bowhead whales, which avoided an operating seismic vessel by 20–30 km (Miller et al. 1999; Richardson et al. 1999). In the cases of migrating bowhead (and gray) whales, the observed changes in behavior appeared to be of little or no biological consequence to the animals—they simply avoided the sound source by displacing their migration route to varying degrees, but within the natural boundaries of the migration corridors (Malme et al. 1984; Malme and Miles 1985; Richardson et al. 1995). Feeding bowhead whales, in contrast to migrating whales, show much smaller avoidance distances (Miller et al. 2005; Harris et al. 2007), presumably because moving away from a food concentration has greater cost to the whales than does a course deviation during migration.

The following subsections provide more details on the documented responses of particular species and groups of baleen whales to marine seismic operations.

Humpback Whales.—Responses of humpback whales to seismic surveys have been studied during migration, on the summer feeding grounds, and on Angolan winter breeding grounds; there has also been discussion of effects on the Brazilian wintering grounds. McCauley et al. (1998, 2000a) studied the responses of migrating humpback whales off Western Australia to a full-scale seismic survey with a 16-airgun 2678-in^3 array, and to a single 20 in^3 airgun with a (horizontal) source level of 227 dB re 1 $\mu Pa \cdot m_{p\text{-}p}$. They found that the overall distribution of humpbacks migrating through their study area was unaffected by the full-scale seismic program, although localized displacement varied with pod composition, behavior, and received sound levels. Observations were made from the seismic vessel, from which the maximum viewing distance was listed as 14 km. Avoidance reactions (course and speed changes) began at 4–5 km for traveling pods, with the closest point of approach (CPA) being 3–4 km at an estimated received level of 157–164 dB re 1 μPa_{rms} (McCauley et al. 1998, 2000a). A greater stand-off range of 7–12 km was observed for more sensitive resting pods (cow-calf pairs; McCauley et al. 1998, 2000a). The mean received level for initial avoidance of an approaching airgun was 140 dB re 1 μPa_{rms} for humpback pods containing females, and at the mean CPA distance the received level was 143 dB re 1 μPa_{rms}. One startle response was reported at 112 dB re 1 μPa_{rms}. The initial avoidance response generally occurred at distances of 5–8 km from the airgun array and 2 km from the single airgun. However, some individual humpback whales, especially males, approached within distances of 100–400 m, where the maximum received level was 179 dB re 1 μPa_{rms}. The McCauley et al. (1998, 2000a,b) studies show evidence of greater avoidance of seismic airgun sounds by pods with females than by other pods during humpback migration off Western Australia.

Humpback whales on their summer feeding grounds in southeast Alaska did not exhibit persistent avoidance when exposed to seismic pulses from a 1.64-L (100 in^3) airgun (Malme et al. 1985). Some humpbacks seemed "startled" at received levels of 150–169 dB re 1 μPa. Malme et al. (1985) concluded that there was no clear evidence of avoidance, despite the possibility of subtle effects, at received levels up to 172 re 1 μPa on an approximate rms basis.

Among wintering humpback whales off Angola (n = 52 useable groups), there were no significant differences in encounter rates (sightings/hr) when a 24-airgun array (3147 in^3 or 5085 in^3) was operating vs. silent (Weir 2008a). There was also no significant difference in the mean CPA (closest observed point of approach) distance of the humpback sightings when airguns were on vs. off (3050 m vs. 2700 m, respectively).

It has been suggested that South Atlantic humpback whales wintering off Brazil may be displaced or even strand upon exposure to seismic surveys (Engel et al. 2004). The evidence for this was circum-

stantial and subject to alternative explanations (IAGC 2004). Also, the evidence was not consistent with subsequent results from the same area of Brazil (Parente et al. 2006), or with direct studies of humpbacks exposed to seismic surveys in other areas and seasons (see above). After allowance for data from subsequent years, there was "no observable direct correlation" between strandings and seismic surveys (IWC 2007, p. 236).

Bowhead Whales.—Responsiveness of bowhead whales to seismic surveys can be quite variable depending on their activity (feeding vs. migrating). Bowhead whales on their summer feeding grounds in the Canadian Beaufort Sea showed no obvious reactions to pulses from seismic vessels at distances of 6–99 km and received sound levels of 107–158 dB on an approximate rms basis (Richardson et al. 1986); their general activities were indistinguishable from those of a control group. However, subtle but statistically significant changes in surfacing–respiration–dive cycles were evident upon statistical analysis. Bowheads usually did show strong avoidance responses when seismic vessels approached within a few kilometers (~3–7 km) and when received levels of airgun sounds were 152–178 dB (Richardson et al. 1986, 1995; Ljungblad et al. 1988; Miller et al. 2005). They also moved away when a single airgun fired nearby (Richardson et al. 1986; Ljungblad et al. 1988). In one case, bowheads engaged in near-bottom feeding began to turn away from a 30-airgun array with a source level of 248 dB re 1 μPa·m at a distance of 7.5 km, and swam away when it came within ~2 km; some whales continued feeding until the vessel was 3 km away (Richardson et al. 1986). This work and subsequent summer studies in the same region by Miller et al. (2005) and Harris et al. (2007) showed that many feeding bowhead whales tend to tolerate higher sound levels than migrating bowhead whales (see below) before showing an overt change in behavior. On the summer feeding grounds, bowhead whales are often seen from the operating seismic ship, though average sighting distances tend to be larger when the airguns are operating. Similarly, preliminary analyses of recent data from the Alaskan Beaufort Sea indicate that bowheads feeding there during late summer and autumn also did not display large-scale distributional changes in relation to seismic operations (Christie et al. 2009; Koski et al. 2009). However, some individual bowheads apparently begin to react at distances a few kilometers away, beyond the distance at which observers on the ship can sight bowheads (Richardson et al. 1986; Citta et al. 2007). The feeding whales may be affected by the sounds, but the need to feed may reduce the tendency to move away until the airguns are within a few kilometers.

Migrating bowhead whales in the Alaskan Beaufort Sea seem more responsive to noise pulses from a distant seismic vessel than are summering bowheads. Bowhead whales migrating west across the Alaskan Beaufort Sea in autumn are unusually responsive, with substantial avoidance occurring out to distances of 20–30 km from a medium-sized airgun source at received sound levels of around 120–130 dB re 1 μPa_{rms} (Miller et al. 1999; Richardson et al. 1999; see also Manly et al. 2007). Those results came from 1996–98, when a partially-controlled study of the effect of Ocean Bottom Cable (OBC) seismic surveys on westward-migrating bowheads was conducted in late summer and autumn in the Alaskan Beaufort Sea. At times when the airguns were not active, many bowheads moved into the area close to the inactive seismic vessel. Avoidance of the area of seismic operations did not persist beyond 12–24 h after seismic shooting stopped. Preliminary analysis of recent data on traveling bowheads in the Alaskan Beaufort Sea also showed a stronger tendency to avoid operating airguns than was evident for feeding bowheads (Christie et al. 2009; Koski et al. 2009).

Bowhead whale calls detected in the presence and absence of airgun sounds have been studied extensively in the Beaufort Sea. Early work on the summering grounds in the Canadian Beaufort Sea showed that bowheads continue to produce calls of the usual types when exposed to airgun sounds, although numbers of calls detected may be somewhat lower in the presence of airgun pulses (Richardson

et al. 1986). Studies during autumn in the Alaskan Beaufort Sea, one in 1996–1998 and another in 2007–2008, have shown that numbers of calls detected are significantly lower in the presence than in the absence of airgun pulses (Greene et al. 1999a,b; Blackwell et al. 2009a,b; Koski et al. 2009; see also Nations et al. 2009). This decrease could have resulted from movement of the whales away from the area of the seismic survey or a reduction in calling behavior, or a combination of the two. However, concurrent aerial surveys showed that there was strong avoidance of the operating airguns during the 1996–98 study, when most of the whales appeared to be migrating (Miller et al. 1999; Richardson et al. 1999). In contrast, aerial surveys during the 2007–08 study showed less consistent avoidance by the bowheads, many of which appeared to be feeding (Christie et al. 2009; Koski et al. 2009). The reduction in call detection rates during periods of airgun operation may have been more dependent on actual avoidance during the 1996–98 study and more dependent on reduced calling behavior during the 2007–08 study, but further analysis of the recent data is ongoing.

There are no data on reactions of bowhead whales to seismic surveys in winter or spring.

Gray Whales.—Malme et al. (1986, 1988) studied the responses of feeding eastern gray whales to pulses from a single 100-in^3 airgun off St. Lawrence Island in the northern Bering Sea. They estimated, based on small sample sizes, that 50% of feeding gray whales stopped feeding at an average received pressure level of 173 dB re 1 μPa on an (approximate) rms basis, and that 10% of feeding whales interrupted feeding at received levels of 163 dB re 1 μPa_{rms}. Malme at al. (1986) estimated that an average pressure level of 173 dB occurred at a range of 2.6–2.8 km from an airgun array with a source level of 250 dB re 1 μPa_{peak} in the northern Bering Sea. These findings were generally consistent with the results of studies conducted on larger numbers of gray whales migrating off California (Malme et al. 1984; Malme and Miles 1985) and western Pacific gray whales feeding off Sakhalin, Russia (Würsig et al. 1999; Gailey et al. 2007; Johnson et al. 2007; Yazvenko et al. 2007a,b), along with a few data on gray whales off British Columbia (Bain and Williams 2006).

Malme and Miles (1985) concluded that, during migration off California, gray whales showed changes in swimming pattern with received levels of ~160 dB re 1 μPa and higher, on an approximate rms basis. The 50% probability of avoidance was estimated to occur at a CPA distance of 2.5 km from a 4000-in^3 airgun array operating off central California. This would occur at an average received sound level of ~170 dB re 1 μPa_{rms}. Some slight behavioral changes were noted when approaching gray whales reached the distances where received sound levels were 140 to 160 dB re 1 μPa_{rms}, but these whales generally continued to approach (at a slight angle) until they passed the sound source at distances where received levels averaged ~170 dB re 1 μPa_{rms} (Malme et al. 1984; Malme and Miles 1985).

There was no indication that western gray whales exposed to seismic noise were displaced from their overall feeding grounds near Sakhalin Island during seismic programs in 1997 (Würsig et al. 1999) and in 2001 (Johnson et al. 2007; Meier et al. 2007; Yazvenko et al. 2007a). However, there were indications of subtle behavioral effects among whales that remained in the areas exposed to airgun sounds (Würsig et al. 1999; Gailey et al. 2007; Weller et al. 2006a). Also, there was evidence of localized redistribution of some individuals within the nearshore feeding ground so as to avoid close approaches by the seismic vessel (Weller et al. 2002, 2006b; Yazvenko et al. 2007a). Despite the evidence of subtle changes in some quantitative measures of behavior and local redistribution of some individuals, there was no apparent change in the frequency of feeding, as evident from mud plumes visible at the surface (Yazvenko et al. 2007b). The 2001 seismic program involved an unusually comprehensive combination of real-time monitoring and mitigation measures designed to avoid exposing western gray whales to received levels of sound above about 163 dB re 1 μPa_{rms} (Johnson et al. 2007). The lack of strong avoid-

ance or other strong responses was presumably in part a result of the mitigation measures. Effects probably would have been more significant without such intensive mitigation efforts.

Gray whales in British Columbia exposed to seismic survey sound levels up to ~170 dB re 1 μPa did not appear to be strongly disturbed (Bain and Williams 2006). The few whales that were observed moved away from the airguns but toward deeper water where sound levels were said to be higher due to propagation effects (Bain and Williams 2006).

Rorquals.—Blue, sei, fin, and minke whales (all of which are members of the genus *Balaenoptera*) often have been seen in areas ensonified by airgun pulses (Stone 2003; MacLean and Haley 2004; Stone and Tasker 2006), and calls from blue and fin whales have been localized in areas with airgun operations (e.g., McDonald et al. 1995; Dunn and Hernandez 2009). Sightings by observers on seismic vessels during 110 large-source seismic surveys off the U.K. from 1997 to 2000 suggest that, during times of good sightability, sighting rates for mysticetes (mainly fin and sei whales) were similar when large arrays of airguns were shooting vs. silent (Stone 2003; Stone and Tasker 2006). However, these whales tended to exhibit localized avoidance, remaining significantly further (on average) from the airgun array during seismic operations compared with non-seismic periods (P = 0.0057; Stone and Tasker 2006). The average CPA distances for baleen whales sighted when large airgun arrays were operating vs. silent were about 1.6 vs. 1.0 km. Baleen whales, as a group, were more often oriented away from the vessel while a large airgun array was shooting compared with periods of no shooting (P <0.05; Stone and Tasker 2006). In addition, fin/sei whales were less likely to remain submerged during periods of seismic shooting (Stone 2003).

In a study off Nova Scotia, Moulton and Miller (2005) found little difference in sighting rates (after accounting for water depth) and initial average sighting distances of balaenopterid whales when airguns were operating (mean = 1324 m) vs. silent (mean = 1303 m). However, there were indications that these whales were more likely to be moving away when seen during airgun operations. Baleen whales at the average sighting distance during airgun operations would have been exposed to sound levels (via direct path) of about 169 dB re 1 μPa_{rms} (Moulton and Miller 2005). Similarly, ship-based monitoring studies of blue, fin, sei and minke whales offshore of Newfoundland (Orphan Basin and Laurentian Sub-basin) found no more than small differences in sighting rates and swim directions during seismic vs. non-seismic periods (Moulton et al. 2005, 2006a,b). Analyses of CPA data yielded variable results.[5] The authors of the Newfoundland reports concluded that, based on observations from the seismic vessel, some mysticetes exhibited localized avoidance of seismic operations (Moulton et al. 2005, 2006a).

Minke whales have occasionally been observed to approach active airgun arrays where received sound levels were estimated to be near 170–180 dB re 1 μPa (McLean and Haley 2004).

Discussion and Conclusions.—Baleen whales generally tend to avoid operating airguns, but avoidance radii are quite variable. Whales are often reported to show no overt reactions to airgun pulses at distances beyond a few kilometers, even though the airgun pulses remain well above ambient noise

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[5] The CPA of baleen whales sighted from the seismic vessels was, on average, significantly closer during non-seismic periods vs. seismic periods in 2004 in the Orphan Basin (means 1526 m vs. 2316 m, respectively; Moulton et al. 2005). In contrast, mean distances without vs. with seismic did not differ significantly in 2005 in either the Orphan Basin (means 973 m vs. 832 m, respectively; Moulton et al. 2006a) or in the Laurentian Sub-basin (means 1928 m vs. 1650 m, respectively; Moulton et al. 2006b). In both 2005 studies, mean distances were greater (though not significantly so) *without* seismic.

levels out to much longer distances. However, studies done since the late 1990s of migrating humpback and migrating bowhead whales show reactions, including avoidance, that sometimes extend to greater distances than documented earlier. Avoidance distances often exceed the distances at which boat-based observers can see whales, so observations from the source vessel can be biased. Observations over broader areas may be needed to determine the range of potential effects of some large-source seismic surveys where effects on cetaceans may extend to considerable distances (Richardson et al. 1999; Bain and Williams 2006; Moore and Angliss 2006). Longer-range observations, when required, can sometimes be obtained via systematic aerial surveys or aircraft-based observations of behavior (e.g., Richardson et al. 1986, 1999; Miller et al. 1999, 2005; Yazvenko et al. 2007a,b) or by use of observers on one or more support vessels operating in coordination with the seismic vessel (e.g., Smultea et al. 2004; Johnson et al. 2007). However, the presence of other vessels near the source vessel can, at least at times, reduce sightability of cetaceans from the source vessel (Beland et al. 2009), thus complicating interpretation of sighting data.

Some baleen whales show considerable tolerance of seismic pulses. However, when the pulses are strong enough, avoidance or other behavioral changes become evident. Because the responses become less obvious with diminishing received sound level, it has been difficult to determine the maximum distance (or minimum received sound level) at which reactions to seismic become evident and, hence, how many whales are affected.

Studies of gray, bowhead, and humpback whales have determined that received levels of pulses in the 160–170 dB re 1 μPa_{rms} range seem to cause obvious avoidance behavior in a substantial fraction of the animals exposed. In many areas, seismic pulses diminish to these levels at distances ranging from 4 to 15 km from the source. A substantial proportion of the baleen whales within such distances may show avoidance or other strong disturbance reactions to the operating airgun array. However, in other situations, various mysticetes tolerate exposure to full-scale airgun arrays operating at even closer distances, with only localized avoidance and minor changes in activities. At the other extreme, in migrating bowhead whales, avoidance often extends to considerably larger distances (20–30 km) and lower received sound levels (120–130 dB re 1 μPa_{rms}). Also, even in cases where there is no conspicuous avoidance or change in activity upon exposure to sound pulses from distant seismic operations, there are sometimes subtle changes in behavior (e.g., surfacing–respiration–dive cycles) that are only evident through detailed statistical analysis (e.g., Richardson et al. 1986; Gailey et al. 2007).

Mitigation measures for seismic surveys, especially nighttime seismic surveys, typically assume that many marine mammals (at least baleen whales) tend to avoid approaching airguns, or the seismic vessel itself, before being exposed to levels high enough for there to be any possibility of injury. This assumes that the ramp-up (soft-start) procedure is used when commencing airgun operations, to give whales near the vessel the opportunity to move away before they are exposed to sound levels that might be strong enough to elicit TTS. As noted above, single-airgun experiments with three species of baleen whales show that those species typically do tend to move away when a single airgun starts firing nearby, which simulates the onset of a ramp up. The three species that showed avoidance when exposed to the onset of pulses from a single airgun were *gray whales* (Malme et al. 1984, 1986, 1988); *bowhead whales* (Richardson et al. 1986; Ljungblad et al. 1988); and *humpback whales* (Malme et al. 1985; McCauley et al. 1998, 2000a,b). Since startup of a single airgun is equivalent to the start of a ramp-up (=soft start), this strongly suggests that many baleen whales will begin to move away during the initial stages of a ramp-up.

Data on short-term reactions by cetaceans to impulsive noises are not necessarily indicative of long-term or biologically significant effects. It is not known whether impulsive sounds affect reproduc-

tive rate or distribution and habitat use in subsequent days or years. However, gray whales have continued to migrate annually along the west coast of North America despite intermittent seismic exploration (and much ship traffic) in that area for decades (Appendix A *in* Malme et al. 1984; Richardson et al. 1995), and there has been a substantial increase in the population over recent decades (Angliss and Outlaw 2008). The western Pacific gray whale population did not seem affected by a seismic survey in its feeding ground during a prior year (Johnson et al. 2007). Similarly, bowhead whales have continued to travel to the eastern Beaufort Sea each summer despite seismic exploration in their summer and autumn range for many years (Richardson et al. 1987), and their numbers have increased notably (Angliss and Outlaw 2008). Bowheads also have been observed over periods of days or weeks in areas ensonified repeatedly by seismic pulses (Richardson et al. 1987; Harris et al. 2007). However, it is generally not known whether the same individual bowheads were involved in these repeated observations (within and between years) in strongly ensonified areas. In any event, in the absence of some unusual circumstances, the history of coexistence between seismic surveys and baleen whales suggests that brief exposures to sound pulses from any single seismic survey are unlikely to result in prolonged effects.

5.2 Toothed Whales

Little systematic information is available about reactions of toothed whales to noise pulses. Few studies similar to the more extensive baleen whale/seismic pulse work summarized above have been reported for toothed whales. However, there are recent systematic data on sperm whales (e.g., Gordon et al. 2006; Madsen et al. 2006; Winsor and Mate 2006; Jochens et al. 2008; Miller et al. 2009). There is also an increasing amount of information about responses of various odontocetes to seismic surveys based on monitoring studies (e.g., Stone 2003; Smultea et al. 2004; Moulton and Miller 2005; Bain and Williams 2006; Holst et al. 2006; Stone and Tasker 2006; Potter et al. 2007; Hauser et al. 2008; Holst and Smultea 2008; Weir 2008a; Barkaszi et al. 2009; Richardson et al. 2009).

Delphinids (Dolphins and similar) and Monodontids (Beluga).—Seismic operators and marine mammal observers on seismic vessels regularly see dolphins and other small toothed whales near operating airgun arrays, but in general there is a tendency for most delphinids to show some avoidance of operating seismic vessels (e.g., Goold 1996a,b,c; Calambokidis and Osmek 1998; Stone 2003; Moulton and Miller 2005; Holst et al. 2006; Stone and Tasker 2006; Weir 2008a; Richardson et al. 2009; see also Barkaszi et al. 2009). In most cases, the avoidance radii for delphinids appear to be small, on the order of 1 km or less, and some individuals show no apparent avoidance. Studies that have reported cases of small toothed whales close to the operating airguns include Duncan (1985), Arnold (1996), Stone (2003), and Holst et al. (2006). When a 3959 in^3, 18-airgun array was firing off California, toothed whales behaved in a manner similar to that observed when the airguns were silent (Arnold 1996). Some dolphins seem to be attracted to the seismic vessel and floats, and some ride the bow wave of the seismic vessel even when a large array of airguns is firing (e.g., Moulton and Miller 2005). Nonetheless, small toothed whales more often tend to head away, or to maintain a somewhat greater distance from the vessel, when a large array of airguns is operating than when it is silent (e.g., Stone and Tasker 2006; Weir 2008a).

Weir (2008b) noted that a group of short-finned pilot whales initially showed an avoidance response to ramp up of a large airgun array, but that this response was limited in time and space. Although the ramp-up procedure is a widely-used mitigation measure, it remains uncertain how effective it is at alerting marine mammals (especially odontocetes) and causing them to move away from seismic operations (Weir 2008b).

Goold (1996a,b,c) studied the effects on common dolphins of 2D seismic surveys in the Irish Sea. Passive acoustic surveys were conducted from the "guard ship" that towed a hydrophone. The results indicated that there was a local displacement of dolphins around the seismic operation. However, observations indicated that the animals were tolerant of the sounds at distances outside a 1-km radius from the airguns (Goold 1996a). Initial reports of larger-scale displacement were later shown to represent a normal autumn migration of dolphins through the area, and were not attributable to seismic surveys (Goold 1996a,b,c).

The beluga is a species that (at least at times) shows long-distance avoidance of seismic vessels. Aerial surveys conducted in the southeastern Beaufort Sea in summer found that sighting rates of belugas were significantly lower at distances 10–20 km compared with 20–30 km from an operating airgun array (Miller et al. 2005). The low number of beluga sightings by marine mammal observers on the vessel seemed to confirm there was a strong avoidance response to the 2250 in^3 airgun array. More recent seismic monitoring studies in the same area have confirmed that the apparent displacement effect on belugas extended farther than has been shown for other small odontocetes exposed to airgun pulses (e.g., Harris et al. 2007).

Observers stationed on seismic vessels operating off the U.K. from 1997 to 2000 have provided data on the occurrence and behavior of various toothed whales exposed to seismic pulses (Stone 2003; Gordon et al. 2004; Stone and Tasker 2006). Dolphins of various species often showed more evidence of avoidance of operating airgun arrays than has been reported previously for small odontocetes. Sighting rates of white-sided dolphins, white-beaked dolphins, *Lagenorhynchus* spp., and all small odontocetes combined were significantly lower during periods when large-volume[6] airgun arrays were shooting. Except for the pilot whale and bottlenose dolphin, CPA distances for all of the small odontocete species tested, including killer whales, were significantly farther from large airgun arrays during periods of shooting compared with periods of no shooting. Pilot whales were less responsive than other small odontocetes in the presence of seismic surveys (Stone and Tasker 2006). For small odontocetes as a group, and most individual species, orientations differed between times when large airgun arrays were operating vs. silent, with significantly fewer animals traveling towards and/or more traveling away from the vessel during shooting (Stone and Tasker 2006). Observers' records suggested that fewer cetaceans were feeding and fewer were interacting with the survey vessel (e.g., bow-riding) during periods with airguns operating, and small odontocetes tended to swim faster during periods of shooting (Stone and Tasker 2006). For most types of small odontocetes sighted by observers on seismic vessels, the median CPA distance was≥0.5 km larger during airgun operations (Stone and Tasker 2006). Killer whales appeared to be more tolerant of seismic shooting in deeper waters.

Data collected during seismic operations in the Gulf of Mexico and off Central America show similar patterns. A summary of vessel-based monitoring data from the Gulf of Mexico during 2003–2008 showed that delphinids were generally seen farther from the vessel during seismic than during non-seismic periods (based on Barkaszi et al. 2009, excluding sperm whales). Similarly, during two NSF-funded L-DEO seismic surveys that used a large 20 airgun array (~7000 in^3), sighting rates of delphinids were lower and initial sighting distances were farther away from the vessel during seismic than non-seismic periods (Smultea et al. 2004; Holst et al. 2005a, 2006; Richardson et al. 2009). Monitoring results during a seismic survey in the Southeast Caribbean showed that the mean CPA of delphinids was 991 m during seismic operations vs. 172 m when the airguns were not operational (Smultea et al. 2004).

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[6] Large volume means at least 1300 in^3, with most (79%) at least 3000 in^3.

Surprisingly, nearly all acoustic detections via a towed passive acoustic monitoring (PAM) array, including both delphinids and sperm whales, were made when the airguns were operating (Smultea et al. 2004). Although the number of sightings during monitoring of a seismic survey off the Yucatán Peninsula, Mexico, was small (n = 19), the results showed that the mean CPA distance of delphinids there was 472 m during seismic operations vs. 178 m when the airguns were silent (Holst et al. 2005a). The acoustic detection rates were nearly 5 times higher during non-seismic compared with seismic operations (Holst et al. 2005a).

For two additional NSF-funded L-DEO seismic surveys in the Eastern Tropical Pacific, both using a large 36-airgun array (~6600 in^3), the results are less easily interpreted (Richardson et al. 2009). During both surveys, the delphinid detection rate was lower during seismic than during non-seismic periods, as found in various other projects, but the mean CPA distance of delphinids was closer (not farther) during seismic periods (Hauser et al. 2008; Holst and Smultea 2008).

During two seismic surveys off Newfoundland and Labrador in 2004–05, dolphin sighting rates were lower during seismic periods than during non-seismic periods after taking temporal factors into account, although the difference was statistically significant only in 2004 (Moulton et al. 2005, 2006a). In 2005, the mean CPA distance of dolphins was significantly farther during seismic periods (807 vs. 652 m); in 2004, the corresponding difference was not significant.

Among Atlantic spotted dolphins off Angola (n = 16 useable groups), marked short-term and localized displacement was found in response to seismic operations conducted with a 24-airgun array (3147 in^3 or 5085 in^3) (Weir 2008a). Sample sizes were low, but CPA distances of dolphin groups were significantly larger when airguns were on (mean 1080 m) vs. off (mean 209 m). No Atlantic spotted dolphins were seen within 500 m of the airguns when they were operating, whereas all sightings when airguns were silent occurred within 500 m, including the only recorded "positive approach" behaviors.

Reactions of toothed whales to a single airgun or other small airgun source are not well documented, but tend to be less substantial than reactions to large airgun arrays (e.g., Stone 2003; Stone and Tasker 2006). During 91 site surveys off the U.K. in 1997–2000, sighting rates of all small odontocetes combined were significantly lower during periods the low-volume[7] airgun sources were operating, and effects on orientation were evident for all species and groups tested (Stone and Tasker 2006). Results from four NSF-funded L-DEO seismic surveys using small arrays (up to 3 GI guns and 315 in^3) were inconclusive. During surveys in the Eastern Tropical Pacific (Holst et al. 2005b) and in the Northwest Atlantic (Haley and Koski 2004), detection rates were slightly lower during seismic compared to non-seismic periods. However, mean CPAs were closer during seismic operations during one cruise (Holst et al. 2005b), and greater during the other cruise (Haley and Koski 2004). Interpretation of the data was confounded by the fact that survey effort and/or number of sightings during non-seismic periods during both surveys was small. Results from another two small-array surveys were even more variable (MacLean and Koski 2005; Smultea and Holst 2008).

Captive bottlenose dolphins and beluga whales exhibited changes in behavior when exposed to strong pulsed sounds similar in duration to those typically used in seismic surveys (Finneran et al. 2000, 2002, 2005). Finneran et al. (2002) exposed a captive bottlenose dolphin and beluga to single impulses from a water gun (80 in^3). As compared with airgun pulses, water gun impulses were expected to contain proportionally more energy at higher frequencies because there is no significant gas-filled bubble, and

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[7] For low volume arrays, maximum volume was 820 in^3, with most (87%) $\leq$180 in^3.

thus little low-frequency bubble-pulse energy (Hutchinson and Detrick 1984). The captive animals sometimes vocalized after exposure and exhibited reluctance to station at the test site where subsequent exposure to impulses would be implemented (Finneran et al. 2002). Similar behaviors were exhibited by captive bottlenose dolphins and a beluga exposed to single underwater pulses designed to simulate those produced by distant underwater explosions (Finneran et al. 2000). It is uncertain what relevance these observed behaviors in captive, trained marine mammals exposed to single transient sounds may have to free-ranging animals exposed to multiple pulses. In any event, the animals tolerated rather high received levels of sound before exhibiting the aversive behaviors mentioned above.

Odontocete responses (or lack of responses) to noise pulses from underwater explosions (as opposed to airgun pulses) may be indicative of odontocete responses to very strong noise pulses. During the 1950s, small explosive charges were dropped into an Alaskan river in attempts to scare belugas away from salmon. Success was limited (Fish and Vania 1971; Frost et al. 1984). Small explosive charges were "not always effective" in moving bottlenose dolphins away from sites in the Gulf of Mexico where larger demolition blasts were about to occur (Klima et al. 1988). Odontocetes may be attracted to fish killed by explosions, and thus attracted rather than repelled by "scare" charges. Captive false killer whales showed no obvious reaction to single noise pulses from small (10 g) charges; the received level was ~185 dB re 1 μPa (Akamatsu et al. 1993). Jefferson and Curry (1994) reviewed several additional studies that found limited or no effects of noise pulses from small explosive charges on killer whales and other odontocetes. Aside from the potential for causing auditory impairment (see below), the tolerance to these charges may indicate a lack of effect, or the failure to move away may simply indicate a stronger desire to feed, regardless of circumstances.

Phocoenids (Porpoises).—Porpoises, like delphinids, show variable reactions to seismic operations, and reactions apparently depend on species. The limited available data suggest that harbor porpoises show stronger avoidance of seismic operations than Dall's porpoises (Stone 2003; MacLean and Koski 2005; Bain and Williams 2006). In Washington State waters, the harbor porpoise—despite being considered a high-frequency specialist—appeared to be the species affected by the lowest received level of airgun sound (<145 dB re 1 μPa_{rms} at a distance >70 km; Bain and Williams 2006). Similarly, during seismic surveys with large airgun arrays off the U.K. in 1997–2000, there were significant differences in directions of travel by harbor porpoises during periods when the airguns were shooting vs. silent (Stone 2003; Stone and Tasker 2006). A captive harbor porpoise exposed to single sound pulses from a small airgun showed aversive behavior upon receipt of a pulse with received level above 174 dB re 1 $\mu Pa_{pk\text{-}pk}$ or SEL >145 dB re 1 $\mu Pa^2 \cdot s$ (Lucke et al. 2009). In contrast, Dall's porpoises seem relatively tolerant of airgun operations (MacLean and Koski 2005; Bain and Williams 2006), although they too have been observed to avoid large arrays of operating airguns (Calambokidis and Osmek 1998; Bain and Williams 2006). The apparent tendency for greater responsiveness in the harbor porpoise is consistent with their relative responsiveness to boat traffic and some other acoustic sources (Richardson et al. 1995; Southall et al. 2007).

Beaked Whales.—There are almost no specific data on the behavioral reactions of beaked whales to seismic surveys. Most beaked whales tend to avoid approaching vessels of other types (e.g., Würsig et al. 1998). They may also dive for an extended period when approached by a vessel (e.g., Kasuya 1986), although it is uncertain how much longer such dives may be as compared to dives by undisturbed beaked whales, which also are often quite long (Baird et al. 2006; Tyack et al. 2006b). In any event, it is likely that most beaked whales would also show strong avoidance of an approaching seismic vessel, regardless of whether or not the airguns are operating. However, this has not been documented explicitly. Northern bottlenose whales sometimes are quite tolerant of slow-moving vessels not emitting airgun pulses (Reeves

et al. 1993; Hooker et al. 2001). The few detections (acoustic or visual) of northern bottlenose whales from seismic vessels during recent seismic surveys off Nova Scotia have been during times when the airguns were shut down; no detections were reported when the airguns were operating (Moulton and Miller 2005; Potter et al. 2007). However, other visual and acoustic studies indicated that some northern bottlenose whales remained in the general area and continued to produce high-frequency clicks when exposed to sound pulses from distant seismic surveys (Gosselin and Lawson 2004; Laurinolli and Cochrane 2005; Simard et al. 2005).

There are increasing indications that some beaked whales tend to strand when military exercises involving mid-frequency sonar operation are ongoing nearby (e.g., Simmonds and Lopez-Jurado 1991; Frantzis 1998; NOAA and USN 2001; Jepson et al. 2003; Barlow and Gisiner 2006; see also the "Strandings and Mortality" subsection, later). These strandings are apparently at least in part a disturbance response, although auditory or other injuries or other physiological effects may also be a factor. Whether beaked whales would ever react similarly to seismic surveys is unknown. Seismic survey sounds are quite different from those of the sonars in operation during the above-cited incidents. No conclusive link has been established between seismic surveys and beaked whale strandings. There was a stranding of two Cuvier's beaked whales in the Gulf of California (Mexico) in September 2002 when the R/V *Maurice Ewing* was conducting a seismic survey in the general area (e.g., Malakoff 2002; Hildebrand 2005). However, NMFS did not establish a cause and effect relationship between this stranding and the seismic survey activities (Hogarth 2002). Cox et al. (2006) noted the "lack of knowledge regarding the temporal and spatial correlation between the [stranding] and the sound source". Hildebrand (2005) illustrated the approximate temporal-spatial relationships between the stranding and the *Ewing*'s tracks, but the time of the stranding was not known with sufficient precision for accurate determination of the CPA distance of the whales to the *Ewing*. Another stranding of Cuvier's beaked whales in the Galápagos occurred during a seismic survey in April 2000; however "There is no obvious mechanism that bridges the distance between this source and the stranding site" (Gentry [ed.] 2002).

Sperm Whales.—All three species of sperm whales have been reported to show avoidance reactions to standard vessels not emitting airgun sounds (e.g., Richardson et al. 1995; Würsig et al. 1998; McAlpine 2002; Baird 2005). However, most studies of the sperm whale *Physeter macrocephalus* exposed to airgun sounds indicate that this species shows considerable tolerance of airgun pulses. The whales usually do not show strong avoidance (i.e., they do not leave the area) and they continue to call.

There were some early and limited observations suggesting that sperm whales in the Southern Ocean ceased calling during some (but not all) times when exposed to weak noise pulses from extremely distant (>300 km) seismic exploration. However, other operations in the area could also have been a factor (Bowles et al. 1994). This "quieting" was suspected to represent a disturbance effect, in part because sperm whales exposed to pulsed man-made sounds at higher frequencies often cease calling (Watkins and Schevill 1975; Watkins et al. 1985). Also, there was an early preliminary account of possible long-range avoidance of seismic vessels by sperm whales in the Gulf of Mexico (Mate et al. 1994). However, this has not been substantiated by subsequent more detailed work in that area (Gordon et al. 2006; Winsor and Mate 2006; Jochens et al. 2008; Miller et al. 2009).

Recent and more extensive data from vessel-based monitoring programs in U.K. waters and off Newfoundland and Angola suggest that sperm whales in those areas show little evidence of avoidance or behavioral disruption in the presence of operating seismic vessels (Stone 2003; Stone and Tasker 2006; Moulton et al. 2005, 2006a; Weir 2008a). Among sperm whales off Angola (n = 96 useable groups), there were no significant differences in encounter rates (sightings/hr) when a 24-airgun array (3147 in^3 or

5085 in^3) was operating vs. silent (Weir 2008a). There was also no significant difference in the CPA distances of the sperm whale sightings when airguns were on vs. off (means 3039 m vs. 2594 m, respectively). Encounter rate tended to increase over the 10-month duration of the seismic survey. These types of observations are difficult to interpret because the observers are stationed on or near the seismic vessel, and may underestimate reactions by some of the more responsive animals, which may be beyond visual range. However, these results do seem to show considerable tolerance of seismic surveys by at least some sperm whales. Also, a study off northern Norway indicated that sperm whales continued to call when exposed to pulses from a distant seismic vessel. Received levels of the seismic pulses were up to 146 dB re 1 $\mu Pa_{p\text{-}p}$ (Madsen et al. 2002).

Similarly, a study conducted off Nova Scotia that analyzed recordings of sperm whale vocalizations at various distances from an active seismic program did not detect any obvious changes in the distribution or behavior of sperm whales (McCall Howard 1999).

Sightings of sperm whales by observers on seismic vessels operating in the Gulf of Mexico during 2003–2008 were at very similar average distances regardless of the airgun operating conditions (Barkaszi et al. 2009). For example, the mean sighting distance was 1839 m when the airgun array was in full operation (n=612) vs. 1960 m when all airguns were off (n=66).

A controlled study of the reactions of tagged sperm whales to seismic surveys was done recently in the Gulf of Mexico — the Sperm Whale Seismic Study or SWSS (Gordon et al. 2006; Madsen et al. 2006; Winsor and Mate 2006; Jochens et al. 2008; Miller et al. 2009). During SWSS, D-tags (Johnson and Tyack 2003) were used to record the movement and acoustic exposure of eight foraging sperm whales before, during, and after controlled exposures to sound from airgun arrays (Jochens et al. 2008; Miller et al. 2009). Whales were exposed to maximum received sound levels of 111–147 dB re 1 μPa_{rms} (131–162 dB re 1 $\mu Pa_{pk\text{-}pk}$) at ranges of ~1.4–12.8 km from the sound source (Miller et al. 2009). Although the tagged whales showed no discernible horizontal avoidance, some whales showed changes in diving and foraging behavior during full-array exposure, possibly indicative of subtle negative effects on foraging (Jochens et al. 2008; Miller et al. 2009; Tyack 2009). Two indications of foraging that they studied were oscillations in pitch and occurrence of echolocation buzzes, both of which tend to occur when a sperm whale closes-in on prey. "Oscillations in pitch generated by swimming movements during foraging dives were on average 6% lower during exposure than during the immediately following post-exposure period, with all 7 foraging whales exhibiting less pitching (P = 0.014). Buzz rates, a proxy for attempts to capture prey, were 19% lower during exposure…" (Miller et al. 2009). Although the latter difference was not statistically significant (P = 0.141), the percentage difference in buzz rate during exposure vs. post-exposure conditions appeared to be strongly correlated with airgun-whale distance (Miller et al. 2009: Fig. 5; Tyack 2009).

Discussion and Conclusions.—Dolphins and porpoises are often seen by observers on active seismic vessels, occasionally at close distances (e.g., bow riding). However, some studies near the U.K., Newfoundland and Angola, in the Gulf of Mexico, and off Central America have shown localized avoidance. Also, belugas summering in the Canadian Beaufort Sea showed larger-scale avoidance, tending to avoid waters out to 10–20 km from operating seismic vessels. In contrast, recent studies show little evidence of conspicuous reactions by sperm whales to airgun pulses, contrary to earlier indications.

There are almost no specific data on responses of beaked whales to seismic surveys, but it is likely that most if not all species show strong avoidance. There is increasing evidence that some beaked whales may strand after exposure to strong noise from sonars. Whether they ever do so in response to seismic

survey noise is unknown. Northern bottlenose whales seem to continue to call when exposed to pulses from distant seismic vessels.

Overall, odontocete reactions to large arrays of airguns are variable and, at least for delphinids and some porpoises, seem to be confined to a smaller radius than has been observed for some mysticetes. However, other data suggest that some odontocetes species, including belugas and harbor porpoises, may be more responsive than might be expected given their poor low-frequency hearing. Reactions at longer distances may be particularly likely when sound propagation conditions are conducive to transmission of the higher-frequency components of airgun sound to the animals' location (DeRuiter et al. 2006; Goold and Coates 2006; Tyack et al. 2006a; Potter et al. 2007).

For delphinids, and possibly the Dall's porpoise, the available data suggest that a ≥170 dB re 1 μPa$_{rms}$ disturbance criterion (rather than ≥160 dB) would be appropriate. With a medium-to-large airgun array, received levels typically diminish to 170 dB within 1–4 km, whereas levels typically remain above 160 dB out to 4–15 km (e.g., Tolstoy et al. 2009). Reaction distances for delphinids are more consistent with the typical 170 dB re 1 μPa$_{rms}$ distances. The 160 dB (rms) criterion currently applied by NMFS was developed based primarily on data from gray and bowhead whales. Avoidance distances for delphinids and Dall's porpoises tend to be shorter than for those two mysticete species. For delphinids and Dall's porpoises, there is no indication of strong avoidance or other disruption of behavior at distances beyond those where received levels would be ~170 dB re 1 μPa$_{rms}$.

5.3 Pinnipeds

Few studies of the reactions of pinnipeds to noise from open-water seismic exploration have been published (for review of the early literature, see Richardson et al. 1995). However, pinnipeds have been observed during a number of seismic monitoring studies. Monitoring in the Beaufort Sea during 1996–2002 provided a substantial amount of information on avoidance responses (or lack thereof) and associated behavior. Additional monitoring of that type has been done in the Beaufort and Chukchi Seas in 2006–2009. Pinnipeds exposed to seismic surveys have also been observed during seismic surveys along the U.S. west coast. Some limited data are available on physiological responses of pinnipeds exposed to seismic sound, as studied with the aid of radio telemetry. Also, there are data on the reactions of pinnipeds to various other related types of impulsive sounds.

Early observations provided considerable evidence that pinnipeds are often quite tolerant of strong pulsed sounds. During seismic exploration off Nova Scotia, gray seals exposed to noise from airguns and linear explosive charges reportedly did not react strongly (J. Parsons *in* Greene et al. 1985). An airgun caused an initial startle reaction among South African fur seals but was ineffective in scaring them away from fishing gear (Anonymous 1975). Pinnipeds in both water and air sometimes tolerate strong noise pulses from non-explosive and explosive scaring devices, especially if attracted to the area for feeding or reproduction (Mate and Harvey 1987; Reeves et al. 1996). Thus, pinnipeds are expected to be rather tolerant of, or to habituate to, repeated underwater sounds from distant seismic sources, at least when the animals are strongly attracted to the area.

In the U.K., a radio-telemetry study demonstrated short-term changes in the behavior of harbor (=common) and gray seals exposed to airgun pulses (Thompson et al. 1998). Harbor seals were exposed to seismic pulses from a 90-in^3 array (3 × 30 in^3 airguns), and behavioral responses differed among individuals. One harbor seal avoided the array at distances up to 2.5 km from the source and only resumed foraging dives after seismic stopped. Another harbor seal exposed to the same small airgun array showed no detectable behavioral response, even when the array was within 500 m. Gray seals

exposed to a single 10-in^3 airgun showed an avoidance reaction: they moved away from the source, increased swim speed and/or dive duration, and switched from foraging dives to predominantly transit dives. These effects appeared to be short-term as gray seals either remained in, or returned at least once to, the foraging area where they had been exposed to seismic pulses. These results suggest that there are interspecific as well as individual differences in seal responses to seismic sounds.

Off California, visual observations from a seismic vessel showed that California sea lions "typically ignored the vessel and array. When [they] displayed behavior modifications, they often appeared to be reacting visually to the sight of the towed array. At times, California sea lions were attracted to the array, even when it was on. At other times, these animals would appear to be actively avoiding the vessel and array" (Arnold 1996). In Puget Sound, sighting distances for harbor seals and California sea lions tended to be larger when airguns were operating; both species tended to orient away whether or not the airguns were firing (Calambokidis and Osmek 1998). Bain and Williams (2006) also stated that their small sample of harbor seals and sea lions tended to orient and/or move away upon exposure to sounds from a large airgun array.

Monitoring work in the Alaskan Beaufort Sea during 1996–2001 provided considerable information regarding the behavior of seals exposed to seismic pulses (Harris et al. 2001; Moulton and Lawson 2002). Those seismic projects usually involved arrays of 6–16 airguns with total volumes 560–1500 in^3. Subsequent monitoring work in the Canadian Beaufort Sea in 2001–2002, with a somewhat larger airgun system (24 airguns, 2250 in^3), provided similar results (Miller et al. 2005). The combined results suggest that some seals avoid the immediate area around seismic vessels. In most survey years, ringed seal sightings averaged somewhat farther away from the seismic vessel when the airguns were operating than when they were not (Moulton and Lawson 2002). Also, seal sighting rates at the water surface were lower during airgun array operations than during no-airgun periods in each survey year except 1997. However, the avoidance movements were relatively small, on the order of 100 m to (at most) a few hundreds of meters, and many seals remained within 100–200 m of the trackline as the operating airgun array passed by.

The operation of the airgun array had minor and variable effects on the behavior of seals visible at the surface within a few hundred meters of the airguns (Moulton and Lawson 2002). The behavioral data indicated that some seals were more likely to swim away from the source vessel during periods of airgun operations and more likely to swim towards or parallel to the vessel during non-seismic periods. No consistent relationship was observed between exposure to airgun noise and proportions of seals engaged in other recognizable behaviors, e.g., "looked" and "dove". Such a relationship might have occurred if seals seek to reduce exposure to strong seismic pulses, given the reduced airgun noise levels close to the surface where "looking" occurs (Moulton and Lawson 2002).

Monitoring results from the Canadian Beaufort Sea during 2001–2002 were more variable (Miller et al. 2005). During 2001, sighting rates of seals (mostly ringed seals) were similar during all seismic states, including periods without airgun operations. However, seals tended to be seen closer to the vessel during non-seismic than seismic periods. In contrast, during 2002, sighting rates of seals were higher during non-seismic periods than seismic operations, and seals were seen farther from the vessel during non-seismic compared to seismic activity (a marginally significant result). The combined data for both years showed that sighting rates were higher during non-seismic periods compared to seismic periods, and that sighting distances were similar during both seismic states. Miller et al. (2005) concluded that seals showed very limited avoidance to the operating airgun array.

Vessel-based monitoring also took place in the Alaskan Chukchi and Beaufort seas during 2006–2008 (Reiser et al. 2009). Observers on the seismic vessels saw phocid seals less frequently while airguns were operating than when airguns were silent. Also, during airgun operations, those observers saw seals less frequently than did observers on nearby vessels without airguns. Finally, observers on the latter "no-airgun" vessels saw seals more often when the nearby source vessels' airguns were operating than when they were silent. All of these observations are indicative of a tendency for phocid seals to exhibit localized avoidance of the seismic source vessel when airguns are firing (Reiser et al. 2009).

In summary, visual monitoring from seismic vessels has shown only slight (if any) avoidance of airguns by pinnipeds, and only slight (if any) changes in behavior. These studies show that many pinnipeds do not avoid the area within a few hundred meters of an operating airgun array. However, based on the studies with large sample size, or observations from a separate monitoring vessel, or radio telemetry, it is apparent that some phocid seals do show localized avoidance of operating airguns. The limited nature of this tendency for avoidance is a concern. It suggests that one cannot rely on pinnipeds to move away, or to move very far away, before received levels of sound from an approaching seismic survey vessel approach those that may cause hearing impairment (see below).

5.4 Sirenians, Sea Otter and Polar Bear

We are not aware of any information on the reactions of sirenians to airgun sounds.

Behavior of sea otters along the California coast was monitored by Riedman (1983, 1984) while they were exposed to a single 100 in^3 airgun and a 4089 in^3 airgun array. No disturbance reactions were evident when the airgun array was as close as 0.9 km. Sea otters also did not respond noticeably to the single airgun. These results suggest that sea otters may be less responsive to marine seismic pulses than some other marine mammals, such as mysticetes and odontocetes (summarized above). Also, sea otters spend a great deal of time at the surface feeding and grooming (Riedman 1983, 1984). While at the surface, the potential noise exposure of sea otters would be much reduced by pressure-release and interference (Lloyd's mirror) effects at the surface (Greene and Richardson 1988; Richardson et al. 1995).

Airgun effects on polar bears have not been studied. However, polar bears on the ice would be largely unaffected by underwater sound. Sound levels received by polar bears in the water would be attenuated because polar bears generally do not dive much below the surface and received levels of airgun sounds are reduced near the surface because of the aforementioned pressure release and interference effects at the water's surface.

6. Hearing Impairment and Other Physical Effects of Seismic Surveys

Temporary or permanent hearing impairment is a possibility when marine mammals are exposed to very strong sounds. Temporary threshold shift (TTS) has been demonstrated and studied in certain captive odontocetes and pinnipeds exposed to strong sounds (reviewed in Southall et al. 2007). However, there has been no specific documentation of TTS let alone permanent hearing damage, i.e. permanent threshold shift (PTS), in free-ranging marine mammals exposed to sequences of airgun pulses during realistic field conditions. Current NMFS policy regarding exposure of marine mammals to high-level sounds is that cetaceans and pinnipeds should not be exposed to impulsive sounds $\geq$180 and 190 dB re 1 μPa_{rms}, respectively (NMFS 2000). Those criteria have been used in establishing the safety (=shut-down) radii planned for numerous seismic surveys conducted under U.S. jurisdiction. However, those criteria were established before there was any information about the minimum received levels of sounds necessary to cause auditory impairment in marine mammals. As discussed below,

- the 180-dB criterion for cetaceans is probably quite precautionary, i.e., lower than necessary to avoid temporary auditory impairment let alone permanent auditory injury, at least for delphinids.
- TTS is not injury and does not constitute "Level A harassment" in U.S. MMPA terminology.
- the minimum sound level necessary to cause permanent hearing impairment ("Level A harassment") is higher, by a variable and generally unknown amount, than the level that induces barely-detectable TTS.
- the level associated with the onset of TTS is often considered to be a level below which there is no danger of permanent damage. The actual PTS threshold is likely to be well above the level causing onset of TTS (Southall et al. 2007).

Recommendations for new science-based noise exposure criteria for marine mammals, frequency-weighting procedures, and related matters were published recently (Southall et al. 2007). Those recommendations have not, as of late 2009, been formally adopted by NMFS for use in regulatory processes and during mitigation programs associated with seismic surveys. However, some aspects of the recommendations have been taken into account in certain EISs and small-take authorizations. NMFS has indicated that it may issue new noise exposure criteria for marine mammals that account for the now-available scientific data on TTS, the expected offset between the TTS and PTS thresholds, differences in the acoustic frequencies to which different marine mammal groups are sensitive, and other relevant factors. Preliminary information about possible changes in the regulatory and mitigation requirements, and about the possible structure of new criteria, was given by Wieting (2004) and NMFS (2005).

Several aspects of the monitoring and mitigation measures that are now often implemented during seismic survey projects are designed to detect marine mammals occurring near the airgun array, and to avoid exposing them to sound pulses that might, at least in theory, cause hearing impairment. In addition, many cetaceans and (to a limited degree) pinnipeds show some avoidance of the area where received levels of airgun sound are high enough such that hearing impairment could potentially occur. In those cases, the avoidance responses of the animals themselves will reduce or (most likely) avoid the possibility of hearing impairment.

Non-auditory physical effects may also occur in marine mammals exposed to strong underwater pulsed sound. Possible types of non-auditory physiological effects or injuries that might (in theory) occur include stress, neurological effects, bubble formation, and other types of organ or tissue damage. It is possible that some marine mammal species (i.e., beaked whales) may be especially susceptible to injury and/or stranding when exposed to strong pulsed sounds. The following subsections summarize available data on noise-induced hearing impairment and non-auditory physical effects.

6.1 Temporary Threshold Shift (TTS)

TTS is the mildest form of hearing impairment that can occur during exposure to a strong sound (Kryter 1985). While experiencing TTS, the hearing threshold rises and a sound must be stronger in order to be heard. It is a temporary phenomenon, and (especially when mild) is not considered to represent physical damage or "injury" (Southall et al. 2007). Rather, the onset of TTS is an indicator that, if the animal is exposed to higher levels of that sound, physical damage is ultimately a possibility.

The magnitude of TTS depends on the level and duration of noise exposure, and to some degree on frequency, among other considerations (Kryter 1985; Richardson et al. 1995; Southall et al. 2007). For sound exposures at or somewhat above the TTS threshold, hearing sensitivity recovers rapidly after exposure to the noise ends. In terrestrial mammals, TTS can last from minutes or hours to (in cases of

strong TTS) days. Only a few data have been obtained on sound levels and durations necessary to elicit mild TTS in marine mammals (none in mysticetes), and none of the published data concern TTS elicited by exposure to multiple pulses of sound during operational seismic surveys (Southall et al. 2007).

Toothed Whales.—There are empirical data on the sound exposures that elicit onset of TTS in captive bottlenose dolphins and belugas. The majority of these data concern non-impulse sound, but there are some limited published data concerning TTS onset upon exposure to a single pulse of sound from a watergun (Finneran et al. 2002). A detailed review of all TTS data from marine mammals can be found in Southall et al. (2007). The following summarizes some of the key results from odontocetes.

Recent information corroborates earlier expectations that the effect of exposure to strong transient sounds is closely related to the total amount of acoustic energy that is received. Finneran et al. (2005) examined the effects of tone duration on TTS in bottlenose dolphins. Bottlenose dolphins were exposed to 3 kHz tones (non-impulsive) for periods of 1, 2, 4 or 8 s, with hearing tested at 4.5 kHz. For 1-s exposures, TTS occurred with SELs of 197 dB, and for exposures >1 s, SEL >195 dB resulted in TTS (SEL is equivalent to energy flux, in dB re 1 $\mu Pa^2 \cdot s$). At an SEL of 195 dB, the mean TTS (4 min after exposure) was 2.8 dB. Finneran et al. (2005) suggested that an SEL of 195 dB is the likely threshold for the onset of TTS in dolphins and belugas exposed to tones of durations 1–8 s (i.e., TTS onset occurs at a near-constant SEL, independent of exposure duration). That implies that, at least for non-impulsive tones, a doubling of exposure time results in a 3 dB lower TTS threshold.

The assumption that, in marine mammals, the occurrence and magnitude of TTS is a function of cumulative acoustic energy (SEL) is probably an oversimplification. Kastak et al. (2005) reported preliminary evidence from pinnipeds that, for prolonged non-impulse noise, higher SELs were required to elicit a given TTS if exposure duration was short than if it was longer, i.e., the results were not fully consistent with an equal-energy model to predict TTS onset. Mooney et al. (2009a) showed this in a bottlenose dolphin exposed to octave-band non-impulse noise ranging from 4 to 8 kHz at SPLs of 130 to 178 dB re 1 μPa for periods of 1.88 to 30 min. Higher SELs were required to induce a given TTS if exposure duration short than if it was longer. Exposure of the aforementioned bottlenose dolphin to a sequence of brief sonar signals showed that, with those brief (but non-impulse) sounds, the received energy (SEL) necessary to elicit TTS was higher than was the case with exposure to the more prolonged octave-band noise (Mooney et al. 2009b). Those authors concluded that, when using (non-impulse) acoustic signals of duration ~0.5 s, SEL must be at least 210–214 dB re 1 $\mu Pa^2 \cdot s$ to induce TTS in the bottlenose dolphin.

On the other hand, the TTS threshold for odontocetes exposed to a single impulse from a watergun (Finneran et al. 2002) appeared to be somewhat lower than for exposure to non-impulse sound. This was expected, based on evidence from terrestrial mammals showing that broadband pulsed sounds with rapid rise times have greater auditory effect than do non-impulse sounds (Southall et al. 2007). The received energy level of a single seismic pulse that caused the onset of mild TTS in the beluga, as measured without frequency weighting, was ~186 dB re 1 $\mu Pa^2 \cdot s$ or 186 dB SEL (Finneran et al. 2002).[8] The rms level of an airgun pulse (in dB re 1 μPa measured over the duration of the pulse) is typically 10–15 dB higher than the SEL for the same pulse when received within a few kilometers of the airguns. Thus, a single airgun pulse might need to have a received level of ~196–201 dB re 1 μPa_{rms} in order to produce brief, mild TTS. Exposure to several strong seismic pulses that each has a flat-weighted received level

[8] If the low-frequency components of the watergun sound used in the experiments of Finneran et al. (2002) are downweighted as recommended by Southall et al. (2007) using their M_{mf}-weighting curve, the effective exposure level for onset of mild TTS was 183 dB re 1 $\mu Pa^2 \cdot s$ (Southall et al. 2007).

near 190 dB_{rms} (175–180 dB SEL) could result in cumulative exposure of ~186 dB SEL (flat-weighted) or ~183 dB SEL (M_{mf}-weighted), and thus slight TTS in a small odontocete. That assumes that the TTS threshold upon exposure to multiple pulses is (to a first approximation) a function of the total received pulse energy, without allowance for any recovery between pulses.

The above TTS information for odontocetes is derived from studies on the bottlenose dolphin and beluga. For the one harbor porpoise tested, the received level of airgun sound that elicited onset of TTS was lower. The animal was exposed to single pulses from a small (20 in^3) airgun, and auditory evoked potential methods were used to test the animal's hearing sensitivity at frequencies of 4, 32, or 100 kHz after each exposure (Lucke et al. 2009). Based on the measurements at 4 kHz, TTS occurred upon exposure to one airgun pulse with received level ~200 dB re 1 $\mu Pa_{pk\text{-}pk}$ or an SEL of 164.3 dB re 1 $\mu Pa^2 \cdot s$. If these results from a single animal are representative, it is inappropriate to assume that onset of TTS occurs at similar received levels in all odontocetes (*cf.* Southall et al. 2007). Some cetaceans may incur TTS at lower sound exposures than are necessary to elicit TTS in the beluga or bottlenose dolphin.

Insofar as we are aware, there are no published data confirming that the auditory effect of a sequence of airgun pulses received by an odontocete is a function of their cumulative energy. Southall et al. (2007) consider that to be a reasonable, but probably somewhat precautionary, assumption. It is precautionary because, based on data from terrestrial mammals, one would expect that a given energy exposure would have somewhat less effect if separated into discrete pulses, with potential opportunity for partial auditory recovery between pulses. However, as yet there has been little study of the rate of recovery from TTS in marine mammals, and in humans and other terrestrial mammals the available data on recovery are quite variable. Southall et al. (2007) concluded that—until relevant data on recovery are available from marine mammals—it is appropriate not to allow for any assumed recovery during the intervals between pulses within a pulse sequence.

Additional data are needed to determine the received sound levels at which small odontocetes would start to incur TTS upon exposure to repeated, low-frequency pulses of airgun sound with variable received levels. To determine how close an airgun array would need to approach in order to elicit TTS, it is necessary to determine the total energy that a mammal would receive as an airgun array approaches, passes at various CPA distances, and moves away (e.g., Erbe and King 2009). At the present state of knowledge, it is also necessary to assume that the effect is directly related to total received energy even though that energy is received in multiple pulses separated by gaps. The lack of data on the exposure levels necessary to cause TTS in toothed whales when the signal is a series of pulsed sounds, separated by silent periods, remains a data gap, as is the lack of published data on TTS in odontocetes other than the beluga, bottlenose dolphin, and harbor porpoise.

Baleen Whales.—There are no data, direct or indirect, on levels or properties of sound that are required to induce TTS in any baleen whale. The frequencies to which mysticetes are most sensitive are assumed to be lower than those to which odontocetes are most sensitive, and natural background noise levels at those low frequencies tend to be higher. As a result, auditory thresholds of baleen whales within their frequency band of best hearing are believed to be higher (less sensitive) than are those of odontocetes at their best frequencies (Clark and Ellison 2004). From this, it is suspected that received levels causing TTS onset may also be higher in mysticetes (Southall et al. 2007). However, based on preliminary simulation modeling that attempted to allow for various uncertainties in assumptions and variability around population means, Gedamke et al. (2008) suggested that some baleen whales whose closest point of approach to a seismic vessel is 1 km or more could experience TTS or even PTS.

In practice during seismic surveys, few if any cases of TTS are expected given the strong likelihood that baleen whales would avoid the approaching airguns (or vessel) before being exposed to levels high enough for there to be any possibility of TTS (see above for evidence concerning avoidance responses by baleen whales). This assumes that the ramp-up (soft-start) procedure is used when commencing airgun operations, to give whales near the vessel the opportunity to move away before they are exposed to sound levels that might be strong enough to elicit TTS. As discussed earlier, single-airgun experiments with bowhead, gray, and humpback whales show that those species do tend to move away when a single airgun starts firing nearby, which simulates the onset of a ramp up.

Pinnipeds.—In pinnipeds, TTS thresholds associated with exposure to brief pulses (single or multiple) of underwater sound have not been measured. Two California sea lions did not incur TTS when exposed to single brief pulses with received levels of ~178 and 183 dB re 1 μPa_{rms} and total energy fluxes of 161 and 163 dB re 1 $\mu Pa^2 \cdot s$ (Finneran et al. 2003). However, initial evidence from more prolonged (non-pulse) exposures suggested that some pinnipeds (harbor seals in particular) incur TTS at somewhat lower received levels than do small odontocetes exposed for similar durations (Kastak et al. 1999, 2005; Ketten et al. 2001). Kastak et al. (2005) reported that the amount of threshold shift increased with increasing SEL in a California sea lion and harbor seal. They noted that, for non-impulse sound, doubling the exposure duration from 25 to 50 min (i.e., a +3 dB change in SEL) had a greater effect on TTS than an increase of 15 dB (95 vs. 80 dB) in exposure level. Mean threshold shifts ranged from 2.9–12.2 dB, with full recovery within 24 hr (Kastak et al. 2005). Kastak et al. (2005) suggested that, for non-impulse sound, SELs resulting in TTS onset in three species of pinnipeds may range from 183 to 206 dB re 1 $\mu Pa^2 \cdot s$, depending on the absolute hearing sensitivity.

As noted above for odontocetes, it is expected that—for impulse as opposed to non-impulse sound—the onset of TTS would occur at a lower cumulative SEL given the assumed greater auditory effect of broadband impulses with rapid rise times. The threshold for onset of mild TTS upon exposure of a harbor seal to impulse sounds has been estimated indirectly as being an SEL of ~171 dB re 1 $\mu Pa^2 \cdot s$ (Southall et al. 2007). That would be approximately equivalent to a single pulse with received level ~181–186 dB re 1 μPa_{rms}, or a series of pulses for which the highest rms values are a few dB lower.

At least for non-impulse sounds, TTS onset occurs at appreciably higher received levels in California sea lions and northern elephant seals than in harbor seals (Kastak et al. 2005). Thus, the former two species would presumably need to be closer to an airgun array than would a harbor seal before TTS is a possibility. Insofar as we are aware, there are no data to indicate whether the TTS thresholds of other pinniped species are more similar to those of the harbor seal or to those of the two less-sensitive species.

Sirenians, Sea Otter and Polar Bear.—There are no available data on TTS in sea otters and polar bears. However, TTS is unlikely to occur in sea otters or polar bears if they are on the water surface, given the pressure release and Lloyd's mirror effects at the water's surface. Furthermore, sea otters tend to inhabit shallow coastal habitats where large seismic survey vessels towing large spreads of streamers may be unable to operate. TTS is also considered unlikely to occur in sirenians as a result of exposure to sounds from a seismic survey. They, like sea otters, tend to inhabit shallow coastal habitats and rarely range far from shore, whereas seismic survey vessels towing large arrays of airguns and (usually) even larger arrays of streamers normally must remain farther offshore because of equipment clearance and maneuverability limitations. Exposures of sea otters and sirenians to seismic surveys are more likely to involve smaller seismic sources that can be used in shallow and confined waters. The impacts of these are inherently less than would occur from a larger source of the types often used farther offshore.

Likelihood of Incurring TTS.—Most cetaceans show some degree of avoidance of seismic vessels operating an airgun array (see above). It is unlikely that these cetaceans would be exposed to airgun pulses at a sufficiently high level for a sufficiently long period to cause more than mild TTS, given the relative movement of the vessel and the marine mammal. TTS would be more likely in any odontocetes that bow- or wake-ride or otherwise linger near the airguns. However, while bow- or wake-riding, odontocetes would be at the surface and thus not exposed to strong sound pulses given the pressure-release and Lloyd Mirror effects at the surface. But if bow- or wake-riding animals were to dive intermittently near airguns, they would be exposed to strong sound pulses, possibly repeatedly.

If some cetaceans did incur mild or moderate TTS through exposure to airgun sounds in this manner, this would very likely be a temporary and reversible phenomenon. However, even a temporary reduction in hearing sensitivity could be deleterious in the event that, during that period of reduced sensitivity, a marine mammal needed its full hearing sensitivity to detect approaching predators, or for some other reason.

Some pinnipeds show avoidance reactions to airguns, but their avoidance reactions are generally not as strong or consistent as those of cetaceans. Pinnipeds occasionally seem to be attracted to operating seismic vessels. There are no specific data on TTS thresholds of pinnipeds exposed to single or multiple low-frequency pulses. However, given the indirect indications of a lower TTS threshold for the harbor seal than for odontocetes exposed to impulse sound (see above), it is possible that some pinnipeds close to a large airgun array could incur TTS.

NMFS (1995, 2000) concluded that cetaceans should not be exposed to pulsed underwater noise at received levels >180 dB re 1 μPa_{rms}. The corresponding limit for pinnipeds has been set by NMFS at 190 dB, although the HESS Team (HESS 1999) recommended a 180-dB limit for pinnipeds in California. The 180 and 190 dB re 1 μPa_{rms} levels have not been considered to be the levels above which TTS might occur. Rather, they were the received levels above which, in the view of a panel of bioacoustics specialists convened by NMFS before TTS measurements for marine mammals started to become available, one could not be certain that there would be no injurious effects, auditory or otherwise, to marine mammals. As summarized above, data that are now available imply that TTS is unlikely to occur in various odontocetes (and probably mysticetes as well) unless they are exposed to a sequence of several airgun pulses stronger than 190 dB re 1 μPa_{rms}. On the other hand, for the harbor seal, harbor porpoise, and perhaps some other species, TTS may occur upon exposure to one or more airgun pulses whose received level equals the NMFS "do not exceed" value of 190 dB re 1 μPa_{rms}. That criterion corresponds to a single-pulse SEL of 175–180 dB re 1 $\mu Pa^2 \cdot s$ in typical conditions, whereas TTS is suspected to be possible in harbor seals and harbor porpoises with a cumulative SEL of ~171 and ~164 dB re 1 $\mu Pa^2 \cdot s$, respectively.

It has been shown that most large whales and many smaller odontocetes (especially the harbor porpoise) show at least localized avoidance of ships and/or seismic operations (see above). Even when avoidance is limited to the area within a few hundred meters of an airgun array, that should usually be sufficient to avoid TTS based on what is currently known about thresholds for TTS onset in cetaceans. In addition, ramping up airgun arrays, which is standard operational protocol for many seismic operators, should allow cetaceans near the airguns at the time of startup (if the sounds are aversive) to move away from the seismic source and to avoid being exposed to the full acoustic output of the airgun array (see above). Thus, most baleen whales likely will not be exposed to high levels of airgun sounds provided the ramp-up procedure is applied. Likewise, many odontocetes close to the trackline are likely to move away before the sounds from an approaching seismic vessel become sufficiently strong for there to be any potential for TTS or other hearing impairment. Therefore, there is little potential for baleen whales or

odontocetes that show avoidance of ships or airguns to be close enough to an airgun array to experience TTS. In the event that a few individual cetaceans did incur TTS through exposure to strong airgun sounds, this is a temporary and reversible phenomenon unless the exposure exceeds the TTS-onset threshold by a sufficient amount for PTS to be incurred (see below). If TTS but not PTS were incurred, it would most likely be mild, in which case recovery is expected to be quick (probably within minutes).

6.2 Permanent Threshold Shift (PTS)

When PTS occurs, there is physical damage to the sound receptors in the ear. In some cases, there can be total or partial deafness, whereas in other cases, the animal has an impaired ability to hear sounds in specific frequency ranges (Kryter 1985). Physical damage to a mammal's hearing apparatus can occur if it is exposed to sound impulses that have very high peak pressures, especially if they have very short rise times. (Rise time is the interval required for sound pressure to increase from the baseline pressure to peak pressure.)

There is no specific evidence that exposure to pulses of airgun sound can cause PTS in any marine mammal, even with large arrays of airguns. However, given the likelihood that some mammals close to an airgun array might incur at least mild TTS (see above), there has been further speculation about the possibility that some individuals occurring very close to airguns might incur PTS (e.g., Richardson et al. 1995, p. 372*ff*; Gedamke et al. 2008). Single or occasional occurrences of mild TTS are not indicative of permanent auditory damage, but repeated or (in some cases) single exposures to a level well above that causing TTS onset might elicit PTS.

Relationships between TTS and PTS thresholds have not been studied in marine mammals, but are assumed to be similar to those in humans and other terrestrial mammals (Southall et al. 2007). Based on data from terrestrial mammals, a precautionary assumption is that the PTS threshold for impulse sounds (such as airgun pulses as received close to the source) is <u>at least</u> 6 dB higher than the TTS threshold on a peak-pressure basis, and probably >6 dB higher (Southall et al. 2007). The low-to-moderate levels of TTS that have been induced in captive odontocetes and pinnipeds during controlled studies of TTS have been confirmed to be temporary, with no measurable residual PTS (Kastak et al. 1999; Schlundt et al. 2000; Finneran et al. 2002, 2005; Nachtigall et al. 2003, 2004). However, very prolonged exposure to sound strong enough to elicit TTS, or shorter-term exposure to sound levels well above the TTS threshold, can cause PTS, at least in terrestrial mammals (Kryter 1985). In terrestrial mammals, the received sound level from a single non-impulsive sound exposure must be far above the TTS threshold for any risk of permanent hearing damage (Kryter 1994; Richardson et al. 1995; Southall et al. 2007). However, there is special concern about strong sounds whose pulses have very rapid rise times. In terrestrial mammals, there are situations when pulses with rapid rise times (e.g., from explosions) can result in PTS even though their peak levels are only a few dB higher than the level causing slight TTS. The rise time of airgun pulses is fast, but not as fast as that of an explosion.

Some factors that contribute to onset of PTS, at least in terrestrial mammals, are as follows:

- exposure to single very intense sound,
- fast rise time from baseline to peak pressure,
- repetitive exposure to intense sounds that individually cause TTS but not PTS, and
- recurrent ear infections or (in captive animals) exposure to certain drugs.

Cavanagh (2000) reviewed the thresholds used to define TTS and PTS. Based on this review and SACLANT (1998), it is reasonable to assume that PTS might occur at a received sound level 20 dB or more above that inducing mild TTS. However, for PTS to occur at a received level only 20 dB above the TTS threshold, the animal probably would have to be exposed to a strong sound for an extended period, or to a strong sound with rather rapid rise time.

More recently, Southall et al. (2007) estimated that received levels would need to exceed the TTS threshold by at least 15 dB, on an SEL basis, for there to be risk of PTS. Thus, for cetaceans exposed to a sequence of sound pulses, they estimate that the PTS threshold might be an M-weighted SEL (for the sequence of received pulses) of ~198 dB re 1 $\mu Pa^2 \cdot s$ (15 dB higher than the M_{mf}-weighted TTS threshold, in a beluga, for a watergun impulse). Additional assumptions had to be made to derive a corresponding estimate for pinnipeds, as the only available data on TTS-thresholds in pinnipeds pertained to non-impulse sound (see above). Southall et al. (2007) estimated that the PTS threshold could be a cumulative M_{pw}-weighted SEL of ~186 dB re 1 $\mu Pa^2 \cdot s$ in the case of a harbor seal exposed to impulse sound. The PTS threshold for the California sea lion and northern elephant seal would probably be higher given the higher TTS thresholds in those species. Southall et al. (2007) also note that, regardless of the SEL, there is concern about the possibility of PTS if a cetacean or pinniped received one or more pulses with peak pressure exceeding 230 or 218 dB re 1 μPa, respectively. Thus, PTS might be expected upon exposure of cetaceans to <u>either</u> SEL ≥198 dB re 1 $\mu Pa^2 \cdot s$ <u>or</u> peak pressure ≥230 dB re 1 μPa. Corresponding proposed dual criteria for pinnipeds (at least harbor seals) are ≥186 dB SEL and ≥ 218 dB peak pressure (Southall et al. 2007). These estimates are all first approximations, given the limited underlying data, assumptions, species differences, and evidence that the "equal energy" model is not be entirely correct.

Sound impulse duration, peak amplitude, rise time, number of pulses, and inter-pulse interval are the main factors thought to determine the onset and extent of PTS. Ketten (1994) has noted that the criteria for differentiating the sound pressure levels that result in PTS (or TTS) are location and species-specific. PTS effects may also be influenced strongly by the health of the receiver's ear.

As described above for TTS, in estimating the amount of sound energy required to elicit the onset of TTS (and PTS), it is assumed that the auditory effect of a given cumulative SEL from a series of pulses is the same as if that amount of sound energy were received as a single strong sound. There are no data from marine mammals concerning the occurrence or magnitude of a potential partial recovery effect between pulses. In deriving the estimates of PTS (and TTS) thresholds quoted here, Southall et al. (2007) made the precautionary assumption that no recovery would occur between pulses.

The TTS section (above) concludes that exposure to several strong seismic pulses that each have flat-weighted received levels near 190 dB re 1 μPa_{rms} (175–180 dB re 1 $\mu Pa^2 \cdot s$ SEL) could result in cumulative exposure of ~186 dB SEL (flat-weighted) or ~183 dB SEL (M_{mf}-weighted), and thus slight TTS in a small odontocete. Allowing for the assumed 15 dB offset between PTS and TTS thresholds, expressed on an SEL basis, exposure to several strong seismic pulses that each have flat-weighted received levels near 205 dB_{rms} (190–195 dB SEL) could result in cumulative exposure of ~198 dB SEL (M_{mf}-weighted), and thus slight PTS in a small odontocete. However, the levels of successive pulses that will be received by a marine mammal that is below the surface as a seismic vessel approaches, passes and moves away will tend to increase gradually and then decrease gradually, with periodic decreases superimposed on this pattern when the animal comes to the surface to breathe. To estimate how close an odontocete's CPA distance would have to be for the cumulative SEL to exceed 198 dB SEL (M_{mf}-weighted), one would (as a minimum) need to allow for the sequence of distances at which airgun shots

would occur, and for the dependence of received SEL on distance in the region of the seismic operation (e.g., Erbe and King 2009).

It is unlikely that an odontocete would remain close enough to a large airgun array for sufficiently long to incur PTS. There is some concern about bowriding odontocetes, but for animals at or near the surface, auditory effects are reduced by Lloyd's mirror and surface release effects. The presence of the vessel between the airgun array and bow-riding odontocetes could also, in some but probably not all cases, reduce the levels received by bow-riding animals (e.g., Gabriele and Kipple 2009). The TTS (and thus PTS) thresholds of baleen whales are unknown but, as an interim measure, assumed to be no lower than those of odontocetes. Also, baleen whales generally avoid the immediate area around operating seismic vessels, so it is unlikely that a baleen whale could incur PTS from exposure to airgun pulses. The TTS (and thus PTS) thresholds of some pinnipeds (e.g., harbor seal) as well as the harbor porpoise may be lower (Kastak et al. 2005; Southall et al. 2007; Lucke et al. 2009). If so, TTS and potentially PTS may extend to a somewhat greater distance for those animals. Again, Lloyd's mirror and surface release effects will ameliorate the effects for animals at or near the surface.

Although it is unlikely that airgun operations during most seismic surveys would cause PTS in many marine mammals, caution is warranted given

- the limited knowledge about noise-induced hearing damage in marine mammals, particularly baleen whales, pinnipeds, and sea otters;
- the seemingly greater susceptibility of certain species (e.g., harbor porpoise and harbor seal) to TTS and presumably also PTS; and
- the lack of knowledge about TTS and PTS thresholds in many species, including various species closely related to the harbor porpoise and harbor seal.

The avoidance reactions of many marine mammals, along with commonly-applied monitoring and mitigation measures (visual and passive acoustic monitoring, ramp ups, and power downs or shut downs when mammals are detected within or approaching the "safety radii"), would reduce the already-low probability of exposure of marine mammals to sounds strong enough to induce PTS.

6.3 Strandings and Mortality

Marine mammals close to underwater detonations of high explosives can be killed or severely injured, and the auditory organs are especially susceptible to injury (Ketten et al. 1993; Ketten 1995). However, explosives are no longer used in marine waters for commercial seismic surveys or (with rare exceptions) for seismic research; they have been replaced by airguns and other non-explosive sources. Airgun pulses are less energetic and have slower rise times, and there is no specific evidence that they can cause serious injury, death, or stranding even in the case of large airgun arrays. However, the association of mass strandings of beaked whales with naval exercises and, in one case, a seismic survey (Malakoff 2002; Cox et al. 2006), has raised the possibility that beaked whales exposed to strong "pulsed" sounds may be especially susceptible to injury and/or behavioral reactions that can lead to stranding (e.g., Hildebrand 2005; Southall et al. 2007). Hildebrand (2005) reviewed the association of cetacean strandings with high-intensity sound events and found that deep-diving odontocetes, primarily beaked whales, were by far the predominant (95%) cetaceans associated with these events, with 2% mysticete whales (minke). However, as summarized below, there is no definitive evidence that airguns can lead to injury, strandings, or mortality even for marine mammals in close proximity to large airgun arrays.

Specific sound-related processes that lead to strandings and mortality are not well documented, but may include (1) swimming in avoidance of a sound into shallow water; (2) a change in behavior (such as a change in diving behavior that might contribute to tissue damage, gas bubble formation, hypoxia, cardiac arrhythmia, hypertensive hemorrhage or other forms of trauma; (3) a physiological change such as a vestibular response leading to a behavioral change or stress-induced hemorrhagic diathesis, leading in turn to tissue damage; and (4) tissue damage directly from sound exposure, such as through acoustically mediated bubble formation and growth or acoustic resonance of tissues. Some of these mechanisms are unlikely to apply in the case of impulse sounds. However, there are increasing indications that gas-bubble disease (analogous to "the bends"), induced in supersaturated tissue by a behavioral response to acoustic exposure, could be a pathologic mechanism for the strandings and mortality of some deep-diving cetaceans exposed to sonar. The evidence for this remains circumstantial and associated with exposure to naval mid-frequency sonar, not seismic surveys (Cox et al. 2006; Southall et al. 2007).

Seismic pulses and mid-frequency sonar signals are quite different, and some mechanisms by which sonar sounds have been hypothesized to affect beaked whales are unlikely to apply to airgun pulses. Sounds produced by airgun arrays are broadband impulses with most of the energy below 1 kHz. Typical military mid-frequency sonars emit non-impulse sounds at frequencies of 2–10 kHz, generally with a relatively narrow bandwidth at any one time (though the frequency may change over time). Thus, it is not appropriate to assume that the effects of seismic surveys on beaked whales or other species would be the same as the apparent effects of military sonar. For example, resonance effects (Gentry 2002) and acoustically-mediated bubble-growth (Crum et al. 2005) are implausible in the case of exposure to broadband airgun pulses. Nonetheless, evidence that sonar signals can, in special circumstances, lead (at least indirectly) to physical damage and mortality (e.g., Balcomb and Claridge 2001; NOAA and USN 2001; Jepson et al. 2003; Fernández et al. 2004, 2005; Hildebrand 2005; Cox et al. 2006) suggests that caution is warranted when dealing with exposure of marine mammals to any high-intensity "pulsed" sound. One of the hypothesized mechanisms by which naval sonars lead to strandings might, in theory, also apply to seismic surveys: If the strong sounds sometimes cause deep-diving species to alter their surfacing–dive cycles in a way that causes bubble formation in tissue, that hypothesized mechanism might apply to seismic surveys as well as mid-frequency naval sonars. However, there is no specific evidence of this upon exposure to airgun pulses.

There is no conclusive evidence of cetacean strandings or deaths at sea as a result of exposure to seismic surveys, but a few cases of strandings in the general area where a seismic survey was ongoing have led to speculation concerning a possible link between seismic surveys and strandings. • Suggestions that there was a link between seismic surveys and strandings of humpback whales in Brazil (Engel et al. 2004) were not well founded (IAGC 2004; IWC 2007). • In Sept. 2002, there was a stranding of two Cuvier's beaked whales in the Gulf of California, Mexico, when the L-DEO seismic vessel R/V *Maurice Ewing* was operating a 20-airgun, 8490-in^3 airgun array in the general area. The evidence linking the stranding to the seismic survey was inconclusive and not based on any physical evidence (Hogarth 2002; Yoder 2002). The ship was also operating its multibeam echosounder at the same time, but this had much less potential than the aforementioned naval sonars to affect beaked whales, given its downward-directed beams, much shorter pulse durations, and lower duty cycle. Nonetheless, the Gulf of California incident plus the beaked whale strandings near naval exercises involving use of mid-frequency sonar suggest a need for caution in conducting seismic surveys in areas occupied by beaked whales until more is known about effects of seismic surveys on those species (Hildebrand 2005).

6.4 Non-Auditory Physiological Effects

Based on evidence from terrestrial mammals and humans, sound is a potential source of stress (Wright and Kuczaj 2007; Wright et al. 2007a,b, 2009). However, almost no information is available on sound-induced stress in marine mammals, or on its potential (alone or in combination with other stressors) to affect the long-term well-being or reproductive success of marine mammals (Fair and Becker 2000; Hildebrand 2005; Wright et al. 2007a,b). Such long-term effects, if they occur, would be mainly associated with chronic noise exposure, which is characteristic of some seismic surveys and exposure situations (McCauley et al. 2000a:62*ff*; Nieukirk et al. 2009) but not of some others.

Available data on potential stress-related impacts of anthropogenic noise on marine mammals are extremely limited, and additional research on this topic is needed. We know of only two specific studies of noise-induced stress in marine mammals. ***(1)*** Romano et al. (2004) examined the effects of single underwater impulse sounds from a seismic water gun (source level up to 228 dB re 1 μPa · m_{p-p}) and single short-duration pure tones (sound pressure level up to 201 dB re 1 μPa) on the nervous and immune systems of a beluga and a bottlenose dolphin. They found that neural-immune changes to noise exposure were minimal. Although levels of some stress-released substances (e.g., catecholamines) changed significantly with exposure to sound, levels returned to baseline after 24 hr. ***(2)*** During playbacks of recorded drilling noise to four captive beluga whales, Thomas et al. (1990) found no changes in blood levels of stress-related hormones. Long-term effects were not measured, and no short-term effects were detected. For both studies, caution is necessary when extrapolating these results to wild animals and to real-world situations given the small sample sizes, use of captive animals, and other technical limitations of the two studies.

Aside from stress, other types of physiological effects that might, in theory, be involved in beaked whale strandings upon exposure to naval sonar (Cox et al. 2006), such as resonance and gas bubble formation, have not been demonstrated and are not expected upon exposure to airgun pulses (see preceding subsection). If seismic surveys disrupt diving patterns of deep-diving species, this might perhaps result in bubble formation and a form of "the bends", as speculated to occur in beaked whales exposed to sonar. However, there is no specific evidence that exposure to airgun pulses has this effect.

In summary, very little is known about the potential for seismic survey sounds (or other types of strong underwater sounds) to cause non-auditory physiological effects in marine mammals. Such effects, if they occur at all, would presumably be limited to short distances and to activities that extend over a prolonged period. The available data do not allow identification of a specific exposure level above which non-auditory effects can be expected (Southall et al. 2007), or any meaningful quantitative predictions of the numbers (if any) of marine mammals that might be affected in these ways.

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APPENDIX C:

REVIEW OF THE EFFECTS OF AIRGUN SOUNDS ON SEA TURTLES[9]

The following subsections review relevant information concerning the potential effects of airgun sounds on sea turtles. This information is included here as background. Much of this information has also been included in varying formats in other reviews, assessments, and regulatory applications prepared by LGL Ltd.

1. Sea Turtle Hearing

Although there have been a limited number of studies on sea turtle hearing (see review by Southwood et al. 2008), the available data are not very comprehensive. However, these data demonstrate that sea turtles appear to be low-frequency specialists (see Table B-1).

Sea turtle auditory perception occurs through a combination of both bone and water conduction rather than air conduction (Lenhardt 1982; Lenhardt and Harkins 1983). Detailed descriptions of sea turtle ear anatomy are found in Ridgway et al. (1969), Lenhardt et al. (1985), and Bartol and Musick (2003). Sea turtles do not have external ears, but the middle ear is well adapted as a peripheral component of a bone conduction system. The thick tympanum is disadvantageous as an aerial receptor, but enhances low-frequency bone conduction hearing (Lenhardt et al. 1985; Bartol et al. 1999; Bartol and Musick 2003). A layer of subtympanal fat emerging from the middle ear is fused to the tympanum (Ketten et al. 2006; Bartol 2004, 2008). A cartilaginous disk, the extracolumella, is found under the tympanic membrane and is attached to the columella (Bartol 2004, 2008). The columella is a long rod that expands to form the stapes, and fibrous strands connect the stapes to the saccule (Bartol 2004, 2008). When the tympanum is depressed, the vibrations are conveyed via the fibrous stapedo-sacular strands to the sacule (Lenhardt et al. 1985). This arrangement of fat deposits and bone enables sea turtles to hear low-frequency sounds while underwater and makes them relatively insensitive to sound above water. Vibrations, however, can be conducted through the bones of the carapace to reach the middle ear.

A variety of audiometric methods are available to assess hearing abilities. Electrophysiological measures of hearing (e.g., auditory brainstem response or ABR) provide good information about relative sensitivity to different frequencies. However, this approach may underestimate the frequency range to which the animal is sensitive and may be imprecise at determining absolute hearing thresholds (e.g., Wolski et al. 2003). Nevertheless, when time is critical and only untrained animals are available, this method can provide useful information on sea turtle hearing (e.g., Wolski et al. 2003).

Ridgway et al. (1969) obtained the first direct measurements of sea turtle hearing sensitivity (Table B-1). They used an electrophysiological technique (cochlear potentials) to determine the response of green sea turtles (*Chelonia mydas*) to aerial- and vibrational-stimuli consisting of tones with frequencies 30 to 700 Hz. They found that green turtles exhibit maximum hearing sensitivity between 300 and 500 Hz Hz, and speculated that the turtles had a useful hearing range of 60–1000 Hz. (However, there was some response to strong vibrational signals at frequencies down to the lowest one tested — 30 Hz.)

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[9] By **Valerie D. Moulton and W. John Richardson**, with subsequent updates (to Feb. 2010) by Mari A. Smultea and Meike Holst, all of LGL Ltd., environmental research associates.

TABLE B-1. Hearing capabilities of sea turtles as measured using behavioral and electro-physiological techniques. ABR: auditory brainstem response; NA: no empirical data available.

Sea Turtle Species	Hearing Range (Hz)	Hearing Highest Sensitivity (Hz)	Technique	Source
Green	60-1000	300-500	Cochlear Potentials [a]	Ridgway et al. 1969
	100-800	600-700 (juveniles) 200-400 (subadults)	ABR [w]	Bartol & Ketten 2006; Ketten & Bartol 2006
	50-1600	50-400	ABR [a,w]	Dow et al. 2008
Hawksbill	NA	NA	NA	NA
Loggerhead	250-1000	250	ABR [a]	Bartol et al. 1999
Olive ridley	NA	NA	NA	NA
Kemp's ridley	100-500	100-200	ABR [w]	Bartol & Ketten 2006; Ketten & Bartol 2006
Leatherback	NA	NA	NA	NA
Flatback	NA	NA	NA	NA

[a] measured in air; [w] measured underwater

Bartol et al. (1999) tested the in-air hearing of juvenile loggerhead turtles *Caretta caretta* (Table B-1). The authors used ABR to determine the response of the sea turtle ear to two types of vibrational stimuli: (1) brief, low-frequency broadband clicks, and (2) brief tone bursts at four frequencies from 250 to 1000 Hz. They demonstrated that loggerhead sea turtles hear well between 250 and 1000 Hz; within that frequency range the turtles were most sensitive at 250 Hz. The authors did not measure hearing sensitivity below 250 Hz or above 1000 Hz. There was an extreme decrease in response to stimuli above 1000 Hz, and the vibrational intensities required to elicit a response may have damaged the turtle's ear. The signals used in this study were very brief — 0.6 ms for the clicks and 0.8–5.5 ms for the tone bursts. In other animals, auditory thresholds decrease with increasing signal duration up to ~100–200 ms. Thus, sea turtles probably could hear weaker signals than demonstrated in the study if the signal duration were longer.

Lenhardt (2002) exposed loggerhead turtles while they were near the bottom of holding tanks at a depth of 1 m to tones from 35 to 1000 Hz. The turtles exhibited startle responses (neck contractions) to these tones. The lowest thresholds were in the 400–500 Hz range (106 dB SPL re 1 μPa), and thresholds in the 100–200 Hz range were ~124 dB (Lenhardt 2002). Thresholds at 735 and 100 Hz were 117 and 156 dB, respectively (Lenhardt 2002). Diving behaviour occurred at 30 Hz and 164 dB.

More recently, ABR techniques have been used to determine the underwater hearing capabilities of six subadult green turtles, two juvenile green turtles, and two juvenile Kemp's ridley (*Lepidochelys kempii*) turtles (Ketten and Bartol 2006; Bartol and Ketten 2006; Table B-1). The turtles were physically restrained in a small box tank with their ears below the water surface and the top of the head exposed above the surface. Pure-tone acoustic stimuli were presented to the animals, though the exact frequencies of these tones were not indicated. The six subadult green turtles detected sound at frequencies 100–500

Hz, with the most sensitive hearing at 200–400 Hz. In contrast, the two juvenile green turtles exhibited a slightly expanded overall hearing range of 100–800 Hz, with their most sensitive hearing occurring at 600–700 Hz. The most restricted range of sensitive hearing (100–200 Hz) was found in the two juvenile Kemp's ridleys turtles, whose overall frequency range was 100–500 Hz.

Preliminary data from a similar study of a trained, captive green turtle indicate that the animal heard and responded behaviorally to underwater tones ranging in frequency from 100 to 500 Hz. At 200 Hz, the threshold was between 107 and 119 dB, and at 400 Hz the threshold was between 121 and 131 dB [reference units not provided] (Streeter 2003; ONR N.D.).

In summary, the limited available data indicate that the frequency range of best hearing sensitivity of sea turtles extends from ~200 to 700 Hz. Sensitivity deteriorates as one moves away from this range to either lower or higher frequencies. However, there is some sensitivity to frequencies as low as 60 Hz, and probably as low as 30 Hz (Ridgway et al. 1969). Thus, there is substantial overlap in the frequencies that sea turtles detect vs. the dominant frequencies in airgun pulses. Given that, plus the high energy levels of airgun pulses, sea turtles undoubtedly hear airgun sounds. We are not aware of measurements of the absolute hearing thresholds of any sea turtle to waterborne sounds similar to airgun pulses. Given the high source levels of airgun pulses and the substantial received levels even at distances many km away from the source, sea turtles probably can also hear distant seismic vessels. However, in the absence of relevant absolute threshold data, we cannot estimate how far away an airgun array might be audible to a sea turtle.

2. Effects of Airgun Pulses on Behavior and Movement

The effects of exposure to airgun pulses on the behavior and distribution of various marine animals have been studied over the past three decades. Most such studies have concerned marine mammals (e.g., see reviews by Richardson et al. 1995; Gordon et al. 2004; Nowacek et al. 2007; Southall et al. 2007), but also fish (e.g., reviewed by Thomson et al. 2001; Herata 2007; Payne et al. 2008). There have been far fewer studies on the effects of airgun noise (or indeed any type of noise) on sea turtles, and little is known about the sound levels that will or will not elicit various types of behavioral reactions. There have been four directed studies that focused on short-term behavioral responses of sea turtles in enclosures to single airguns. However, comparisons of results among studies are difficult because experimental designs and reporting procedures have varied greatly, and few studies provided specific information about the levels of the airgun pulses received by the turtles. Although monitoring studies are now providing some information on responses (or lack of responses) of free-ranging sea turtles to seismic surveys, we are not aware of any directed studies on responses of free-ranging sea turtles to seismic sounds or on the long-term effects of seismic or other sounds on sea turtles.

***Directed Studies*.—**The most recent of the studies of caged sea turtles exposed to airgun pulses was a study by McCauley et al. (2000a,b) off Western Australia. The authors exposed caged green and loggerhead sea turtles (one of each) to pulses from an approaching and then receding 20 in^3 airgun operating at 1500 psi and a 5-m airgun depth. The single airgun fired every 10 s. There were two trials separated by two days; the first trial involved ~2 h of airgun exposure and the second ~1 h. The results from the two trials showed that, above a received level of 166 dB re 1 μPa (rms) [10], the turtles noticeably

[10] rms = root mean square. This measure represents the average received sound pressure over the duration of the pulse, with duration being defined in a specific way (from the time when 5% of the pulse energy has been received to the time when 95% of the energy has been received). The rms received level of a seismic pulse is typically

increased their swim speed relative to periods when no airguns were operating. The behavior of the sea turtles became more erratic when received levels exceeded 175 dB re 1 μPa rms. The authors suggested that the erratic behavior exhibited by the caged sea turtles would likely, in unrestrained turtles, be expressed as an avoidance response (McCauley et al. 2000a,b).

O'Hara and Wilcox (1990) tested the reactions to airguns by loggerhead sea turtles held in a 300 × 45 m area of a canal in Florida with a bottom depth of 10 m. Nine turtles were tested at different times. The sound source consisted of one 10 in^3 airgun plus two 0.8 in^3 "poppers" operating at 2000 psi[11] and an airgun-depth of 2 m for prolonged periods of 20–36 h. The turtles maintained a standoff range of about 30 m when exposed to airgun pulses every 15 or 7.5 s. Some turtles may have remained on the bottom of the enclosure when exposed to airgun pulses. O'Hara and Wilcox (1990) did not measure the received airgun sound levels. McCauley et al. (2000a,b) estimated that "the level at which O'Hara saw avoidance was around 175–176 dB re 1 μPa rms." The levels received by the turtles in the Florida study probably were actually a few dB less than 175–176 dB because the calculations by McCauley et al. apparently did not allow for the shallow 2-m airgun depth in the Florida study. The effective source level of airguns is less when they are at a depth of 2 m vs. 5 m (Greene et al. 2000).

Moein et al. (1994) investigated the avoidance behavior and physiological responses of loggerhead turtles exposed to an operating airgun, as well as the effects on their hearing. The turtles were held in a netted enclosure ~18 m by 61 m by 3.6 m deep, with an airgun of unspecified size at each end. Only one airgun was operated at any one time; the firing rate was one shot every 5–6 s. Ten turtles were tested individually, and seven of these were retested several days later. The airgun was initially discharged when the turtles were near the center of the enclosure and the subsequent movements of the turtles were documented. The turtles exhibited avoidance during the first presentation of airgun sounds at a mean range of 24 m, but the avoidance response waned quickly. Additional trials conducted on the same turtles several days later did not show statistically significant avoidance reactions. However, there was an indication of slight initial avoidance followed by rapid waning of the avoidance response which the authors described as "habituation". Their auditory study indicated that exposure to the airgun pulses may have resulted in temporary threshold shift (TTS; see later section). Reduced hearing sensitivity may also have contributed to the waning response upon continued exposure. Based on physiological measurements, there was some evidence of increased stress in the sea turtles, but this stress could also have resulted from handling of the turtles.

Inconsistencies in reporting procedures and experimental design prevent direct comparison of this study with either McCauley et al. (2000a,b) or O'Hara and Wilcox (1990). Moein et al. (1994) stated, without further details, that "three different decibel levels (175, 177, 179) were utilized" during each test. These figures probably are received levels in dB re 1 μPa, and probably relate to the initial exposure distance (mean 24 m), but these details were not specified. Also, it was not specified whether these values were measured or estimated, or whether they are expressed in peak-peak, peak, rms, SEL, or some

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about 10 dB less than its peak level, and about 16 dB less than its peak-to-peak level (Greene et al. 1997, 2000; McCauley et al. 1998, 2000a,b).

[11] There was no significant reaction by five turtles during an initial series of tests with the airguns operating at the unusually low pressure of 1000 psi. The source and received levels of airgun sounds would have been substantially lower when the air pressure was only 1000 psi than when it was at the more typical operating pressure of 2000 psi.

other units. Given the shallow water in the enclosure (3.6 m), any estimates based on simple assumptions about propagation would be suspect.

Lenhardt (2002) exposed captive loggerhead sea turtles while underwater to seismic airgun (Bolt 600) sounds in a large net enclosure. At received levels of 151–161 dB, turtles were found to increase swimming speeds. Similar to the McCauley et al. studies (2000a,b--see above), near a received level of ~175 dB, an avoidance reaction was common in initial trials, but habituation then appeared to occur. Based on ABRs measured pre- and post-airgun exposures, a TTS of over 15 dB was found in one animal, with recovery two weeks later. Lenhardt (2002) suggested that exposure of sea turtles to airguns at water depths >10 m may result in exposure to more energy in the low frequencies with unknown biological effects.

Despite the problems in comparing these studies, they are consistent in showing that, at some received level, sea turtles show avoidance of an operating airgun. McCauley et al. (2000a,b) found evidence of behavioral responses when the received level from a single small airgun was 166 dB re 1 μPa rms and avoidance responses at 175 dB re 1 μPa rms. Based on these data, McCauley et al. estimated that, for a typical airgun array (2678 in^3, 12-elements) operating in 100–120 m water depth, sea turtles may exhibit behavioral changes at ~2 km and avoidance around 1 km. These estimates are subject to great variation, depending on the seismic source and local propagation conditions.

A further potential complication is that sea turtles on or near the bottom may receive sediment-borne "headwave" signals from the airguns (McCauley et al. 2000a,b). As previously discussed, it is believed that sea turtles use bone conduction to hear. It is unknown how sea turtles might respond to the headwave component of an airgun impulse or to bottom vibrations.

Related studies involving stimuli other than airguns may also be relevant. ***(1)*** Two loggerhead turtles resting on the bottom of shallow tanks responded repeatedly to low-frequency (20–80 Hz) tones by becoming active and swimming to the surface. They remained at the surface or only slightly submerged for the remainder of the 1-min trial (Lenhardt 1994). Although no detailed data on sound levels at the bottom vs. surface were reported, the surfacing response probably reduced the levels of underwater sound to which the turtles were exposed. ***(2)*** In a separate study, a loggerhead and a Kemp's ridley sea turtle responded similarly when vibratory stimuli at 250 or 500 Hz were applied to the head for 1 s (Lenhardt et al. 1983). There appeared to be rapid habituation to these vibratory stimuli. ***(3)*** Turtles in tanks showed agitated behaviour when exposed to simulated boat noise and recordings from the U.S. Navy's Low Frequency Active (LFA) sonar (Samuel et al. 2005, 2006). The tones and vibratory stimuli used in these two studies were quite different from airgun pulses. However, it is possible that resting sea turtles may exhibit a similar "alarm" response, possibly including surfacing or alternatively diving, when exposed to any audible noise, regardless of whether it is a pulsed sound or tone.

***Monitoring Results.*—**Data on sea turtle behavior near airgun operations have also been collected during marine mammal and sea turtle monitoring and mitigation programs associated with various seismic operations around the world. Although the primary objectives concerned marine mammals, sea turtle sightings have also been documented in some of monitoring projects. Results suggest that some sea turtles exhibit behavioral changes and/or avoidance within an area of unknown size near a seismic vessel. However, avoidance of approaching seismic vessels is sufficiently limited and small-scale such that sea turtles are often seen from operating seismic vessels. Also, average distances from the airguns to these sea turtles are usually not greatly increased when the airguns are operating as compared with times when airguns are silent.

For example, during six large-source (10–20 airguns; 3050–8760 in^3) and small-source (up to six airguns or three GI guns; 75–1350 in^3) surveys conducted by L-DEO during 2003–2005, the mean closest point of approach (CPA) for turtles was closer during non-seismic than seismic periods: 139 m vs. 228 m and 120 m vs. 285 m, respectively (Holst et al. 2006). During a large-source L-DEO seismic survey off the Pacific coast of Central America in 2008, the turtle sighting rate during non-seismic periods was seven times greater than that during seismic periods (Holst and Smultea 2008). In addition, distances of turtles seen from the seismic vessel were significantly farther from the airgun array when it was operating (mean 159 m, n = 77) than when the airguns were off (mean 118 m, n = 69; Mann-Whitney U test, P<0.001) (Holst and Smultea 2008). During another L-DEO survey in the Eastern Tropical Pacific in 2008, the turtle sighting rate during non-seismic periods was 1.5 times greater than that during seismic periods; however, turtles tended to be seen closer to the airgun array when it was operating, but this difference was not statistically significant (Hauser et al. 2008).

Weir (2007) reported on the behavior of sea turtles near seismic exploration operations off Angola, West Africa. A total of 240 sea turtles were seen during 676 h of vessel-based monitoring, mainly for associated marine mammals mitigation and monitoring observations. Airgun arrays with total volumes of 5085 and 3147 in^3 were used at different times during the seismic program. Sea turtles tended to be seen slightly closer to the seismic source, and at sighting rates twice as high, during non-seismic vs. seismic periods (Weir 2007). However, there was no significant difference in the median distance of turtle sightings from the array during non-seismic vs. seismic periods, with means of 743 m (n = 112) and 779 m (n = 57).

Off northeastern Brazil, 46 sea turtles were seen during 2028 h of vessel-based monitoring of seismic exploration using 4–8 GI airguns (Parente et al. 2006). There were no apparent differences in turtle sighting rates during seismic and non-seismic periods, but detailed behavioral data during seismic operations were lacking (Parente et al. 2006).

Behavioral responses of marine mammals and fish to seismic surveys sometimes vary depending on species, time of year, activity of the animal, and other unknown factors. The same species may show different responses at different times of year or even on different days (e.g., Richardson et al. 1995; Thomson et al. 2001). Sea turtles of different ages vary in size, behavior, feeding habits, and preferred water depths. Nothing specific is known about the ways in which these factors may be related to airgun sound effects in sea turtles. However, it is reasonable to expect lesser effects in young turtles concentrated near the surface (where levels of airgun sounds are attenuated) as compared with older turtles that spend more time at depth where airgun sounds are generally stronger.

3. Possible Effects of Airgun Sounds on Distribution

In captive enclosures, sea turtles generally respond to seismic noise by startling, increasing swimming speed, and/or swimming away from the noise source. Animals resting on the bottom often become active and move toward the surface where received sound levels normally will be reduced, although some turtles dive upon exposure. Unfortunately, quantitative data for free-ranging sea turtles exposed to seismic pulses are very limited, and potential long-term behavioral effects of seismic exposure have not been investigated. The paucity of data precludes clear predictions of sea turtle responses to seismic noise. Available evidence suggests that localized behavioral and distributional effects on sea turtles are likely during seismic operations, including responses to the seismic vessel, airguns, and other gear (e.g., McCauley 1994; Pendoley 1997; Weir 2007). Pendoley (1997) summarized potential effects of seismic operations on the behavior and distribution of sea turtles and identified biological periods and

habitats considered most sensitive to potential disturbance. The possible responses of free-ranging sea turtles to seismic pulses could include

- avoiding the entire seismic survey area to the extent that turtles move to less preferred habitat;
- avoiding only the immediate area around the active seismic vessel (i.e., local avoidance of the source vessel but remain in the general area); and
- exhibiting no appreciable avoidance, although short-term behavioral reactions are likely.

Complete avoidance of an area, if it occurred, could exclude sea turtles from their preferred foraging area and could displace them to areas where foraging is sub-optimal. Avoidance of a preferred foraging area may prevent sea turtles from obtaining preferred prey species and hence could impact their nutritional status. The potential alteration of a migration route might also have negative impacts. However, it is not known whether avoidance by sea turtles would ever be on a sufficient geographic scale, or be sufficiently prolonged, to prevent turtles from reaching an important destination.

Available evidence suggests that the zone of avoidance around seismic sources is not likely to exceed a few kilometers (McCauley et al. 2000a,b). Avoidance reactions on that scale could prevent sea turtles from using an important coastal area or bay if there was a prolonged seismic operation in the area, particularly in shallow waters (e.g., Pendoley 1997). Sea turtles might be excluded from the area for the duration of the seismic operation, or they might remain but exhibit abnormal behavioral patterns (e.g., lingering longer than normal at the surface where received sound levels are lower). Whether those that were displaced would return quickly after the seismic operation ended is unknown.

It is unclear whether exclusion from a particular nesting beach by seismic operations, if it occurred, would prevent or decrease reproductive success. It is believed that females migrate to the region of their birth and select a nesting beach (Miller 1997). However, the degree of site fidelity varies between species and also intra-seasonally by individuals. If a sea turtle is excluded from a particular beach, it may select a more distant, undisturbed nesting site in the general area (Miller 1997). For instance, Bjorndal et al. (1983) reported a maximal intra-seasonal distance between nesting sites of 290 km, indicating that turtles use multiple nesting sites spaced up to a few hundred kilometers apart. Also, it is uncertain whether a turtle that failed to go ashore because of seismic survey activity would abandon the area for that full breeding cycle, or would simply delay going ashore until the seismic vessel moved to a different area.

Shallow coastal waters can contain relatively high densities of sea turtles during nesting, hatching, and foraging periods. Thus, seismic operations in these areas could correspondingly impact a relatively higher number of individual turtles during sensitive biological periods. Samuel et al. (2005) noted that anthropogenic noise in vital sea turtle habitats, such as a major coastal foraging area off Long Island, NY, could affect sea turtle behaviour and ecology. There are no specific data that demonstrate the consequences to sea turtles if seismic operations with large or small arrays of airguns occur in important areas at biologically important times of year. However, a number of mitigation measures can, on a case-by-case basis, be considered for application in areas important to sea turtles (e.g., Pendoley 1997).

4. Possible Impacts of Airgun Sounds on Hearing

Noise-induced hearing damage can be either temporary or permanent. In general, the received sound must be strong for either to occur, and must be especially strong and/or prolonged for permanent impairment to occur.

Few studies have directly investigated hearing or noise-induced hearing loss in sea turtles. Moein et al. (1994) used an evoked potential method to test the hearing of loggerhead sea turtles exposed to a few hundred pulses from a single airgun. Turtle hearing was tested before, within 24 h after, and two

weeks after exposure to pulses of airgun sound. Levels of airgun sound to which the turtles were exposed were not specifically reported. The authors concluded that five turtles exhibited some change in their hearing when tested within 24 h after exposure relative to pre-exposure hearing, and that hearing had reverted to normal when tested two weeks after exposure. The results are consistent with the occurrence of TTS upon exposure of the turtles to airgun pulses. Unfortunately, the report did not state the size of the airgun used, or the received sound levels at various distances. The distances of the turtles from the airgun were also variable during the tests; the turtle was about 30 m from the airgun at the start of each trial, but it could then either approach the airgun or move away to a maximum of about 65 m during subsequent airgun pulses. Thus, the levels of airgun sounds that apparently elicited TTS are not known. Nonetheless, it is noteworthy that there was evidence of TTS from exposure to pulses from a single airgun. However, the turtles were confined and unable to move more than about 65 m away. Similarly, Lenhardt (2002) exposed loggerhead turtles in a large net enclosure to airgun pulses. A TTS of >15 dB was evident for one loggerhead turtle, with recovery occurring in two weeks. Turtles in the open sea might have moved away from an airgun operating at a fixed location, and in the more typical case of a towed airgun or airgun array, very few shots would occur at or around one location. Thus, exposure to underwater sound during net-enclosure experiments was not typical of that expected during an operational seismic survey.

Studies with terrestrial reptiles have demonstrated that exposure to airborne impulse noise can cause hearing loss. For example, desert tortoises (*Gopherus agassizii*) exhibited TTS after exposure to repeated high-intensity sonic booms (Bowles et al. 1999). Recovery from these temporary hearing losses was usually rapid (<1 h), which suggested that tortoises can tolerate these exposures without permanent injury (Bowles et al. 1999).

The results from captive, restrained sea turtles exposed repeatedly to seismic sounds in enclosed areas indicate that TTS is possible under these artificial conditions. However, there are no data to indicate whether there are any plausible field situations in which exposure to repeated airgun pulses at close range could cause permanent threshold shift (PTS) or hearing impairment in sea turtles. Hearing impairment (whether temporary or permanent) from seismic sounds is considered unlikely to occur at sea; turtles are unlikely to be exposed to more than a few strong pulses close to the sound source, as individuals are mobile and the vessel travels relatively quickly compared to the swimming speed of a sea turtle. However, in the absence of specific information on received levels of impulse sound necessary to elicit TTS and PTS in sea turtles, it is uncertain whether there are circumstances where these effects could occur in the field. If sea turtles exhibit little or no behavioral avoidance, or if they acclimate to seismic noise to the extent that avoidance reactions cease, sea turtles might sustain hearing loss if they are close enough to seismic sources. Similarly, in the absence of quantitative data on behavioral responses, it is unclear whether turtles in the area of seismic operations prior to start-up move out of the area when standard ramp-up (=soft-start) procedures are in effect. It has been proposed that sea turtles require a longer ramp-up period because of their relatively slow swimming speeds (Eckert 2000). However, it is unclear at what distance (if any) from a seismic source sea turtles could sustain hearing impairment, and whether there would ever be a possibility of exposure to sufficiently high levels for a sufficiently long period to cause permanent hearing damage.

In theory, a reduction in hearing sensitivity, either temporary or permanent, may be harmful for sea turtles. However, very little is known about the role of sound perception in the sea turtle's normal activities. While it is not possible to estimate how much of a problem it would be for a turtle to have either temporary or permanent hearing impairment, there is some evidence indicating that hearing plays an important role in sea turtle survival. ***(1)*** It has been suggested (Eckert et al. 1998; Eckert 2000) that sea

turtles may use passive reception of acoustic signals to detect the hunting sonar of killer whales (*Orcinus orca*), a known predator of leatherback sea turtles *Dermochelys coriacea* (Fertl and Fulling 2007). Further investigation is needed before this hypothesis can be accepted. Some communication calls of killer whales include components at frequencies low enough to overlap the frequency range where sea turtles hear. However, the echolocation signals of killer whales are at considerably higher frequencies and may be inaudible to sea turtles (e.g., Simon et al. 2007). ***(2)*** Hearing impairment, either temporary or permanent, might inhibit a turtle's ability to avoid injury from vessels. A recent study found that green sea turtles often responded behaviorally to close, oncoming small vessels and that the nature of the response was related to vessel speed, with fewer turtles displaying a flee response as vessel speed increased (Hazel et al. 2007). However, Hazel et al. (2007) suggested that a turtles' ability to detect an approaching vessel was vision-dependent. ***(3)*** Hearing may play a role in navigation. For example, it has been proposed that sea turtles may identify their breeding beaches by their acoustic signature (Lenhardt et al. 1983). However, available evidence suggests that visual, wave, and magnetic cues are the main navigational cues used by sea turtles, at least in the case of hatchlings and juveniles (Lohmann et al. 1997, 2001; Lohmann and Lohmann 1998).

5. Other Physical Effects

Other potential direct physical effects to sea turtles during seismic operations include entanglement with seismic gear (e.g., cables, buoys, streamers, etc.) and ship strikes (Pendoley 1997; Ketos Ecology 2007; Weir 2007; Hazel et al. 2007). Entanglement of sea turtles with marine debris, fishing gear, and other equipment has been documented; turtles can become entangled in cables, lines, nets, or other objects suspended in the water column and can become injured or fatally wounded, drowned, or suffocated (e.g., Lutcavage et al. 1997). Seismic-survey personnel have reported that sea turtles (number unspecified) became fatally entrapped between gaps in tail-buoys associated with industrial seismic vessel gear deployed off West Africa in 2003 (Weir 2007). However, no incidents of entanglement of sea turtles have been documented during NSF-funded seismic surveys, which since 2003 have included dedicated ship-based monitoring by trained biological observers, in some cases in areas with many sea turtles (e.g.,Holst et al. 2005a,b; Holst and Smultea 2008; Hauser et al. 2008).

6. Conclusions

Based on available data concerning sea turtles and other marine animals, it is likely that some sea turtles exhibit behavioral changes and/or avoidance within an area of unknown size near an operating seismic survey vessel. There is also the possibility of temporary hearing impairment or perhaps even permanent hearing damage to turtles close to the airguns. However, there are very few data on temporary hearing loss and no data on permanent hearing loss in sea turtles exposed to airgun pulses. Although some information is available about effects of exposure to sounds from a single airgun on captive sea turtles, the long term acoustic effects (if any) of a full-scale marine seismic operation on free-ranging sea turtles are unknown. Entanglement of turtles in seismic gear and vessel strikes during seismic survey operations are also possible but do not seem to be common. The greatest impact is likely to occur if seismic operations occur in or near areas where turtles concentrate, and at seasons when turtles are concentrated there. However, there are no specific data that demonstrate the consequences of such seismic operations to sea turtles. Until more data become available, it would be prudent to avoid seismic operations near important nesting beaches or in areas of known concentrated feeding during times of year when those areas are in use by many sea turtles.

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APPENDIX D:

REVIEW OF THE EFFECTS OF AIRGUN SOUNDS ON FISHES[12]

Here we review literature about the effects of airgun sounds on fishes during seismic surveys. The potential effect of seismic sounds on fish has been studied with a variety of taxa, including marine, freshwater, and anadromous species (reviewed by Fay and Popper 2000; Ladich and Popper 2004; Hastings and Popper 2005; Popper and Hastings 2009a,b).

It is sometimes difficult to interpret studies on the effects of underwater sound on marine animals because authors often do not provide enough information, including received sound levels, source sound levels, and specific characteristics of the sound. Specific characteristics of the sound include units and references, whether the sound is continuous or impulsive, and its frequency range. Underwater sound pressure levels are typically reported as a number of decibels referenced to a reference level, usually 1 micro-Pascal (µPa). However, the sound pressure dB number can represent multiple types of measurements, including "zero to peak", "peak to peak", or averaged ("rms"). Sound exposure levels (SEL) may also be reported as dB. The SEL is the integration of all the acoustic energy contained within a single sound event. Unless precise measurement types are reported, it can be impossible to directly compare results from two or more independent studies.

1. Acoustic Capabilities

Sensory systems – like those that allow for hearing – provide information about an animal's physical, biological, and social environments, in both air and water. Extensive work has been done to understand the structures, mechanisms, and functions of animal sensory systems in aquatic environments (Atema et al. 1988; Kapoor and Hara 2001; Collin and Marshall 2003). All fish species have hearing and skin-based mechanosensory systems (inner ear and lateral line systems, respectively) that provide information about their surroundings (Fay and Popper 2000). Fay (2009) and some others refer to the ambient sounds to which fishes are exposed as 'underwater soundscapes'. Anthropogenic sounds can have important negative consequences for fish survival and reproduction if they disrupt an individual's ability to sense its soundscape, which often tells of predation risk, prey items, or mating opportunities. Potential negative effects include masking of key environmental sounds or social signals, displacement of fish from their habitat, or interference with sensory orientation and navigation.

Fish hearing via the inner ear is typically restricted to low frequencies. As with other vertebrates, fish hearing involves a mechanism whereby the beds of hair cells (Howard et al. 1988; Hudspeth and Markin 1994) located in the inner ear are mechanically affected and cause a neural discharge (Popper and Fay 1999). At least two major pathways for sound transmittance between sound source and the inner ear have been identified for fishes. The most primitive pathway involves direct transmission to the inner ear's otolith, a calcium carbonate mass enveloped by sensory hairs. The inertial difference between the dense otolith and the less-dense inner ear causes the otolith to stimulate the surrounding sensory hair cells. This motion differential is interpreted by the central nervous system as sound.

The second transmission pathway between sound source and the inner ear of fishes is via the swim bladder, a gas-filled structure that is much less dense than the rest of the fish's body. The swim bladder, being more compressible and expandable than either water or fish tissue, will differentially contract and

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[12] By **John R. Christian and R.C. Bocking**, LGL Ltd., environmental research associates (rev. Feb. 2010)

expand relative to the rest of the fish in a sound field. The pulsating swim bladder transmits this mechanical disturbance directly to the inner ear (discussed below). Such a secondary source of sound detection may be more or less effective at stimulating the inner ear depending on the amplitude and frequency of the pulsation, and the distance and mechanical coupling between the swim bladder and the inner ear (Popper and Fay 1993).

A recent paper by Popper and Fay (2010) discusses the designation of fishes based on sound detection capabilities. They suggest that the designations 'hearing specialist' and 'hearing generalist' no longer be used for fishes because of their vague and sometimes contradictory definitions, and that there is instead a range of hearing capabilities across species that is more like a continuum, presumably based on the relative contributions of pressure to the overall hearing capabilities of a species.

According to Popper and Fay (2010), one end of this continuum is represented by fishes that only detect particle motion because they lack pressure-sensitive gas bubbles (e.g., swim bladder). These species include elasmobranchs (e.g., sharks) and jawless fishes, and some teleosts including flatfishes. Fishes at this end of the continuum are typically capable of detecting sound frequencies below 1500 Hz.

The other end of the fish hearing continuum is represented by fishes with highly specialized otophysic connections between pressure receptive organs, such as the swim bladder, and the inner ear. These fishes include some squirrelfish, mormyrids, herrings, and otophysan fishes (freshwater fishes with Weberian apparatus, an articulated series of small bones that extend from the swim bladder to the inner ear). Rather than being limited to 1.5 kHz or less in hearing, these fishes can typically hear up to several kHz. One group of fish in the anadromous herring sub-family Alosinae (shads and menhaden) can detect sounds to well over 180 kHz (Mann et al. 1997, 1998, 2001). This may be the widest hearing range of any vertebrate that has been studied to date. While the specific reason for this very high frequency hearing is not totally clear, there is strong evidence that this capability evolved for the detection of the ultrasonic sounds produced by echolocating dolphins to enable the fish to detect, and avoid, predation (Mann et al. 1997; Plachta and Popper 2003).

All other fishes have hearing capabilities that fall somewhere between these two extremes of the continuum. Some have unconnected swim bladders located relatively far from the inner ear (e.g., salmonids, tuna) while others have unconnected swim bladders located relatively close to the inner ear (e.g., Atlantic cod, *Gadus morhua*). There has also been the suggestion that Atlantic cod can detect 38 kHz (Astrup and Møhl 1993). However, the general consensus was that this was not hearing with the ear; probably the fish were responding to exceedingly high pressure signals from the 38-kHz source through some other receptor in the skin, such as touch receptors (Astrup and Møhl 1998).

It is important to recognize that the swim bladder itself is not a sensory end organ, but rather an intermediate part of the sound pathway between sound source and the inner ear of some fishes. The inner ear of fishes is ultimately the organ that translates the particle displacement component into neural signals for the brain to interpret as sound.

A third mechanosensory pathway found in most bony fishes and elasmobranchs (i.e., cartilaginous fishes) involves the lateral line system. It too relies on sensitivity to water particle motion. The basic sensory unit of the lateral line system is the neuromast, a bundle of sensory and supporting cells whose projecting cilia, similar to those in the ears, are encased in a gelatinous cap. Neuromasts detect distorted sound waves in the immediate vicinity of fishes. Generally, fishes use the lateral line system to detect the particle displacement component of low frequency acoustic signals (up to 160 to 200 Hz) over a distance of one to two body lengths. The lateral line is used in conjunction with other sensory systems, including hearing (Sand 1981; Coombs and Montgomery 1999).

2. Potential Effects on Fishes

Review papers on the effects of anthropogenic sources of underwater sound on fishes have been published recently (Popper 2009; Popper and Hastings 2009a,b). These papers consider various sources of anthropogenic sound, including seismic airguns. For the purposes of this review, only the effects of seismic airgun sound are considered.

2.1 Marine Fishes

Evidence for airgun-induced damage to fish ears has come from studies using pink snapper *Pagrus auratus* (McCauley et al. 2000a,b, 2003). In these experiments, fish were caged and exposed to the sound of a single moving seismic airgun every 10 s over a period of 1 h and 41 min. The source SPL at 1 m was about 223 dB re 1 $\mu Pa \cdot m_{p\text{-}p}$, and the received SPLs ranged from 165 to 209 dB re 1 $\mu Pa_{p\text{-}p}$. The sound energy was highest over the 20–70 Hz frequency range. The pink snapper were exposed to more than 600 airgun discharges during the study. In some individual fish, the sensory epithelium of the inner ear sustained extensive damage as indicated by ablated hair cells. Damage was more extensive in fish examined 58 days post-exposure compared to those examined 18 h post-exposure. There was no evidence of repair or replacement of damaged sensory cells up to 58 days post-exposure. McCauley et al. (2000a,b, 2003) included the following caveats in the study reports: (1) fish were caged and unable to swim away from the seismic source, (2) only one species of fish was examined, (3) the impact on the ultimate survival of the fish is unclear, and (4) airgun exposure specifics required to cause the observed damage were not obtained (i.e., a few high SPL signals or the cumulative effect of many low to moderate SPL signals).

The fish exposed to sound from a single airgun in this study also exhibited startle responses to short range start up and high-level airgun signals (i.e., with received SPLs of 182 to 195 dB re 1 μPa_{rms} (McCauley et al. 2000a,b). Smaller fish were more likely to display a startle response. Responses were observed above received SPLs of 156 to 161 dB re 1 μPa_{rms}. The occurrence of both startle response (classic C-turn response) and alarm responses (e.g., darting movements, flash school expansion, fast swimming) decreased over time. Other observations included downward distributional shift that was restricted by the 10 m x 6 m x 3 m cages, increase in swimming speed, and the formation of denser aggregations. Fish behavior appeared to return to pre-exposure state 15–30 min after cessation of seismic firing.

Pearson et al. (1992) investigated the effects of seismic airgun sound on the behavior of captive rockfishes (*Sebastes* sp.) exposed to the sound of a single stationary airgun at a variety of distances. The airgun used in the study had a source SPL at 1 m of 223 dB re 1 $\mu Pa \cdot m_{0\text{-}p}$, and measured received SPLs ranged from 137 to 206 dB re 1 $\mu Pa_{0\text{-}p}$. The authors reported that rockfishes reacted to the airgun sounds by exhibiting varying degrees of startle and alarm responses, depending on the species of rockfish and the received SPL. Startle responses were observed at a minimum received SPL of 200 dB re 1 $\mu Pa_{0\text{-}p}$, and alarm responses occurred at a minimum received SPL of 177 dB re 1 $\mu Pa_{0\text{-}p}$. Other observed behavioral changes included the tightening of schools, downward distributional shift, and random movement and orientation. Some fishes ascended in the water column and commenced to mill (i.e., “eddy”) at increased speed, while others descended to the bottom of the enclosure and remained motionless. Pre-exposure behavior was reestablished from 20 to 60 min after cessation of seismic airgun discharge. Pearson et al. (1992) concluded that received SPL thresholds for overt rockfish behavioral response and more subtle rockfish behavioral response are 180 dB re 1 $\mu Pa_{0\text{-}p}$ and 161 dB re 1 $\mu Pa_{0\text{-}p}$, respectively.

Using an experimental hook and line fishery approach, Skalski et al. (1992) studied the potential effects of seismic airgun sound on the distribution and catchability of rockfishes. The source SPL of the single airgun used in the study was 223 dB re 1 μPa·m $_{0\text{-}p}$, and the received SPLs at the bases of the rockfish aggregations ranged from 186 to 191 dB re 1 μPa$_{0\text{-}p}$. Characteristics of the fish aggregations were assessed using echosounders. During long-term stationary seismic airgun discharge, there was an overall downward shift in fish distribution. The authors also observed a significant decline in total catch of rockfishes during seismic discharge. It should be noted that this experimental approach was quite different from an actual seismic survey, in that duration of exposure was much longer.

In another study, caged European sea bass (*Dicentrarchus labrax*) were exposed to multiple discharges from a moving seismic airgun array with a source SPL of about 256 dB re 1 μPa·m $_{0\text{-}p}$ (unspecified measure type) (Santulli et al. 1999). The airguns were discharged every 25 s during a 2-h period. The minimum distance between fish and seismic source was 180 m. The authors did not indicate any observed pathological injury to the sea bass. Blood was collected from both exposed fish (6 h post-exposure) and control fish (6 h pre-exposure) and subsequently analyzed for cortisol, glucose, and lactate levels. Levels of cortisol, glucose, and lactate were significantly higher in the sera of exposed fish compared to sera of control fish. The elevated levels of all three chemicals returned to pre-exposure levels within 72 h of exposure (Santulli et al. 1999).

Santulli et al. (1999) also used underwater video cameras to monitor fish response to seismic airgun discharge. Resultant video indicated slight startle responses by some of the sea bass when the seismic airgun array discharged as far as 2.5 km from the cage. The proportion of sea bass that exhibited startle response increased as the airgun sound source approached the cage. Once the seismic array was within 180 m of the cage, the sea bass were densely packed at the middle of the enclosure, exhibiting random orientation, and appearing more active than they had been under pre-exposure conditions. Normal behavior resumed about 2 h after airgun discharge nearest the fish (Santulli et al. 1999).

Boeger et al. (2006) reported observations of coral reef fishes in field enclosures before, during and after exposure to seismic airgun sound. This Brazilian study used an array of eight airguns that was presented to the fishes as both a mobile sound source and a static sound source. Minimum distances between the sound source and the fish cage ranged from 0 to 7 m. Received sound levels were not reported by Boeger et al. (2006). Neither mortality nor external damage to the fishes was observed in any of the experimental scenarios. Most of the airgun array discharges resulted in startle responses although these behavioral changes lessened with repeated exposures, suggesting habituation.

Chapman and Hawkins (1969) investigated the reactions of free ranging whiting (silver hake), *Merluccius bilinearis*, to an intermittently discharging stationary airgun with a source SPL of 220 dB re 1 μPa·m$_{0\text{-}p}$. Received SPLs were estimated to be 178 dB re 1 μPa$_{0\text{-}p}$. The whiting were monitored with an echosounder. Prior to any airgun discharge, the fish were located at a depth range of 25 to 55 m. In apparent response to the airgun sound, the fish descended, forming a compact layer at depths greater than 55 m. After an hour of exposure to the airgun sound, the fish appeared to have habituated as indicated by their return to the pre-exposure depth range, despite the continuing airgun discharge. Airgun discharge ceased for a time and upon its resumption, the fish again descended to greater depths, indicating only temporary habituation.

Hassel et al. (2003, 2004) studied the potential effects of exposure to airgun sound on the behavior of captive lesser sandeel, *Ammodytes marinus*. Depth of the study enclosure used to hold the sandeel was about 55 m. The moving airgun array had an estimated source SPL of 256 dB re 1 μPa·m (unspecified measure type). Received SPLs were not measured. Exposures were conducted over a 3-day period in a

10 km × 10 km area with the cage at its center. The distance between airgun array and fish cage ranged from 55 m when the array was overhead to 7.5 km. No mortality attributable to exposure to the airgun sound was noted. Behavior of the fish was monitored using underwater video cameras, echosounders, and commercial fishery data collected close to the study area. The approach of the seismic vessel appeared to cause an increase in tail-beat frequency although the sandeels still appeared to swim calmly. During seismic airgun discharge, many fish exhibited startle responses, followed by flight from the immediate area. The frequency of occurrence of startle response seemed to increase as the operating seismic array moved closer to the fish. The sandeels stopped exhibiting the startle response once the airgun discharge ceased. The sandeel tended to remain higher in the water column during the airgun discharge, and none of them were observed burying themselves in the soft substrate. The commercial fishery catch data were inconclusive with respect to behavioral effects.

Various species of demersal fishes, blue whiting, and some small pelagic fishes were exposed to a moving seismic airgun array with a source SPL of about 250 dB re 1 μPa·m (unspecified measure type) (Dalen and Knutsen 1986). Received SPLs estimated using the assumption of spherical spreading ranged from 200 to 210 dB re 1 μPa (unspecified measure type). Seismic sound exposures were conducted every 10 s during a one week period. The authors used echosounders and sonars to assess the pre- and post-exposure fish distributions. The acoustic mapping results indicated a significant decrease in abundance of demersal fish (36%) after airgun discharge but comparative trawl catches did not support this. Non-significant reductions in the abundances of blue whiting and small pelagic fish were also indicated by post-exposure acoustic mapping.

La Bella et al. (1996) studied the effects of exposure to seismic airgun sound on fish distribution using echosounder monitoring and changes in catch rate of hake by trawl, and clupeoids by gill netting. The seismic array used was composed of 16 airguns and had a source SPL of 256 dB re 1 μPa ·m $_{0\text{-}p}$ The shot interval was 25 s, and exposure durations ranged from 4.6 to 12 h. Horizontal distributions did not appear to change as a result of exposure to seismic discharge, but there was some indication of a downward shift in the vertical distribution. The catch rates during experimental fishing did not differ significantly between pre- and post-seismic fishing periods.

Wardle et al. (2001) used video and telemetry to make behavioral observations of marine fishes (primarily juvenile saithe, adult pollock, juvenile cod, and adult mackerel) inhabiting an inshore reef off Scotland before, during, and after exposure to discharges of a stationary airgun. The received SPLs ranged from about 195 to 218 dB re 1 μPa$_{0\text{-}p}$. Pollock did not move away from the reef in response to the seismic airgun sound, and their diurnal rhythm did not appear to be affected. However, there was an indication of a slight effect on the long-term day-to-night movements of the pollock. Video camera observations indicated that fish exhibited startle responses ("C-starts") to all received levels. There were also indications of behavioral responses to visual stimuli. If the seismic source was visible to the fish, they fled from it. However, if the source was not visible to the fish, they often continued to move toward it.

The potential effects of exposure to seismic sound on fish abundance and distribution were also investigated by Slotte et al. (2004). Twelve days of seismic survey operations spread over a period of 1 month used a seismic airgun array with a source SPL of 222.6 dB re 1 μPa·m$_{p\text{-}p}$. The SPLs received by the fish were not measured. Acoustic surveys of the local distributions of various kinds of pelagic fish, including herring, blue whiting, and mesopelagic species, were conducted during the seismic surveys. There was no strong evidence of short-term horizontal distributional effects. With respect to vertical distribution, blue whiting and mesopelagics were distributed deeper (20 to 50 m) during the seismic

survey compared to pre-exposure. The average densities of fish aggregations were lower within the seismic survey area, and fish abundances appeared to increase in accordance with increasing distance from the seismic survey area.

Fertilized capelin (*Mallotus villosus*) eggs and monkfish (*Lophius americanus*) larvae were exposed to seismic airgun sound and subsequently examined and monitored for possible effects of the exposure (Payne et al. 2009). The laboratory exposure studies involved a single airgun. Approximate received SPLs measured in the capelin egg and monkfish larvae exposures were 199 to 205 dB re 1 $\mu Pa_{p\text{-}p}$ and 205 dB re 1 $\mu Pa_{p\text{-}p}$, respectively. The capelin eggs were exposed to either 10 or 20 airgun discharges, and the monkfish larvae were exposed to either 10 or 30 discharges. No statistical differences in mortality/morbidity between control and exposed subjects were found at 1 to 4 days post-exposure in any of the exposure trials for either the capelin eggs or the monkfish larvae.

In uncontrolled experiments, Kostyvchenko (1973) exposed the eggs of numerous fish species (anchovy, red mullet, crucian carp, blue runner) to various sound sources, including seismic airguns. With the seismic airgun discharge as close as 0.5 m from the eggs, over 75% of them survived the exposure. Egg survival rate increased to over 90% when placed 10 m from the airgun sound source. The range of received SPLs was about 215 to 233 dB re 1 $\mu Pa_{0\text{-}p}$.

Eggs, yolk sac larvae, post-yolk sac larvae, post-larvae, and fry of various commercially important fish species (cod, saithe, herring, turbot, and plaice) were exposed to received SPLs ranging from 220 to 242 dB re 1 µPa (unspecified measure type) (Booman et al. 1996). These received levels corresponded to exposure distances ranging from 0.75 to 6 m. The authors reported some cases of injury and mortality but most of these occurred as a result of exposures at very close range (i.e., <15 m). The rigor of anatomical and pathological assessments was questionable.

Saetre and Ona (1996) applied a "worst-case scenario" mathematical model to investigate the effects of seismic sound on fish eggs and larvae. They concluded that mortality rates caused by exposure to seismic airgun sound are so low compared to the natural mortality that the impact of seismic surveying on recruitment to a fish stock must be regarded as insignificant.

2.2 Freshwater Fishes

Popper et al. (2005) tested the hearing sensitivity of three Mackenzie River fish species after exposure to five discharges from a seismic airgun. The mean received peak SPL was 205 to 209 dB re 1 µPa per discharge, and the approximate mean received SEL was 176 to 180 dB re 1 $\mu Pa^2 \cdot s$ per discharge. While the broad whitefish showed no Temporary Threshold Shift (TTS) as a result of the exposure, adult northern pike and lake chub exhibited TTSs of 10 to 15 dB, followed by complete recovery within 24 h of exposure. The same animals were also examined to determine whether there were observable effects on the sensory cells of the inner ear as a result of exposure to seismic sound (Song et al. 2008). No damage to the ears of the fishes was found, including those that exhibited TTS.

In another part of the same Mackenzie River project, Jorgenson and Gyselman (2009) investigated the behavioral responses of arctic riverine fishes to seismic airgun sound. They used hydroacoustic survey techniques to determine whether fish behavior upon exposure to airgun sound can either mitigate or enhance the potential impact of the sound. The study indicated that fish behavioral characteristics were generally unchanged by the exposure to airgun sound. The tracked fish did not exhibit herding behavior in front of the mobile airgun array and, therefore, were not exposed to sustained high sound levels.

2.3 Anadromous Fishes

In uncontrolled experiments using a very small sample of different groups of young salmonids, including Arctic cisco, fish were caged and exposed to various types of sound. One sound type was either a single firing or a series of four firings 10 to 15 s apart of a 300-in^3 seismic airgun at 2000 to 2200 psi (Falk and Lawrence 1973). Swim bladder damage was reported but no mortality was observed when fish were exposed within 1 to 2 m of an airgun source with source level, as estimated by Turnpenny and Nedwell (1994), of ~230 dB re 1 μPa·m (unspecified measure).

Thomsen (2002) exposed rainbow trout and Atlantic salmon held in aquaculture enclosures to the sounds from a small airgun array. Received SPLs were 142 to 186 dB re 1 $\mu Pa_{p\text{-}p}$. The fish were exposed to 124 pulses over a 3-day period. In addition to monitoring fish behavior with underwater video cameras, the authors also analyzed cod and haddock catch data from a longline fishing vessel operating in the immediate area. Only eight of the 124 shots appeared to evoke behavioral reactions by the salmonids, but overall impacts were minimal. No fish mortality was observed during or immediately after exposure. The author reported no significant effects on cod and haddock catch rates, and the behavioral effects were hard to differentiate from normal behavior.

Weinhold and Weaver (1972, cited in Turnpenny et al. 1994) exposed caged coho salmon smolts to impulses from 330 and 660-in^3 airguns at distances ranging from 1 to 10 m, resulting in received levels estimated at ~214 to 216 dB (units not given). No lethal effects were observed.

It should be noted that, in a recent and comprehensive review, Hastings and Popper (2005) take issue with many of the authors cited above for problems with experimental design and execution, measurements, and interpretation. Hastings and Popper (2005) deal primarily with possible effects of pile-driving sounds (which, like airgun sounds, are impulsive and repetitive). However, that review provides an excellent and critical review of the impacts to fish from other underwater anthropogenic sounds.

3. Indirect Effects on Fisheries

The most comprehensive experimentation on the effects of seismic airgun sound on catchability of fishes was conducted in the Barents Sea by Engås et al. (1993, 1996). They investigated the effects of seismic airgun sound on distributions, abundances, and catch rates of cod and haddock using acoustic mapping and experimental fishing with trawls and longlines. The maximum source SPL was about 248 dB re 1 $\mu Pa \cdot m_{0\text{-}p}$ based on back-calculations from measurements collected via a hydrophone at depth 80 m. Nomeasurements of the received SPLs were made. Davis et al. (1998) estimated the received SPL at the sea bottom immediately below the array and at 18 km from the array to be 205 dB re 1 $\mu Pa_{0\text{-}p}$ and 178 dB re 1 $\mu Pa_{0\text{-}p}$, respectively. Engås et al. (1993, 1996) concluded that there were indications of distributional change during and immediately following the seismic airgun discharge (45 to 64% decrease in acoustic density according to sonar data). The lowest densities were observed within 9.3 km of the seismic discharge area. The authors indicated that trawl catches of both cod and haddock declined after the seismic operations. While longline catches of haddock also showed decline after seismic airgun discharge, those for cod increased.

Løkkeborg (1991), Løkkeborg and Soldal (1993), and Dalen and Knutsen (1986) also examined the effects of seismic airgun sound on demersal fish catches. Løkkeborg (1991) examined the effects on cod catches. The source SPL of the airgun array used in his study was 239 dB re 1 μPa·m (unspecified measure type), but received SPLs were not measured. Approximately 43 h of seismic airgun discharge occurred during an 11-day period, with a five-second interval between pulses. Catch rate decreases

ranging from 55 to 80% within the seismic survey area were observed. This apparent effect persisted for at least 24 h within about 10 km of the survey area.

Turnpenny et al. (1994) examined results of these studies as well as the results of other studies on rockfish. They used rough estimations of received SPLs at catch locations and concluded that catchability is reduced when received SPLs exceed 160 to 180 dB re 1 $\mu Pa_{0\text{-}p}$. They also concluded that reaction thresholds of fishes lacking a swim bladder (e.g., flatfish) would likely be about 20 dB higher. Given the considerable variability in sound transmission loss between different geographic locations, the SPLs that were assumed in these studies were likely quite inaccurate.

Turnpenny and Nedwell (1994) also reported on the effects of seismic airgun discharge on inshore bass fisheries in shallow U.K. waters (5 to 30 m deep). The airgun array used had a source level of 250 dB re 1 $\mu Pa \cdot m_{0\text{-}p}$. Received levels in the fishing areas were estimated to be 163–191 dB re 1 $\mu Pa_{0\text{-}p}$. Using fish tagging and catch record methodologies, they concluded that there was not any distinguishable migration from the ensonified area, nor was there any reduction in bass catches on days when seismic airguns were discharged. The authors concluded that effects on fisheries would be smaller in shallow nearshore waters than in deep water because attenuation of sound is more rapid in shallow water.

Skalski et al. (1992) used a 100-in^3 airgun with a source level of 223 dB re 1 $\mu Pa \cdot m_{0\text{-}p}$ to examine the potential effects of airgun sound on the catchability of rockfishes. The moving airgun was discharged along transects in the study fishing area, after which a fishing vessel deployed a set line, ran three echo-sounder transects, and then deployed two more set lines. Each fishing experiment lasted 1 h 25 min. Received SPLs at the base of the rockfish aggregations ranged from 186 to 191 dB re 1 $\mu Pa_{0\text{-}p}$. The catch-per-unit-effort (CPUE) for rockfish declined on average by 52.4% when the airguns were operating. Skalski et al. (1992) believed that the reduction in catch resulted from a change in behavior of the fishes. The fish schools descended towards the bottom and their swimming behavior changed during airgun discharge. Although fish dispersal was not observed, the authors hypothesized that it could have occurred at a different location with a different bottom type. Skalski et al. (1992) did not continue fishing after cessation of airgun discharge. They speculated that CPUE would quickly return to normal in the experimental area, because fish behavior appeared to normalize within minutes of cessation of airgun discharge. However, in an area where exposure to airgun sound might have caused the fish to disperse, the authors suggested that a lower CPUE might persist for a longer period.

European sea bass were exposed to sound from seismic airgun arrays with a source SPL of 262 dB re 1 $\mu Pa \cdot m_{0\text{-}p}$ (Pickett et al. 1994). The seismic survey was conducted over a period of 4 to 5 months. The study was intended to investigate the effects of seismic airgun discharge on inshore bass fisheries. Information was collected through a tag and release program, and from the logbooks of commercial fishermen. Most of the 152 recovered fish from the tagging program were caught within 10 km of the release site, and it was suggested that most of these bass did not leave the area for a prolonged period. With respect to the commercial fishery, no significant changes in catch rate were observed (Pickett et al. 1994).

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APPENDIX E:

REVIEW OF THE EFFECTS OF AIRGUN SOUNDS ON MARINE INVERTEBRATES[13]

This review provides a detailed summary of the limited data and available literature on the observed effects (or lack of effects) of exposure to airgun sound on marine invertebrates. Specific conditions and results of the studies, including sound exposure levels and sound thresholds of responses, are discussed when available.

Sound caused by underwater seismic survey equipment results in energy pulses with very high peak pressures (Richardson et al. 1995). This was especially true when chemical explosives were used for underwater surveys. Virtually all underwater seismic surveying conducted today uses airguns which typically have lower peak pressures and longer rise times than chemical explosives. However, sound levels from underwater airgun discharges might still be high enough to potentially injure or kill animals located close to the source. Also, there is a potential for disturbance to normal behavior upon exposure to airgun sound. The following sections provide an overview of sound production and detection in marine invertebrates, and information on the effects of exposure to sound on marine invertebrates, with an emphasis on seismic survey sound. In addition, Fisheries and Oceans Canada has published two internal documents that provide a literature review of the effects of seismic and other underwater sound on invertebrates (Moriyasu et al. 2004; Payne et al. 2008). The available information as reviewed in those documents and here includes results of studies of varying degrees of scientific rigor as well as anecdotal information.

1. Sound Production

Much of the available information on acoustic abilities of marine invertebrates pertains to crustaceans, specifically lobsters, crabs and shrimps. Other acoustic-related studies have been conducted on cephalopods. Many invertebrates are capable of producing sound, including barnacles, amphipods, shrimp, crabs, and lobsters (Au and Banks 1998; Tolstoganova 2002). Invertebrates typically produce sound by scraping or rubbing various parts of their bodies, although they also produce sound in other ways. Sounds made by marine invertebrates may be associated with territorial behavior, mating, courtship, and aggression. On the other hand, some of these sounds may be incidental and not have any biological relevance. Sounds known to be produced by marine invertebrates have frequencies ranging from 87 Hz to 200 kHz, depending on the species.

Both male and female American lobsters *Homarus americanus* produce a buzzing vibration with the carapace when grasped (Pye and Watson III 2004; Henninger and Watson III 2005). Larger lobsters vibrate more consistently than smaller lobsters, suggesting that sound production may be involved with mating behavior. Sound production by other species of lobsters has also been studied. Among deep-sea lobsters, sound level was more variable at night than during the day, with the highest levels occurring at the lowest frequencies.

While feeding, king crab *Paralithodes camtschaticus* produce impulsive sounds that appear to stimulate movement by other crabs, including approach behavior (Tolstoganova 2002). King crab also appeared to produce 'discomfort' sounds when environmental conditions were manipulated. These discomfort sounds differ from the feeding sounds in terms of frequency range and pulse duration.

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[13] By **John Christian**, LGL Ltd., environmental research associates (revised Nov. 2009).

Snapping shrimp *Synalpheus parneomeris* are among the major sources of biological sound in temperate and tropical shallow-water areas (Au and Banks 1998). By rapidly closing one of its frontal chelae (claws), a snapping shrimp generates a forward jet of water and the cavitation of fast moving water produces a sound. Both the sound and the jet of water may function in feeding and territorial behaviors of alpheidae shrimp. Measured source sound pressure levels (SPLs) for snapping ship were 183–189 dB re 1 μPa · $m_{p\text{-}p}$ and extended over a frequency range of 2–200 kHz.

2. Sound Detection

There is considerable debate about the hearing capabilities of aquatic invertebrates. Whether they are able to hear or not depends on how underwater sound and underwater hearing are defined. In contrast to the situation in fish and marine mammals, no physical structures have been discovered in aquatic invertebrates that are stimulated by the pressure component of sound. However, vibrations (i.e., mechanical disturbances of the water) are also characteristic of sound waves. Rather than being pressure-sensitive, aquatic invertebrates appear to be most sensitive to the vibrational component of sound (Breithaupt 2002). Statocyst organs may provide one means of vibration detection for aquatic invertebrates.

More is known about the acoustic detection capabilities in decapod crustaceans than in any other marine invertebrate group, although cephalopod acoustic capabilities are now becoming a focus of study. Crustaceans appear to be most sensitive to sounds of low frequencies, i.e., <1000 Hz (Budelmann 1992; Popper et al. 2001). A study by Lovell et al. (2005) suggests greater sensitivity of the prawn *Palaemon serratus* to low-frequency sound than previously thought. Lovell et al. (2006) showed that *P. serratus* is capable of detecting a 500 Hz tone regardless of the prawn's body size and the related number and size of statocyst hair cells. Studies of American lobsters suggest that these crustaceans are more sensitive to higher frequency sounds than previously realized (Pye and Watson III 2004).

It is possible that statocyst hair cells of cephalopods are directionally sensitive in a way that is similar to the responses of hair cells of the vertebrate vestibular and lateral line systems (Budelmann and Williamson 1994; Budelmann 1996). Kaifu et al. (2008) provided evidence that the cephalopod *Octopus ocellatus* detects particle motion with its statocyst. Studies by Packard et al. (1990), Rawizza (1995) and Komak et al. (2005) have tested the sensitivities of various cephalopods to water-borne vibrations, some of which were generated by low-frequency sound. Using the auditory brainstem response (ABR) approach, Hu et al. (2009) showed that auditory evoked potentials can be obtained in the frequency ranges 400 to 1500 Hz for the squid *Sepiotheutis lessoniana* and 400 to 1000 Hz for the octopus *Octopus vulgaris*, higher than frequencies previously observed to be detectable by cephalopods.

In summary, only a few studies have been conducted on the sensitivity of certain invertebrate species to underwater sound. Available data suggest that they are capable of detecting vibrations but they do not appear to be capable of detecting pressure fluctuations.

3. Potential Seismic Effects

In marine invertebrates, potential effects of exposure to sound can be categorized as pathological, physiological, and behavioral. Pathological effects include lethal and sub-lethal injury to the animals, physiological effects include temporary primary and secondary stress responses, and behavioral effects refer to changes in exhibited behaviors (i.e., disturbance). The three categories should not be considered as independent of one another and are likely interrelated in complex ways.

***Pathological Effects*.—**In water, acute injury or death of organisms as a result of exposure to sound appears to depend on two features of the sound source: (1) the received peak pressure, and (2) the time required for the pressure to rise and decay. Generally, the higher the received pressure and the less time it takes for the pressure to rise and decay, the greater the chance of acute pathological effects. Considering the peak pressure and rise/decay time characteristics of seismic airgun arrays used today, the associated pathological zone for invertebrates would be expected to be small (i.e., within a few meters of the seismic source, at most). Few studies have assessed the potential for pathological effects on invertebrates from exposure to seismic sound.

The pathological impacts of seismic survey sound on marine invertebrates were investigated in a pilot study on snow crabs *Chionoecetes opilio* (Christian et al. 2003, 2004). Under controlled field experimental conditions, captive adult male snow crabs, egg-carrying female snow crabs, and fertilized snow crab eggs were exposed to variable SPLs (191–221 dB re 1 $\mu Pa_{0\text{-}p}$) and sound energy levels (SELs) (<130–187 dB re 1 $\mu Pa^2 \cdot s$). Neither acute nor chronic (12 weeks post-exposure) mortality was observed for the adult crabs. However, a significant difference in development rate was noted between the exposed and unexposed fertilized eggs/embryos. The egg mass exposed to seismic energy had a higher proportion of less-developed eggs than did the unexposed mass. It should be noted that both egg masses came from a single female and any measure of natural variability was unattainable (Christian et al. 2003, 2004).

In 2003, a collaborative study was conducted in the southern Gulf of St. Lawrence, Canada, to investigate the effects of exposure to sound from a commercial seismic survey on egg-bearing female snow crabs (DFO 2004). This study had design problems that impacted interpretation of some of the results (Chadwick 2004). Caged animals were placed on the ocean bottom at a location within the survey area and at a location outside of the survey area. The maximum received SPL was ~195 dB re 1 $\mu Pa_{0\text{-}p}$. The crabs were exposed for 132 hr of the survey, equivalent to thousands of seismic shots of varying received SPLs. The animals were retrieved and transferred to laboratories for analyses. Neither acute nor chronic lethal or sub-lethal injury to the female crabs or crab embryos was indicated. DFO (2004) reported that some exposed individuals had short-term soiling of gills, antennules and statocysts, bruising of the hepatopancreas and ovary, and detached outer membranes of oocytes. However, these differences could not be linked conclusively to exposure to seismic survey sound. Boudreau et al. (2009) presented the proceedings of a workshop held to evaluate the results of additional studies conducted to answer some questions arising from the original study discussed in DFO (2004). Proceedings of the workshop did not include any more definitive conclusions regarding the original results.

Payne et al. (2007) recently conducted a pilot study of the effects of exposure to airgun sound on various health endpoints of the American lobster. Adult lobsters were exposed either 20 to 200 times to 202 dB re 1$\mu Pa_{p\text{-}p}$ or 50 times to 227 dB re 1$\mu Pa_{p\text{-}p}$, and then monitored for changes in survival, food consumption, turnover rate, serum protein level, serum enzyme levels, and serum calcium level. Observations extended over a period of a few days to several months. Results showed no delayed mortality or damage to the mechanosensory systems associated with animal equilibrium and posture (as assessed by turnover rate).

In a field study, Pearson et al. (1994) exposed Stage II larvae of the Dungeness crab *Cancer magister* to single discharges from a seven-airgun array and compared their mortality and development rates with those of unexposed larvae. No statistically significant differences were found in immediate survival, long-term survival, or time to molt between the exposed and unexposed larvae, even those exposed within 1 m of the seismic source.

In 2001 and 2003, there were two incidents of multiple strandings of the giant squid *Architeuthis dux* on the north coast of Spain, and there was speculation that the strandings were caused by exposure to geophysical seismic survey sounds occurring at about the same time in the Bay of Biscay (Guerra et al. 2004). A total of nine giant squid, either stranded or moribund and floating at the surface, were collected at these times. However, Guerra et al. (2004) did not present any evidence that conclusively links the giant squid strandings and floaters to seismic activity in the area. Based on necropsies of seven (six females and one male) specimens, there was evidence of acute tissue damage. The authors speculated that one female with extensive tissue damage was affected by the impact of acoustic waves. However, little is known about the impact of strong airgun signals on cephalopods and the authors did not describe the seismic sources, locations, and durations of the Bay of Biscay surveys. In addition, there were no controls, the observations were circumstantial, and the examined animals had been dead long enough for commencement of tissue degradation.

McCauley et al. (2000a,b) exposed caged cephalopods to noise from a single 20-in^3 airgun with maximum SPLs of >200 dB re 1 $\mu Pa_{0\text{-}p}$. Statocysts were removed and preserved, but at the time of publication, results of the statocyst analyses were not available. No squid or cuttlefish mortalities were reported as a result of these exposures.

Physiological Effects.**—**Biochemical responses by marine invertebrates to acoustic exposure have also been studied to a limited degree. Such studies of stress responses could possibly provide some indication of the physiological consequences of acoustic exposure and perhaps any subsequent chronic detrimental effects. Stress responses could potentially affect animal populations by reducing reproductive capacity and adult abundance.

Stress indicators in the haemolymph of adult male snow crabs were monitored immediately after exposure of the animals to seismic survey sound (Christian et al. 2003, 2004) and at various intervals after exposure. No significant acute or chronic differences were found between exposed and unexposed animals in which various stress indicators (e.g., proteins, enzymes, cell type count) were measured.

Payne et al. (2007), in their study of the effects of exposure of adult American lobsters to airgun sound, noted decreases in the levels of serum protein, particular serum enzymes and serum calcium, in the haemolymph of animals exposed to the sound pulses. Statistically significant differences (P=0.05) were noted in serum protein at 12 days post-exposure, serum enzymes at 5 days post-exposure, and serum calcium at 12 days post-exposure. During the histological analysis conducted 4 months post-exposure, Payne et al. (2007) noted more deposits of PAS-stained material, likely glycogen, in the hepatopancreas of some of the exposed lobsters. Accumulation of glycogen could be due to stress or disturbance of cellular processes.

Price (2007) found that blue mussels *Mytilus edulis* responded to a 10 kHz pure tone continuous signal by decreasing respiration. Smaller mussels did not appear to react until exposed for 30 min whereas larger mussels responded after 10 min of exposure. The oxygen uptake rate tended to be reduced to a greater degree in the larger mussels than in the smaller animals.

In general, the limited studies done to date on the effects of acoustic exposure on marine invertebrates have not demonstrated any serious pathological and physiological effects.

Behavioral Effects.**—**Some recent studies have focused on potential behavioral effects on marine invertebrates.

Christian et al. (2003) investigated the behavioral effects of exposure to airgun sound on snow crabs. Eight animals were equipped with ultrasonic tags, released, and monitored for multiple days prior to exposure and after exposure. Received SPL and SEL were ~191 dB re 1 $\mu Pa_{0\text{-}p}$ and <130 dB re 1 $\mu Pa^2 \cdot s$, respectively. The crabs were exposed to 200 discharges over a 33-min period. None of the tagged animals left the immediate area after exposure to the seismic survey sound. Five animals were captured in the snow crab commercial fishery the following year, one at the release location, one 35 km from the release location, and three at intermediate distances from the release location.

Another study approach used by Christian et al. (2003) involved monitoring snow crabs with a remote video camera during their exposure to airgun sound. The caged animals were placed on the ocean bottom at a depth of 50 m. Received SPL and SEL were ~202 dB re 1 $\mu Pa_{0\text{-}p}$ and 150 dB re 1 $\mu Pa^2 \cdot s$, respectively. The crabs were exposed to 200 discharges over a 33-min period. They did not exhibit any overt startle response during the exposure period.

Christian et al. (2003) also investigated the pre- and post-exposure catchability of snow crabs during a commercial fishery. Received SPLs and SELs were not measured directly and likely ranged widely considering the area fished. Maximum SPL and SEL were likely similar to those measured during the telemetry study. There were seven pre-exposure and six post-exposure trap sets. Unfortunately, there was considerable variability in set duration because of poor weather. Results indicated that the catch-per-unit-effort did not decrease after the crabs were exposed to seismic survey sound.

Parry and Gason (2006) statistically analyzed data related to rock lobster *Jasus edwardsii* commercial catches and seismic surveying in Australian waters from 1978 to 2004. They did not find any evidence that lobster catch rates were affected by seismic surveys.

Caged female snow crabs exposed to airgun sound associated with a recent commercial seismic survey conducted in the southern Gulf of St. Lawrence, Canada, exhibited a higher rate of 'righting' than those crabs not exposed to seismic survey sound (J. Payne, Research Scientist, DFO, St. John's, Nfld., pers. comm.). 'Righting' refers to a crab's ability to return itself to an upright position after being placed on its back. Christian et al. (2003) made the same observation in their study.

Payne et al. (2007), in their study of the effects of exposure to airgun sound on adult American lobsters, noted a trend for increased food consumption by the animals exposed to seismic sound.

Andriguetto-Filho et al. (2005) attempted to evaluate the impact of seismic survey sound on artisanal shrimp fisheries off Brazil. Bottom trawl yields were measured before and after multiple-day shooting of an airgun array. Water depth in the experimental area ranged between 2 and 15 m. Results of the study did not indicate any significant deleterious impact on shrimp catches. Anecdotal information from Newfoundland, Canada, indicated that catch rates of snow crabs showed a significant reduction immediately following a pass by a seismic survey vessel (G. Chidley, Newfoundland fisherman, pers. comm.). Additional anecdotal information from Newfoundland indicated that a school of shrimp observed via a fishing vessel sounder shifted downwards and away from a nearby seismic airgun sound source (H. Thorne, Newfoundland fisherman, pers. comm.). This observed effect was temporary.

Caged brown shrimp *Crangon crangon* reared under different acoustical conditions exhibited differences in aggressive behavior and feeding rate (Lagardère 1982). Those exposed to a continuous sound source showed more aggression and less feeding behavior. It should be noted that behavioral responses by caged animals may differ from behavioral responses of animals in the wild.

McCauley et al. (2000a,b) provided the first evidence of the behavioral response of southern calamari squid *Sepioteuthis australis* exposed to seismic survey sound. McCauley et al. reported on the

exposure of caged cephalopods (50 squid and two cuttlefish) to noise from a single 20-in^3 airgun. The cephalopods were exposed to both stationary and mobile sound sources. The two-run total exposure times during the three trials ranged from 69 to 119 min. at a firing rate of once every 10–15 s. The maximum SPL was >200 dB re 1 $\mu Pa_{0\text{-}p}$. Some of the squid fired their ink sacs apparently in response to the first shot of one of the trials and then moved quickly away from the airgun. In addition to the above-described startle responses, some squid also moved towards the water surface as the airgun approached. McCauley et al. (2000a,b) reported that the startle and avoidance responses occurred at a received SPL of 174 dB re 1 μPa_{rms}. They also exposed squid to a ramped approach-depart airgun signal whereby the received SPL was gradually increased over time. No strong startle response (i.e., ink discharge) was observed, but alarm responses, including increased swimming speed and movement to the surface, were observed once the received SPL reached a level in the 156–161 dB re 1 μPa_{rms} range.

Komak et al. (2005) also reported the results of a study of cephalopod behavioral responses to local water movements. In this case, juvenile cuttlefish *Sepia officinalis* exhibited various behavioral responses to local sinusoidal water movements of different frequencies between 0.01 and 1000 Hz. These responses included body pattern changing, movement, burrowing, reorientation, and swimming. Similarly, the behavioral responses of the octopus *Octopus ocellatus* to non-impulse sound have been investigated by Kaifu et al. (2007). The sound stimuli, reported as having levels 120 dB re 1 μPa rms, were at various frequencies: 50, 100, 150, 200 and 1000 Hz. The respiratory activity of the octopus changed when exposed to sound in the 50–150 Hz range but not for sound at 200–1,000 Hz. Respiratory suppression by the octopus might have represented a means of escaping detection by a predator.

Low-frequency sound (<200 Hz) has also been used as a means of preventing settling/fouling by aquatic invertebrates such as zebra mussels *Dreissena polymorpha* (Donskoy and Ludyanskiy 1995) and balanoid barnacles *Balanus* sp. (Branscomb and Rittschof 1984). Price (2007) observed that blue mussels *Mytilus edulis* closed their valves upon exposure to 10 kHz pure tone continuous sound.

Although not demonstrated in the invertebrate literature, masking can be considered a potential effect of anthropogenic underwater sound on marine invertebrates. Some invertebrates are known to produce sounds (Au and Banks 1998; Tolstoganova 2002; Latha et al. 2005). The functionality and biological relevance of these sounds are not understood (Jeffs et al. 2003, 2005; Lovell et al. 2005; Radford et al. 2007). If some of the sounds are of biological significance to some invertebrates, then masking of those sounds or of sounds produced by predators, at least the particle displacement component, could potentially have adverse effects on marine invertebrates. However, even if masking does occur in some invertebrates, the intermittent nature of airgun sound is expected to result in less masking effect than would occur with continuous sound.

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